

POSITIVE CLUSTERS FOR SMOOTH PERTURBATIONS OF A CRITICAL ELLIPTIC EQUATION IN DIMENSIONS FOUR AND FIVE

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ABSTRACT. We construct clustering positive solutions for a perturbed critical elliptic equation on a closed manifold of dimension $n = 4, 5$. Such a construction is already available in the literature in dimensions $n \geq 6$ (see for instance [10, 14, 30, 32, 36]) and not possible in dimension 3 by [27]. This also provides new patterns for the Lin–Ni [23] problem on closed manifolds and completes results by Brézis and Li [8] about this problem.

1. INTRODUCTION AND MAIN RESULT

Let (M^n, g) be a smooth closed Riemannian manifold of dimension $n \geq 3$, and $2^* = \frac{2n}{n-2}$ be the critical Sobolev exponent for the embeddings of $H^1(M)$ into the Lebesgue spaces. Given smooth perturbations $(h_\varepsilon)_\varepsilon$ of a function h_0 in M , the asymptotic behavior of a sequence $(u_\varepsilon)_\varepsilon$ of smooth positive functions satisfying

$$\Delta_g u_\varepsilon + h_\varepsilon u_\varepsilon = u_\varepsilon^{2^*-1} \tag{1.1}$$

for all $\varepsilon > 0$ has been intensively studied in the last decades. Here $\Delta_g = -\operatorname{div}_g(\nabla \cdot)$ is the Laplace–Beltrami operator. If such a sequence $(u_\varepsilon)_\varepsilon$ is bounded in $H^1(M)$, then we know from Struwe [41] that there exist $k \in \mathbb{N}$, k sequences $(\mu_{1,\varepsilon})_\varepsilon, \dots, (\mu_{k,\varepsilon})_\varepsilon$ of positive numbers converging to 0, and k sequences $(\xi_{1,\varepsilon})_\varepsilon, \dots, (\xi_{k,\varepsilon})_\varepsilon$ of points converging to ξ_1, \dots, ξ_k in M such that

$$u_\varepsilon = u_0 + \sum_{i=1}^k \left(\frac{\sqrt{n(n-2)}\mu_{i,\varepsilon}}{\mu_{i,\varepsilon}^2 + d_g(\xi_{i,\varepsilon}, \cdot)^2} \right)^{\frac{n-2}{2}} + o(1) \tag{1.2}$$

up to a subsequence, where $o(1) \rightarrow 0$ strongly and $u_\varepsilon \rightharpoonup u_0$ in $H^1(M)$ as $\varepsilon \rightarrow 0$. If the sequence $(u_\varepsilon)_\varepsilon$ is not uniformly bounded, then we say that $(u_\varepsilon)_\varepsilon$ blows up and in this case, it follows from classical elliptic estimates that k is non-zero in (1.2). If $\xi_1 = \dots = \xi_k = \xi_0$, then we say that $(u_\varepsilon)_\varepsilon$ blows up with k peaks at the point ξ_0 .

In the case of dimension 3, it was proved by Li and Zhu [27] (see Theorem 6.3 in Hebey [21]) that ξ_1, \dots, ξ_k are necessarily distinct in (1.2). By contrast, in the case of dimensions larger than or equal to 6, Druet

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and Hebey [14], Robert and Vétois [36], and more recently, Morabito, Pistoia, and Vaira [30] and Pistoia and Vaira [32] have given examples of $(h_\varepsilon)_\varepsilon$ and $(u_\varepsilon)_\varepsilon$ for which $k \geq 2$ is arbitrary and the sequences $(\xi_{i,\varepsilon})_\varepsilon$, $i = 1, \dots, k$, converge to the same point of M in (1.2) (see also Chen and Lin [10] where a similar result was obtained for the prescribed scalar curvature equation on the sphere in dimensions $n \geq 7$). The main goal of this paper is to prove that such examples can actually be given starting from dimension 4. We state our result as follows.

Theorem 1.1. *Let (M, g) be a closed manifold of dimension $n \in \{4, 5\}$. Assume that the scalar curvature S_g of the manifold has a non-degenerate minimum point ξ_0 such that $S_g(\xi_0) < 0$. Then for any natural number $k > 1$, there exists a family of positive solutions $(u_{k,\varepsilon})_{\varepsilon > 0}$ of the equations*

$$\Delta_g u_{k,\varepsilon} + \varepsilon u_{k,\varepsilon} = u_{k,\varepsilon}^{2^*-1} \quad \text{in } M \quad (1.3)$$

such that $(u_{k,\varepsilon})_{\varepsilon > 0}$ blows up with k peaks at the point ξ_0 as $\varepsilon \rightarrow 0$.

According to the terminology of Schoen [38], the blow-up points of $(u_{\varepsilon,k})_\varepsilon$ that we construct in Theorem 1.1 are non-isolated blow-up points. Isolation of blow-up points turned out to be a crucial step in the proofs of compactness for the Yamabe equation (see Druet [13], Khuri, Marques, and Schoen [22], Li and Zhang [25, 26], Li and Zhu [27], Marques [28], Schoen [39], and Schoen and Zhang [40]). Isolated blow-up points for the Yamabe equation were constructed by Brendle [4] and Brendle and Marques [6] in high dimensions (see also the survey papers [5, 7, 29]). However, as we explained above, with regards to solutions $(u_\varepsilon)_\varepsilon$ of more general perturbed critical elliptic equations like (1.1), the a priori blow-up analysis cannot rule out in general non-isolated blow-up points in dimensions $n \geq 4$ (see for instance [14, 15]).

More specifically, looking for non-constant solutions of Equation (1.3) or “patterns” has some relevance in mathematical biology (see for instance [18]). This is referred to in the literature as the Lin–Ni [23] or Lin–Ni–Takagi [24] problem. In the case of a closed manifold, Brézis and Li [8] proved that the only solution to (1.3) is the constant solution for $0 < \varepsilon \ll 1$. This result also holds true when the scalar curvature S_g is positive everywhere in dimensions $n \geq 4$ (see Druet [13] and Remark 6.1 (i) in Hebey [21]). The above Theorem 1.1 proves that this result generically fails in dimensions $n = 4, 5$ when S_g is negative somewhere. Moreover the clustering solutions that we construct in Theorem 1.1 give new type of patterns for the Lin–Ni problem. The first author proved in [43] that Theorem 1.1 fails for all $k \geq 1$ in dimensions $n \geq 6$ and also that in dimensions $n = 4, 5$, the non-degeneracy assumption in Theorem 1.1 can be removed in case $k = 1$ (see the one-peak version of Theorem 1.1 in [43]).

