

# Adaptive boundary element methods with convergence rates

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ESI Workshop on Wavelets in Scientific Computing  
Vienna

Monday November 12, 2012



# Boundary integral equations

Boundary integral equations are rooted in the works of Gauss, August Beer, and Carl Neumann on reformulations of the Dirichlet problem as integral equations involving the single- and double layer potentials.

There are many ways to convert (interior or exterior) boundary value problems for  $\Omega$  into an integral equation

$$Au = f \quad \text{on} \quad \Gamma = \partial\Omega.$$

Typically,  $A$  has a singular kernel,  $A: H^t(\Gamma) \rightarrow H^{-t}(\Gamma)$  is self-adjoint and bounded, and satisfies

$$\langle Au, u \rangle \geq \alpha \|u\|_t^2,$$

with  $\alpha > 0$  and  $t \in \{0, \pm \frac{1}{2}\}$ . In particular,  $A$  is invertible.

# Adaptive boundary element methods

For a triangulation  $T$  of  $\Gamma$ , let  $S = S(T)$  be the space of piecewise constant functions on  $\Gamma$  subordinate to  $T$ . Then the Galerkin approximation  $u_T \in S$  of  $u$  from the subspace  $S \subset H^t$  ( $t < \frac{1}{2}$ ) is the solution of

$$\langle Au_T, v \rangle = \langle f, v \rangle, \quad \forall v \in S.$$

Local *a posteriori* error indicators,  $\eta(T, \tau)$ , are supposed to measure how much error the triangle  $\tau$  contains, e.g.,  $\|u - u_T\|_{t, \tau}$ . We need a parameter  $0 < \theta < 1$ , and an initial triangulation  $T_0$ . Then we repeat the following for  $k = 0, 1, \dots$

- Compute  $u_k = u_{T_k}$ , and the error indicators  $\eta(T_k, \tau)$ ,  $\tau \in T_k$ .
- Choose a minimal subset  $R \subset T_k$ , such that

$$\sum_{\tau \in R} \eta(T_k, \tau) \geq \theta \sum_{\tau \in T_k} \eta(T_k, \tau).$$

- Refine (at least) all triangles in  $R$ , to get  $T_{k+1}$ .

## Some prior work on *a posteriori* error indicators

Residual is equivalent to error:  $\|r_T\|_{-t} \equiv \|f - Au_T\|_{-t} \sim \|u - u_T\|_t$ . There is a localization issue for  $t$  fractional. Recall the Slobodeckij norm

$$|v|_{s,\omega}^2 = \int_{\omega \times \omega} \frac{|v(x) - v(y)|^2}{|x - y|^{2+2s}} dx dy.$$

- Faermann '00-'02: for  $-1 < t \leq 0$ , global equivalence

$$\|r_T\|_{-t}^2 \sim \sum_{z \in N_T} |r_T|_{-t,\omega(z)}^2.$$

- Carstensen, Maischak, Stephan '01: for  $-1 < t \leq 0$ , global upper bound

$$\|r_T\|_{-t}^2 \lesssim \sum_{\tau \in T} h^{2(1-t)} |r_T|_{1,\tau}^2.$$

- Carstensen, Maischak, Praetorius, Stephan '04, Nochetto, von Petersdorff, Zhang '10: for  $t > 0$ , global upper bound

$$\|r_T\|_{-t}^2 \lesssim \sum_{\tau \in T} h^{2t} |r_T|_{0,\tau}^2.$$

## Results on *a posteriori* error indicators

Gantumur '11: Lower bounds and local results. Similar results were independently obtained for  $t = -\frac{1}{2}$  by Feischl, Karkulik, Melenk, and Praetorius. Example of a local result for  $t = 0$ :

### Lemma

Let  $T'$  be a refinement of  $T$ , and let  $\gamma = \bigcup_{\tau \in T \setminus T'} \tau$ . Then we have

$$\alpha \|u_T - u_{T'}\| \leq \|r_T\|_\gamma \leq \beta \|u_T - u_{T'}\| + 2 \|r_T - v\|_\gamma$$

for any function  $v \in S_{T'}$ .