There is an abundant literature about the original Lin–Ni problem, namely Equation (1.3) posed on a bounded domain of the Euclidean space with zero Neumann boundary condition. We mention of course the works of Lin and Ni [23] and Lin, Ni, and Takagi [24], where after proving a subcritical analogue result in [24], it was conjectured in [20] that this equation does not have any other solution than the constant solution for $0 < \varepsilon \ll 1$. Without any pretension to exhaustivity, we also mention Adimurthi and Yadava [1, 2] and Budd, Knapp, and Peletier [9] for a complete discussion of the radial case when the domain is a ball (conjecture false for $n = 4, 5, 6$ and true otherwise) and Rey and Wei [33] and Wei, Xu, and Yang [46] who proved that the conjecture fails for all bounded domains of dimension $n = 5$ and $n = 4, 6$ respectively. The solutions constructed in [33] and [46] have isolated blow-up points in the interior of the domain, one blow-up point in [46] and multiple blow-up points in [33]. Zhu [48] proved that the Lin–Ni conjecture holds true in 3–dimensional convex domains and Wang, Wei, and Yan [44, 45] proved that the conjecture fails for non-convex domains of dimension $n \geq 3$. Druet, Robert, and Wei [16] proved that the Lin–Ni conjecture is true in convex domains of dimension $n \notin \{4, 5, 6\}$, assuming a bound on the energy of solutions. In the case where the parameter ε does not approach zero, we mention for instance the works of del Pino, Felmer, Román, and Wei [12] for ε close to a fixed number, and Esposito [17], Gui and Lin [19], and Wei and Yan [47] for ε converging to infinity, and we refer to these papers and the references therein for a more complete discussion. A vectorial version of the Lin–Ni conjecture has also been considered by Hebey [20].

The proof of Theorem 1.1 relies on the Lyapunov–Schmidt method and uses the general formalism developed in Robert and Vétois [35]. This allows to reduce the problem to finding critical points of an energy function on a finite dimensional space, here of dimension $k(n + 1) + 1$. In our case, we are dealing with a situation where the reduced energy function has a saddle point. To manage this type of situations, we prove a general critical point result in Appendix A which allows to restrict the computations of C^1 –estimates to a smaller number of variables. This generalizes an argument used by Chen, Wei, and Yan [11] in the case of a function of two real variables. We believe this result may be useful in future works based on the Lyapunov–Schmidt method when dealing with a saddle point situation.

Another specificity of our constructions is the role played by the interaction between the peaks and the constant solutions. This can be seen by looking at the dependence on ε of the parameter z_ε in our approximated solutions, which are of the form

$$u_\varepsilon = z_\varepsilon + \sum_{i=1}^k \left(\frac{\sqrt{n(n-2)}\mu_{i,\varepsilon}}{\mu_{i,\varepsilon}^2 + d_g(\xi_{i,\varepsilon}, \cdot)^2} \right)^{\frac{n-2}{2}} + \phi_\varepsilon,$$

where z_ε is a small positive parameter, $\mu_{i,\varepsilon}$ and $\xi_{i,\varepsilon}$ are as in (1.2), and ϕ_ε is a remainder term in $H^1(M)$ which is orthogonal to a finite dimensional subspace including the constant functions. While in dimension $n = 5$, z_ε behaves at first order like the constant solutions of (1.3), namely $z_\varepsilon \sim \varepsilon^{3/4}$ as $\varepsilon \rightarrow 0$, the situation becomes very different when the dimension n jumps down to 4 (see (2.4)). In this case, we find that z_ε has exponential decay as $\varepsilon \rightarrow 0$, which indicates that there is a much stronger interaction between this term and the peaks in dimension $n = 4$, which as explained above, is the lowest possible dimension for the existence of positive clusters. This is also the reason why we obtain different expressions for the reduced energy functions in dimensions $n = 4$ and $n = 5$.

The paper is organized as follows. We introduce our ansatz of multi-peak solutions and perform the main part of the proof of Theorem 1.1 in Section 2. We perform the error estimates and C^0 -energy estimates in Section 3 and the C^1 -energy estimates in Section 4. Finally we prove our general critical point result in Appendix A.

2. PROOF OF THEOREM 1.1

We fix $k > 1$ and $\xi_0 \in M$ as in the statement of Theorem 1.1. Since M is compact, we may fix a positive real number r_0 such that r_0 is less than the injectivity radius at all points of the manifold (M, g) . For any real numbers $\varepsilon, K > 0$, we consider the parameter set

$$\mathcal{D}_{K,\varepsilon} := \left\{ (\xi, \mu) = ((\xi_1, \dots, \xi_k), (\mu_1, \dots, \mu_k)) \in B(\xi_0, r_0)^k \times (0, \varepsilon)^k : \right. \\ \left. \frac{\mu_i}{\mu_j} + \frac{\mu_j}{\mu_i} + \frac{d_g(\xi_i, \xi_j)^2}{\mu_i \mu_j} > K \quad \forall i \neq j \right\},$$

where $d_g(\xi_i, \xi_j)$ is the geodesic distance between ξ_i and ξ_j , and $B(\xi_0, r_0)$ is the geodesic ball of center ξ_0 and radius r_0 in the manifold (M, g) . We let χ be a smooth cutoff function such that $0 \leq \chi \leq 1$ on $[0, \infty)$, $\chi = 1$ on $[0, r_0/2]$, and $\chi = 0$ on $[r_0, \infty)$. We consider the family of profiles

$$u_{z,\xi,\mu}(x) := z + \sum_{i=1}^k W_{\xi_i, \mu_i}(x),$$

for all $x \in M$ and $(z, \xi, \mu) \in (0, \varepsilon) \times \mathcal{D}_{K,\varepsilon}$, where

$$W_{\xi_i, \mu_i}(x) := \chi(d_g(x, \xi_i)) \left(\frac{\sqrt{n(n-2)\mu_i}}{\mu_i^2 + d_g(x, \xi_i)^2} \right)^{\frac{n-2}{2}}$$

for all $i \in \{1, \dots, k\}$.