### Proof of the first inequality.

Let  $v = u_{T'} - u_T$ , and let  $v_T \in S_T$  be the  $L^2$ -orthogonal projection of  $v$  onto  $S_T$ . Then we have

$$\langle Av, v \rangle = \langle r_T, v \rangle = \langle r_T, v - v_T \rangle \leq \|r_T\|_\gamma \|v - v_T\|_\gamma \leq \|r_T\|_\gamma \|v\|_\gamma$$

where we have used that  $v = v_T$  outside  $\gamma$ .



# Oscillation

The second inequality  $\|r_T\|_\gamma \leq \beta \|u_T - u_{T'}\| + 2\|r_T - v\|_\gamma$ .

Let  $v \in S_{T'}$  be supported in  $\gamma$ . Then we have

$$\|v\|_\gamma^2 = \langle v, v \rangle = \langle v - r_T, v \rangle + \langle A(u_{T'} - u_T), v \rangle \leq (\|v - r_T\|_\gamma + \|A(u_{T'} - u_T)\|_\gamma) \|v\|_\gamma$$

implying that  $\|r_T\|_\gamma \leq \|r_T - v\|_\gamma + \|v\|_\gamma \leq 2\|r_T - v\|_\gamma + \|A(u_{T'} - u_T)\|$ .  $\square$

Suppose  $r_T$  is piecewise  $H^r$ . Then

$$\inf_{v \in S_{T'}} \|r_T - v\|_\gamma^2 \leq C_J^2 \sum_{\tau \in T \setminus T'} h_\tau^{2r} |r_T|_{r,\tau}^2.$$

Define

$$\text{osc}(T, \omega) := \left( \sum_{\tau \in T, \tau \subset \omega} h_\tau^{2r} |f - Au_T|_{r,\tau}^2 \right)^{\frac{1}{2}},$$

for  $\omega \subseteq \Gamma$  and  $v \in S_T$ , so that we have

$$\alpha \|u_T - u_{T'}\| \leq \|r_T\|_\gamma \leq \beta \|u_T - u_{T'}\| + 2C_J \text{osc}(T, \gamma).$$

# Some other works on convergence analysis

Symm's integral equation ( $t = -\frac{1}{2}$ ).

- Ferraz-Leite, Ortner, Praetorius '10: With  $\tilde{T}$  the uniform refinement of  $T$ , use error estimators of the type

$$\eta(T, \tau) = h_\tau^{1/2} \|u_T - u_{\tilde{T}}\|_\tau.$$

Assume saturation (1985-):

$$\|u - u_{\tilde{T}}\| \leq \alpha \|u - u_T\|, \quad (\alpha < 1).$$

Then  $\|u - u_k\| \leq C\rho^k$  with  $\rho < 1$ .

- Aurada, Ferraz-Leite, Praetorius '11: Estimator convergence  $\sum_\tau \eta(T_k, \tau) \rightarrow 0$  without saturation.
- Feischl, Karkulik, Melenk, Praetorius '11: Weighted residual estimator from [CMS01], geometric error reduction and convergence rate, without saturation.

# Geometric error reduction

Assume

$$\sum_{\tau \in T} h_{\tau}^{2r} |Av|_{r,\tau}^2 \leq C_A \|v\|^2, \quad v \in S_T,$$

for all admissible  $T$ . Let  $T, T'$  be admissible partitions with  $T'$  being a refinement of  $T$ , and let  $\gamma = \bigcup_{\tau \in T \setminus T'} \tau$ . Suppose, for some  $\theta \in (0, 1]$  that

$$\|r_T\|_{\gamma}^2 + \text{osc}(T, \gamma)^2 \geq \theta (\|r_T\|_{\Gamma}^2 + \text{osc}(T, \Gamma)^2).$$