For any real number $\varepsilon > 0$, the energy functional of Equation (1.3) is defined as

$$J_\varepsilon(u) = \frac{1}{2} \int_M (|\nabla u|_g^2 + \varepsilon u^2) dv_g - \frac{1}{2^*} \int_M u_+^{2^*} dv_g$$

for all $u \in H^1(M)$, where $u_+ := \max(u, 0)$. For any $(z, \xi, \mu) \in (0, \varepsilon) \times \mathcal{D}_{K, \varepsilon}$, we define our profile's error as

$$R_{\varepsilon, z, \xi, \mu} := \left\| (\Delta_g + \varepsilon) u_{z, \xi, \mu} - u_{z, \xi, \mu}^{2^* - 1} \right\|_{L^{\frac{2n}{n+2}}(M)}.$$

As a particular case of Theorem 1.1 of Robert and Vétois [35], we obtain the following result.

Proposition 2.1. *There exist positive constants ε_0 , C_0 , and K_0 , such that for any real number $\varepsilon \in (0, \varepsilon_0)$, there exists a mapping $\phi_\varepsilon \in C^1((0, \varepsilon_0) \times \mathcal{D}_{K_0, \varepsilon_0}, H^1(M))$ such that for any $(z, \xi, \mu) \in (0, \varepsilon_0) \times \mathcal{D}_{K_0, \varepsilon_0}$ we have*

$$|J_\varepsilon(u_{z, \xi, \mu} + \phi_\varepsilon(z, \xi, \mu)) - J_\varepsilon(u_{z, \xi, \mu})| \leq C_0 R_{\varepsilon, z, \xi, \mu}^2, \quad (2.1)$$

$$\|\phi_\varepsilon(z, \xi, \mu)\|_{H^1(M)} \leq C_0 R_{\varepsilon, z, \xi, \mu}, \quad (2.2)$$

and

$$\begin{aligned} D_u J_\varepsilon(u_{z, \xi, \mu} + \phi_\varepsilon(z, \xi, \mu)) &= 0 \\ \iff (\partial_z \mathcal{J}_\varepsilon(z, \xi, \mu), D_\mu \mathcal{J}_\varepsilon(z, \xi, \mu), D_\xi \mathcal{J}_\varepsilon(z, \xi, \mu)) &= (0, 0, 0), \end{aligned} \quad (2.3)$$

where $\mathcal{J}_\varepsilon(z, \xi, \mu) = J_\varepsilon(u_{z, \xi, \mu} + \phi_\varepsilon(z, \xi, \mu))$.

Now we need to specify the dependence of our parameters (z, ξ, μ) with respect to ε . For any $s \in \mathbb{R}$, $t = (t_1, \dots, t_k) \in \mathbb{R}^k$, and $\tau = (\tau_1, \dots, \tau_k) \in (T_{\xi_0} M)^k$, where $T_{\xi_0} M$ is the tangent space of (M, g) at the point ξ_0 , we define

$$z_{\varepsilon, s} := \begin{cases} \varepsilon^{-1} e^{-s/\varepsilon} & \text{if } n = 4 \\ \varepsilon^{3/4} + s \varepsilon^{5/4} & \text{if } n = 5, \end{cases} \quad (2.4)$$

$$\mu_{\varepsilon, s, t} = (\mu_{\varepsilon, s, t_i})_{1 \leq i \leq k} := (\mu_{\varepsilon, s} t_i)_{1 \leq i \leq k}, \quad \mu_{\varepsilon, s} := \begin{cases} e^{-s/\varepsilon} & \text{if } n = 4 \\ \varepsilon^{3/2} & \text{if } n = 5, \end{cases}$$

and

$$\xi_{\varepsilon, \tau} = (\xi_{\varepsilon, \tau_i})_{1 \leq i \leq k} := (\exp_{\xi_0}(\delta_\varepsilon \tau_i))_{1 \leq i \leq k}, \quad \delta_\varepsilon := \begin{cases} \varepsilon^{1/4} & \text{if } n = 4 \\ \varepsilon^{3/10} & \text{if } n = 5. \end{cases}$$

In particular, we point out that for any $i, j \in \{1, \dots, k\}$, we have

$$d_g(\xi_{\varepsilon, \tau_i}, \xi_{\varepsilon, \tau_j}) = \delta_\varepsilon |\tau_i - \tau_j| + O(\delta_\varepsilon^2) \quad (2.5)$$

as $\varepsilon \rightarrow 0$. For any real number $\alpha > 1$, we define the parameter set

$$X_\alpha := Y_\alpha \times [a_\alpha, \alpha] \times [1/\alpha, \alpha]^k$$

where $a_\alpha := 1/\alpha$ in case $n = 4$, $a_\alpha := -\alpha$ in case $n = 5$, and

$$Y_\alpha := \{\tau \in (T_{\xi_0}M)^k : |\tau_i| < \alpha \text{ and } |\tau_i - \tau_j| > 1/\alpha \quad \forall i \neq j\}. \quad (2.6)$$

Here $|\cdot|$ is the Euclidean norm. As an easy consequence of (2.5) and the convergence rates of $\mu_{\varepsilon,s}$ and δ_ε , we obtain that for any $\alpha > 1$, there exists $\varepsilon_\alpha \in (0, \varepsilon_0)$ such that for any $\varepsilon \in (0, \varepsilon_\alpha)$ and $(\tau, s, t) \in X_\alpha$, we have $(z_{\varepsilon,s}, \xi_{\varepsilon,\tau}, \mu_{\varepsilon,s,t}) \in (0, \varepsilon_0) \times \mathcal{D}_{K_0, \varepsilon_0}$, where ε_0 and K_0 are defined by Proposition 2.1. For the sake of simplicity, we denote

$$\begin{aligned} W_{\varepsilon, \tau_i, s, t_i} &:= W_{\xi_{\varepsilon, \tau_i}, \mu_{\varepsilon, s, t_i}}, & u_{\varepsilon, \tau, s, t} &:= u_{z_{\varepsilon, s}, \xi_{\varepsilon, \tau}, \mu_{\varepsilon, s, t}}, \\ R_{\varepsilon, \tau, s, t} &:= R_{\varepsilon, z_{\varepsilon, s}, \xi_{\varepsilon, \tau}, \mu_{\varepsilon, s, t}}, & \text{and } \phi_{\varepsilon, \tau, s, t} &:= \phi_\varepsilon(z_{\varepsilon, s}, \xi_{\varepsilon, \tau}, \mu_{\varepsilon, s, t}). \end{aligned}$$

We state our C^0 -energy estimates in Proposition 2.2 below. We refer to Section 3 for the proof of this result.

Proposition 2.2. *We fix $\alpha > 0$. As $\varepsilon \rightarrow 0$, we have*

$$\begin{aligned} J_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) &= kc_0 - \frac{e^{-2s/\varepsilon}}{\varepsilon} \left(c_1 S_g(\xi_0) s \sum_{i=1}^k t_i^2 \right. \\ &\quad \left. + c_2 \sum_{i=1}^k t_i - c_3 \right) - \frac{e^{-2s/\varepsilon}}{\sqrt{\varepsilon}} \sum_{i=1}^k \left(\frac{c_1}{2} s t_i^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) \right. \\ &\quad \left. + c_4 \sum_{j \neq i} \frac{t_i t_j}{|\tau_i - \tau_j|^2} \right) + o\left(\frac{e^{-2s/\varepsilon}}{\sqrt{\varepsilon}}\right) \quad (2.7) \end{aligned}$$

in case $n = 4$, and

$$\begin{aligned} J_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) &= kc_5 + c_6 \varepsilon^{5/2} - \varepsilon^3 \sum_{i=1}^k \left(c_7 S_g(\xi_0) t_i^2 + c_8 t_i^{3/2} \right) \\ &\quad - \varepsilon^{7/2} \left(c_9 s^2 + c_8 s \sum_{i=1}^k t_i^{3/2} \right) - \varepsilon^{18/5} \sum_{i=1}^k \left(\frac{c_7}{2} t_i^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) \right. \\ &\quad \left. + c_{10} \sum_{j \neq i} \frac{t_i^{3/2} t_j^{3/2}}{|\tau_i - \tau_j|^3} \right) + o(\varepsilon^{18/5}) \quad (2.8) \end{aligned}$$

in case $n = 5$, uniformly in $(\tau, s, t) \in X_\alpha$, where c_0, \dots, c_{10} are positive constants depending only on (M, g) .

In view of the asymptotic expansions (2.7) and (2.8), we introduce the changes of variables

$$\hat{s} = \begin{cases} \varepsilon^{-1/2} (s - s_0) & \text{if } n = 4 \\ \varepsilon^{-1/20} (s - s_0) & \text{if } n = 5 \end{cases} \quad \text{and} \quad \hat{t} = \delta_\varepsilon^{-1} (t - t_0), \quad (2.9)$$

where

$$s_0 := \begin{cases} \frac{c_2}{2c_1(-S_g(\xi_0))t_0} & \text{if } n = 4 \\ -\frac{kc_8 t_0^{3/2}}{2c_9} & \text{if } n = 5 \end{cases}$$

and

$$t_0 := \begin{cases} \frac{2c_3}{kc_2} & \text{if } n = 4 \\ \left(\frac{3c_8}{4c_7 S_g(\xi_0)}\right)^2 & \text{if } n = 5. \end{cases}$$

Choosing α large enough so that $(s_0, t_0) \in [1/\alpha, \alpha]^2$ in case $n = 4$ and $(s_0, t_0) \in [-\alpha, \alpha] \times [1/\alpha, \alpha]$ in case $n = 5$, we can easily see that for any compact subset A of $Y \times \mathbb{R}^{k+1}$, where

$$Y := \left\{ \tau \in (T_{\xi_0}M)^k : |\tau_i - \tau_j| \neq 0 \quad \forall i \neq j \right\},$$

there exists $\varepsilon_A > 0$ such that for any $\varepsilon \in (0, \varepsilon_A)$, $(\tau, \hat{s}, \hat{t}) \in A$ implies $(\tau, s, t) \in X_\alpha$ for α large. Putting together (2.7)–(2.9), we obtain

$$J_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) = \begin{cases} kc_0 + F_\varepsilon(\tau, \hat{s}, \hat{t}) \varepsilon^{-1/2} e^{-2s_0/\varepsilon} & \text{if } n = 4 \\ kc_5 + c_6 \varepsilon^{5/2} - \frac{k}{4} c_8 t_0^{3/2} \varepsilon^3 \\ \quad + \frac{k^2 c_8^2}{4c_9} t_0^3 \varepsilon^{7/2} + F_\varepsilon(\tau, \hat{s}, \hat{t}) \varepsilon^{18/5} & \text{if } n = 5, \end{cases}$$

where

$$F_\varepsilon(\tau, \hat{s}, \hat{t}) = e^{-2\hat{s}/\sqrt{\varepsilon}} \left(kc_1(-S_g(\xi_0))t_0^2 \hat{s} + \sum_{i=1}^k \left(\frac{c_2}{2t_0} \hat{t}_i^2 - \frac{c_1}{2} s_0 t_0^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) - c_4 \sum_{j \neq i} \frac{t_0^2}{|\tau_i - \tau_j|^2} \right) + o(1) \right) \quad (2.10)$$

in case $n = 4$, and

$$F_\varepsilon(\tau, \hat{s}, \hat{t}) = -c_9 \hat{s}^2 + \sum_{i=1}^k \left(\frac{c_7}{2} (-S_g(\xi_0)) \hat{t}_i^2 - \frac{c_7}{2} t_0^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) - c_{10} \sum_{j \neq i} \frac{t_0^3}{|\tau_i - \tau_j|^3} \right) + o(1) \quad (2.11)$$

in case $n = 5$, as $\varepsilon \rightarrow 0$, uniformly in $(\tau, \hat{s}, \hat{t}) \in A$ for all compact subsets A of $Y \times \mathbb{R}^{k+1}$.

In addition to the above C^0 -estimates, we need C^1 -energy estimates in the variables t_i . We state these estimates in Proposition 2.3 below. We refer to Section 4 for the proof of this result.

Proposition 2.3. *Let A be a compact subset of $Y \times \mathbb{R}^{k+1}$. For any $i \in \{1, \dots, k\}$, we have*

$$\partial_{\hat{t}_i} F_\varepsilon(\tau, \hat{s}, \hat{t}) = \begin{cases} e^{-2\hat{s}/\sqrt{\varepsilon}} \left(\frac{c_2 \hat{t}_i}{t_0} + o(1) \right) & \text{if } n = 4 \\ -c_7 S_g(\xi_0) \hat{t}_i + o(1) & \text{if } n = 5 \end{cases} \quad (2.12)$$

as $\varepsilon \rightarrow 0$, uniformly in $(\tau, \hat{s}, \hat{t}) \in A$.