Then there exist constants  $\delta \geq 0$  and  $\rho \in (0, 1)$  such that

$$\|u - u_{T'}\|^2 + \delta \text{osc}(T', \Gamma)^2 \leq \rho (\|u - u_T\|^2 + \delta \text{osc}(T, \Gamma)^2).$$

Proof sketch:

$$\|u - u_T\| \lesssim \|r\|_{\Gamma} \lesssim \|r\|_{\gamma} \lesssim \|u_T - u_{T'}\|.$$

$$\|u - u_T\|^2 = \|u_T - u_{T'}\|^2 + \|u - u_{T'}\|^2.$$



# Convergence rates

We know  $\|u - u_k\| \leq C\rho^k$  with  $\rho < 1$ . How fast does  $\#T_k$  grow?

Define approximation classes

$$\mathcal{A}_s = \{u \in L^2 : \inf_{\#T \leq N} \inf_{v \in S_T} \|u - v\| \leq CN^{-s}\}.$$

It is known that  $W^{2s,p} \subset \mathcal{A}_s$  with  $\frac{1}{p} = s + \frac{1}{2}$ , and that  $W^{2s,p}$  is much larger than  $H^{2s}$ , and friendlier to solutions of BVP and BIE.

Define  $\mathcal{A}_{r,s}$  by replacing  $\|u - v\|$  with  $\|u - v\| + \text{osc}$ . We expect  $\mathcal{A}_{r,s}$  to be close to  $\mathcal{A}_s$ .

Assume

$$\sum_{\tau \in T} h_{\tau}^{2r} |Av|_{r,\tau}^2 \leq C_A \|v\|^2, \quad v \in S_T,$$

for all admissible  $T$ . Let  $\theta \in (0, \theta^*)$ . Let  $f$  be piecewise  $H^r$  in the initial triangulation, and  $u \in \mathcal{A}_{r,s}$  for some  $s > 0$ . Then

$$\|u - u_k\| \leq C |u|_{\mathcal{A}_{r,s}} (\#T_k)^{-s}.$$

# Inverse-type inequalities

$$\sum_{\tau \in T} h_{\tau}^{2r} |Av|_{r,\tau}^2 \leq C_A \|v\|^2, \quad v \in S_T.$$

If  $A = I$  or multiplication by a smooth function, then it is the standard inverse inequality. Validity of this inequality depends on how  $A$  shifts low frequencies to high frequencies locally, and how it moves frequencies around in space. We decompose  $L^2 = S_T \oplus H_T$  and correspondingly,  $Av = (Av)_S + (Av)_H$ . The low frequency component poses no problem:

$$\sum_{\tau \in T} h_{\tau}^{2r} |(Av)_S|_{r,\tau}^2 \lesssim \|(Av)_S\|^2 \leq \|Av\|^2 \lesssim \|v\|^2.$$

For each triangle  $\tau \in T$ , we decompose  $v$  as  $v = v_{\tau} + (v - v_{\tau})$ , where  $v_{\tau}$  is the part of  $v$  near  $\tau$ . Then the high frequency component of  $Av$  locally decomposes into near-field interactions and far-field interactions:

$$(Av)_H|_{\tau} = (Av_{\tau})_H|_{\tau} + (A(v - v_{\tau}))_H|_{\tau}.$$

For boundary integral operators, the far-field part is harmless, and the near-field part is ok if the underlying surface is regular (e.g.,  $C^{1,1}$ ).

## Further developments

The inverse-type inequalities for polyhedral surfaces and for the 4 standard BIOs have been proved by Aurada, Feischl, Führer, Karkulik, Melenk, and Praetorius in 2012.

I speculate that wavelet techniques can be adapted to prove the same result.

It should also be possible to characterize the approximation classes.

# Open problems

- higher order discretizations
- to characterize the approximation classes associated to the proposed adaptive BEMs
- to extend the analysis to transmission problems, and adaptive FEM-BEM coupling
- complexity analysis, i.e., the problem of quadrature and linear algebra solvers
- convergence rate for adaptive BEMs based on non-residual type error estimators