We are now in position to prove our main result.

Proof of Theorem 1.1. We fix a compact subset A of $Y \times \mathbb{R}^{k+1}$. The choice of A will be precised in the proof. As a consequence of (2.3), it suffices to show that for small $\varepsilon > 0$, there exists $(\tau_\varepsilon, \hat{s}_\varepsilon, \hat{t}_\varepsilon) \in A$ such that $(z_{\varepsilon, s_\varepsilon}, \xi_{\varepsilon, \tau_\varepsilon}, \mu_{\varepsilon, s_\varepsilon, t_\varepsilon})$ is a critical point of the function \mathcal{J}_ε defined in Proposition 2.1. As is easily seen, $(z_{\varepsilon, s_\varepsilon}, \xi_{\varepsilon, \tau_\varepsilon}, \mu_{\varepsilon, s_\varepsilon, t_\varepsilon})$ is a critical point of \mathcal{J}_ε if and only if $(\tau_\varepsilon, \hat{s}_\varepsilon, \hat{t}_\varepsilon)$ is a critical point of F_ε . Here \hat{s}_ε and \hat{t}_ε are defined as in (2.9).

Now we aim to apply Lemma A.1 in the appendix to the function F_ε in a suitable product set. For the sake of clarity, we separate the cases $n = 4$ and $n = 5$.

In case $n = 4$, we take $A := \overline{\Omega_1 \times \Omega_2}$, where $\Omega_2 := B(0, r_0)$ is the open ball in \mathbb{R}^k of center 0 and radius $r_0 := \sqrt{t_0/c_2}$, and Ω_1 is the open subset of $(T_{\xi_0} M)^k \times \mathbb{R}$ defined as

$$\Omega_1 := \left\{ (\tau, \hat{s}) \in Y \times \mathbb{R} : G(\tau) - 1 < H(\hat{s}) < \inf_Y G + 1 \right\},$$

where

$$G(\tau) := \sum_{i=1}^k \left(\frac{c_1}{2} s_0 t_0^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) + c_4 \sum_{j \neq i} \frac{t_0^2}{|\tau_i - \tau_j|^2} \right)$$

and

$$H(\hat{s}) := k c_1 (-S_g(\xi_0)) t_0^2 \hat{s}$$

for all $(\tau, \hat{s}) \in Y \times \mathbb{R}$. Since by assumption $D^2 S_g(\xi_0)$ is positive definite, we obtain that $G > 0$ in Y and A is a compact subset of $Y \times \mathbb{R}^{k+1}$. Then Point (i) in Lemma A.1 is an immediate consequence of (2.12). Now we prove Point (ii). We let $(\bar{\tau}, \bar{s}) \in \Omega_1$ be such that

$$G(\bar{\tau}) = \inf_Y G \quad \text{and} \quad H(\bar{s}) = \inf_Y G + \frac{1}{2}. \quad (2.13)$$

From (2.10) and (2.13), we obtain

$$\inf_{\Omega_2} F_\varepsilon(\bar{\tau}, \bar{s}, \cdot) = e^{-2\bar{s}/\sqrt{\varepsilon}} \left(\frac{1}{2} + o(1) \right) \quad (2.14)$$

as $\varepsilon \rightarrow 0$. By using the fact that $r_0^2 < 2t_0/c_2$, we also obtain

$$\sup_{\partial\Omega_1 \times \Omega_2} F_\varepsilon = O\left(e^{-2s^*/\sqrt{\varepsilon}}\right) = o\left(e^{-2\bar{s}/\sqrt{\varepsilon}}\right) \quad (2.15)$$

as $\varepsilon \rightarrow 0$, where $s^* := \bar{s} + 1/(2kc_1(-S_g(\xi_0))t_0^2)$ so that $H(s^*) = G(\bar{\tau}) + 1$. It follows from (2.14) and (2.15) that

$$\inf_{\Omega_2} F_\varepsilon(\bar{\tau}, \bar{s}, \cdot) > \sup_{\partial\Omega_1 \times \Omega_2} F_\varepsilon$$

for small ε . Therefore Point (ii) in Lemma A.1 is also satisfied.

In case $n = 5$, we take $A := \overline{\Omega_1 \times \Omega_2}$, where $\Omega_2 := B(0, r_0)$ is the open ball in \mathbb{R}^k of center 0 and radius $r_0 := \sqrt{1/(-c_7 S_g(\xi_0))}$, and Ω_1 is the open subset of $(T_{\xi_0}M)^k \times \mathbb{R}$ defined as

$$\Omega_1 := \left\{ (\tau, \hat{s}) \in Y \times \mathbb{R} : G(\tau, \hat{s}) < \inf_Y G(\cdot, 0) + 1 \right\},$$

where

$$G(\tau, \hat{s}) := c_9 \hat{s}^2 + \sum_{i=1}^k \left(\frac{c_7}{2} t_0^2 D^2 S_g(\xi_0) \cdot (\tau_i, \tau_i) + c_{10} \sum_{j \neq i} \frac{t_0^3}{|\tau_i - \tau_j|^3} \right)$$

for all $(\tau, \hat{s}) \in Y \times \mathbb{R}$. Similarly to the case $n = 4$, we obtain that $G > 0$ in $Y \times \mathbb{R}$ and A is a compact subset of $Y \times \mathbb{R}^{k+1}$. Point (i) in Lemma A.1 follows from (2.12) together with the assumption that $S_g(\xi_0) < 0$. To prove Point (ii), we let $\bar{\tau} \in Y$ be such that

$$G(\bar{\tau}, 0) = \inf_Y G(\cdot, 0). \quad (2.16)$$

From (2.11), (2.16), and since $\frac{c_7}{2}(-S_g(\xi_0))r_0^2 < 1$, we obtain

$$\sup_{\partial\Omega_1 \times \Omega_2} F_\varepsilon = -\inf_Y G(\cdot, 0) - 1 + \frac{c_7}{2}(-S_g(\xi_0))r_0^2 + o(1) < \inf_{\Omega_2} F_\varepsilon(\bar{\tau}, 0, \cdot)$$

for small ε . It follows that Point (ii) in Lemma A.1 is also satisfied.

In both cases $n = 4$ and $n = 5$, we are now in position to apply Lemma A.1 to the function F_ε in the set $\Omega_1 \times \Omega_2$. We obtain that for small ε , there exists a critical point $(\tau_\varepsilon, \hat{s}_\varepsilon, \hat{t}_\varepsilon) \in \Omega_1 \times \Omega_2$ of F_ε . This ends the proof of Theorem 1.1. \square

3. PROOF OF THE C^0 -ENERGY ESTIMATES

This section is devoted to the proof of Proposition 2.2. We start with proving the following error estimate.

Lemma 3.1. *We fix $\alpha > 0$. We have*

$$R_{\varepsilon, \tau, s, t} = \begin{cases} O(e^{-s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^{9/4}) & \text{if } n = 5 \end{cases} \quad (3.1)$$

as $\varepsilon \rightarrow 0$ uniformly in $(\tau, s, t) \in X_\alpha$.

Proof of Lemma 3.1. From the triangular inequality, we obtain

$$\begin{aligned} R_{\varepsilon,\tau,s,t} &\leq \text{Vol}_g(M)^{\frac{n+2}{2n}} |\varepsilon z_{\varepsilon,s} - z_{\varepsilon,s}^{2^*-1}| \\ &\quad + \sum_{i=1}^k \|(\Delta_g + \varepsilon) W_{\varepsilon,\tau_i,s,t_i} - W_{\varepsilon,\tau_i,s,t_i}^{2^*-1}\|_{L^{\frac{2n}{n+2}}(M)} \\ &\quad + \left\| z_{\varepsilon,s}^{2^*-1} + \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} \right\|_{L^{\frac{2n}{n+2}}(M)}, \end{aligned} \quad (3.2)$$

where $\text{Vol}_g(M)$ is the volume of the manifold (M, g) . A straightforward calculation gives

$$\varepsilon z_{\varepsilon,s} - z_{\varepsilon,s}^{2^*-1} = \begin{cases} O(e^{-s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^{9/4}) & \text{if } n = 5. \end{cases} \quad (3.3)$$

For any $i \in \{1, \dots, k\}$, we have (see for instance Robert and Vétois [34])

$$\begin{aligned} &\|(\Delta_g + \varepsilon) W_{\varepsilon,\tau_i,s,t_i} - W_{\varepsilon,\tau_i,s,t_i}^{2^*-1}\|_{L^{\frac{2n}{n+2}}(M)} \\ &= O\left(\mu_{\varepsilon,s}^{\frac{n-2}{2}}\right) = \begin{cases} O(e^{-s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^{9/4}) & \text{if } n = 5. \end{cases} \end{aligned} \quad (3.4)$$

With regard to the last term in the right-hand side of (3.2), we have

$$\begin{aligned} &\left\| z_{\varepsilon,s}^{2^*-1} + \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} \right\|_{L^{\frac{2n}{n+2}}(M)} \\ &= O\left(z_{\varepsilon,s} \sum_{i=1}^k \|W_{\varepsilon,\tau_i,s,t_i}^{2^*-2}\|_{L^{\frac{2n}{n+2}}(M)} + z_{\varepsilon,s}^{2^*-2} \sum_{i=1}^k \|W_{\varepsilon,\tau_i,s,t_i}\|_{L^{\frac{2n}{n+2}}(M)} \right. \\ &\quad \left. + \sum_{i=1}^k \sum_{j \neq i} \|W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} W_{\varepsilon,\tau_j,s,t_j}\|_{L^{\frac{2n}{n+2}}(M)} \right). \end{aligned} \quad (3.5)$$

Rough estimates give

$$\|W_{\varepsilon,\tau_i,s,t_i}\|_{L^{\frac{2n}{n+2}}(M)} = O\left(\mu_{\varepsilon,s}^{\frac{n-2}{2}}\right), \quad (3.6)$$

$$\|W_{\varepsilon,\tau_i,s,t_i}^{2^*-2}\|_{L^{\frac{2n}{n+2}}(M)} = O\left(\mu_{\varepsilon,s}^{\frac{n-2}{2}}\right), \quad (3.7)$$

and

$$\|W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} W_{\varepsilon,\tau_j,s,t_j}\|_{L^{\frac{2n}{n+2}}(M)} = O\left(\mu_{\varepsilon,s}^{n-2} d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j})^{2-n}\right) \quad (3.8)$$

for all $i, j \in \{1, \dots, k\}$, $i \neq j$. The latter estimate can be obtained by splitting the integral into three integrals on the domains $M \setminus B(\xi_0, r_0/2)$, $B(\xi_0, r_0/2) \setminus B(\xi_{\varepsilon,\tau_i}, d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j})/2)$, and $B(\xi_{\varepsilon,\tau_i}, d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j})/2)$, and using suitable changes of variable together with the fact that

$\mu_{\varepsilon,s} = o(d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j}))$ as $\varepsilon \rightarrow 0$. By putting together (3.5)–(3.8), we then obtain

$$\left\| z_{\varepsilon,s}^{2^*-1} + \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} \right\|_{L^{\frac{2n}{n+2}}(M)} = \begin{cases} O(\varepsilon^{-1}e^{-2s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^3) & \text{if } n = 5. \end{cases} \quad (3.9)$$

Finally (3.1) follows from (3.2)–(3.4) and (3.9). \square

Proof of Proposition 2.2. From (2.1) and Lemma 3.1, we obtain

$$J_\varepsilon(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}) = J_\varepsilon(u_{\varepsilon,\tau,s,t}) + \begin{cases} O(e^{-2s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^{9/2}) & \text{if } n = 5. \end{cases} \quad (3.10)$$

Moreover we have

$$\begin{aligned} J_\varepsilon(u_{\varepsilon,\tau,s,t}) &= J_\varepsilon(z_{\varepsilon,s}) + \sum_{i=1}^k J_\varepsilon(W_{\varepsilon,\tau_i,s,t_i}) + \varepsilon z_{\varepsilon,s} \sum_{i=1}^k \int_M W_{\varepsilon,\tau_i,s,t_i} dv_g \\ &\quad - z_{\varepsilon,s} \sum_{i=1}^k \int_M W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} dv_g - \frac{1}{2} \sum_{i=1}^k \sum_{j \neq i} \int_M W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} W_{\varepsilon,\tau_j,s,t_j} dv_g \\ &\quad + \frac{1}{2} \sum_{i=1}^k \sum_{j \neq i} \int_M (\Delta_g W_{\varepsilon,\tau_i,s,t_i} + \varepsilon W_{\varepsilon,\tau_i,s,t_i} - W_{\varepsilon,\tau_i,s,t_i}^{2^*-1}) W_{\varepsilon,\tau_j,s,t_j} dv_g \\ &\quad + \frac{1}{2^*} \int_M \left(z_{\varepsilon,s}^{2^*} + \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*} + 2^* z_{\varepsilon,s} \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} \right. \\ &\quad \left. + 2^* \sum_{i=1}^k \sum_{j \neq i} W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} W_{\varepsilon,\tau_j,s,t_j} - u_{\varepsilon,\tau,s,t}^{2^*} \right) dv_g. \end{aligned} \quad (3.11)$$

A straightforward calculation gives

$$\begin{aligned} J_\varepsilon(z_{\varepsilon,s}) &= \text{Vol}_g(M) \left(\frac{\varepsilon z_{\varepsilon,s}^2}{2} - \frac{z_{\varepsilon,s}^{2^*}}{2^*} \right) \\ &= \begin{cases} \text{Vol}_g(M) \frac{e^{-2s/\varepsilon}}{2\varepsilon} + O\left(\frac{e^{-4s/\varepsilon}}{\varepsilon^4}\right) & \text{if } n = 4 \\ \text{Vol}_g(M) \left(\frac{\varepsilon^{5/2}}{5} - \frac{2}{3} s^2 \varepsilon^{7/2} \right) + O(\varepsilon^4) & \text{if } n = 5, \end{cases} \end{aligned} \quad (3.12)$$

where $\text{Vol}_g(M)$ is the volume of the manifold (M, g) . For any $i \in \{1, \dots, k\}$, we have (see for instance Robert and Vétois [34])

$$\begin{aligned} J_\varepsilon(W_{\varepsilon,\tau_i,s,t_i}) &= \frac{K_n^{-n}}{n} + \\ &\quad \begin{cases} \frac{K_4^{-4}}{8} S_g(\xi_{\varepsilon,\tau_i}) \mu_{\varepsilon,s,t_i}^2 \ln \mu_{\varepsilon,s} + O(\mu_{\varepsilon,s}^2 + \varepsilon \mu_{\varepsilon,s}^2 |\ln \mu_{\varepsilon,s}|) & \text{if } n = 4 \\ -\frac{K_5^{-5}}{10} S_g(\xi_{\varepsilon,\tau_i}) \mu_{\varepsilon,s,t_i}^2 + O(\mu_{\varepsilon,s}^3 + \varepsilon \mu_{\varepsilon,s}^2) & \text{if } n = 5, \end{cases} \end{aligned} \quad (3.13)$$

where K_n is the Sobolev constant which was obtained by Rodemich [37], Aubin [3], and Talenti [42], namely

$$\frac{1}{K_n} := \inf_{u \in D^{1,2}(\mathbb{R}^n) \setminus \{0\}} \frac{\|\nabla u\|_{L^2(\mathbb{R}^n)}}{\|u\|_{L^{2^*}(\mathbb{R}^n)}} = \frac{1}{2} \sqrt{n(n-2)} \text{Vol}(\mathbb{S}^n)^{1/n}, \quad (3.14)$$

where $\text{Vol}(\mathbb{S}^n)$ is the volume of the standard n -dimensional sphere. Moreover since ξ_0 is a critical point of S_g , a straightforward Taylor expansion gives

$$S_g(\xi_{\varepsilon, \tau_i}) = S_g(\xi_0) + \frac{1}{2} D^2 S_g(\xi_0)(\tau_i, \tau_i) \delta_\varepsilon^2 + O(\delta_\varepsilon^3). \quad (3.15)$$

It follows from (3.13) and (3.15) that

$$J_\varepsilon(W_{\varepsilon, \tau_i, s, t_i}) = \begin{cases} \frac{K_4^{-4}}{4} \left(1 - \frac{1}{2} S_g(\xi_0) s t_i^2 \frac{e^{-2s/\varepsilon}}{\varepsilon} \right. \\ \quad \left. - \frac{1}{4} D^2 S_g(\xi_0)(\tau_i, \tau_i) s t_i^2 \frac{e^{-2s/\varepsilon}}{\sqrt{\varepsilon}} \right) + O\left(\frac{e^{-2s/\varepsilon}}{\varepsilon^{1/4}}\right) & \text{if } n = 4 \\ \frac{K_5^{-5}}{5} \left(1 - \frac{1}{2} S_g(\xi_0) t_i^2 \varepsilon^3 \right. \\ \quad \left. - \frac{1}{4} D^2 S_g(\xi_0)(\tau_i, \tau_i) t_i^2 \varepsilon^{18/5} \right) + O(\varepsilon^{39/10}) & \text{if } n = 5. \end{cases} \quad (3.16)$$

With regard to the third, fourth, and fifth terms in the right-hand side of (3.11), we obtain

$$\varepsilon z_{\varepsilon, s} \int_M W_{\varepsilon, \tau_i, s, t_i} dv_g = O\left(\varepsilon z_{\varepsilon, s} \mu_{\varepsilon, s}^{\frac{n-2}{2}}\right) = \begin{cases} O(e^{-2s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^4) & \text{if } n = 5, \end{cases} \quad (3.17)$$

$$z_{\varepsilon, s} \int_M W_{\varepsilon, \tau_i, s, t_i}^{2^*-1} dv_g = z_{\varepsilon, s} \mu_{\varepsilon, s}^{\frac{n-2}{2}} (I_n + O(\mu_{\varepsilon, s}^2 |\ln \mu_{\varepsilon, s}|)) \\ = \begin{cases} \frac{e^{-2s/\varepsilon}}{\varepsilon} t_i I_4 + O\left(\frac{e^{-4s/\varepsilon}}{\varepsilon^2}\right) & \text{if } n = 4 \\ (\varepsilon^3 + s\varepsilon^{7/2}) t_i^{3/2} I_5 + O(\varepsilon^6 |\ln \varepsilon|) & \text{if } n = 5, \end{cases} \quad (3.18)$$

where

$$I_n := \int_{\mathbb{R}^n} \left(\frac{\sqrt{n(n-2)}}{1+|x|^2} \right)^{\frac{n+2}{2}} dx, \quad (3.19)$$

and

$$\int_M W_{\varepsilon, \tau_i, s, t_i}^{2^*-1} W_{\varepsilon, \tau_j, s, t_j} dv_g \\ = \int_{B((\xi_{\varepsilon, \tau_i}, d_g(\xi_{\varepsilon, \tau_i}, \xi_{\varepsilon, \tau_j}))/2)} W_{\varepsilon, \tau_i, s, t_i}^{2^*-1} W_{\varepsilon, \tau_j, s, t_j} dv_g + O\left(\frac{\mu_{\varepsilon, s}^n}{d_g(\xi_{\varepsilon, \tau_i}, \xi_{\varepsilon, \tau_j})^n}\right)$$

$$\begin{aligned}
 &= \frac{\mu_{\varepsilon,s,t_i}^{\frac{n-2}{2}} \mu_{\varepsilon,s,t_j}^{\frac{n-2}{2}}}{d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j})^{n-2}} (I_n + o(1)) \\
 &= \begin{cases} \frac{e^{-2s/\varepsilon} t_i t_j}{\sqrt{\varepsilon} |\tau_i - \tau_j|^2} (I_4 + o(1)) & \text{if } n = 4 \\ \frac{\varepsilon^{18/5} t_i^{3/2} t_j^{3/2}}{|\tau_i - \tau_j|^3} (I_5 + o(1)) & \text{if } n = 5 \end{cases} \quad (3.20)
 \end{aligned}$$

for all $i, j \in \{1, \dots, k\}$, $i \neq j$, where I_n is as in (3.19). To estimate the next term, we observe that

$$\Delta_g W_{\varepsilon,\tau_i,s,t_i} = W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} + O(W_{\varepsilon,\tau_i,s,t_i}),$$

which gives

$$\begin{aligned}
 &\int_M (\Delta_g W_{\varepsilon,\tau_i,s,t_i} + \varepsilon W_{\varepsilon,\tau_i,s,t_i} - W_{\varepsilon,\tau_i,s,t_i}^{2^*-1}) W_{\varepsilon,\tau_j,s,t_j} dv_g \\
 &= O\left(\int_M W_{\varepsilon,\tau_i,s,t_i} W_{\varepsilon,\tau_j,s,t_j} dv_g\right) \\
 &= \begin{cases} O(\mu_{\varepsilon,s}^2 |\ln(d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j}))|) & \text{if } n = 4 \\ O(\mu_{\varepsilon,s}^3 d_g(\xi_{\varepsilon,\tau_i}, \xi_{\varepsilon,\tau_j})^{-1}) & \text{if } n = 5 \end{cases} \\
 &= \begin{cases} O(e^{-2s/\varepsilon} |\ln \varepsilon|) & \text{if } n = 4 \\ O(\varepsilon^{21/5}) & \text{if } n = 5 \end{cases} \quad (3.21)
 \end{aligned}$$

for all $i, j \in \{1, \dots, k\}$, $i \neq j$. With regard to the last term in the right-hand side of (3.11), we have

$$\begin{aligned}
 &\int_M \left(z_{\varepsilon,s}^{2^*} + \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*} + 2^* z_{\varepsilon,s} \sum_{i=1}^k W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} \right. \\
 &\quad \left. + 2^* \sum_{i=1}^k \sum_{j \neq i} W_{\varepsilon,\tau_i,s,t_i}^{2^*-1} W_{\varepsilon,\tau_j,s,t_j} - u_{\varepsilon,\tau,s,t}^{2^*} \right) dv_g \\
 &= O\left(z_{\varepsilon,s}^{2^*-1} \sum_{i=1}^k \int_M W_{\varepsilon,\tau_i,s,t_i} dv_g + z_{\varepsilon,s}^2 \sum_{i=1}^k \int_M W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} dv_g \right. \\
 &\quad \left. + \sum_{i=1}^k \sum_{j \neq i} \int_M W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} W_{\varepsilon,\tau_j,s,t_j}^2 dv_g \right). \quad (3.22)
 \end{aligned}$$

Rough estimates give

$$\int_M W_{\varepsilon,\tau_i,s,t_i} dv_g = O\left(\mu_{\varepsilon,s}^{\frac{n-2}{2}}\right), \quad (3.23)$$

$$\int_M W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} dv_g = \begin{cases} O(\mu_{\varepsilon,s}^2 |\ln \mu_{\varepsilon,s}|) & \text{if } n = 4 \\ O(\mu_{\varepsilon,s}^2) & \text{if } n = 5, \end{cases} \quad (3.24)$$

and

$$\begin{aligned} & \int_M W_{\varepsilon, \tau_i, s, t_i}^{2^*-2} W_{\varepsilon, \tau_j, s, t_j}^2 dv_g \\ &= \begin{cases} O\left(\mu_{\varepsilon, s}^4 |\ln \mu_{\varepsilon, s}| d_g(\xi_{\varepsilon, \tau_i}, \xi_{\varepsilon, \tau_j})^{-4}\right) & \text{if } n = 4 \\ O\left(\mu_{\varepsilon, s}^4 d_g(\xi_{\varepsilon, \tau_i}, \xi_{\varepsilon, \tau_j})^{-4}\right) & \text{if } n = 5 \end{cases} \end{aligned} \quad (3.25)$$

for all $i, j \in \{1, \dots, k\}$, $i \neq j$. By combining (3.22)–(3.25), we obtain

$$\begin{aligned} & \int_M \left(z_{\varepsilon, s}^{2^*} + \sum_{i=1}^k W_{\varepsilon, \tau_i, s, t_i}^{2^*} + 2^* z_{\varepsilon, s} \sum_{i=1}^k W_{\varepsilon, \tau_i, s, t_i}^{2^*-1} \right. \\ & \quad \left. + 2^* \sum_{i=1}^k \sum_{j \neq i} W_{\varepsilon, \tau_i, s, t_i}^{2^*-1} W_{\varepsilon, \tau_j, s, t_j} - u_{\varepsilon, \tau, s, t}^{2^*} \right) dv_g \\ &= \begin{cases} O(e^{-2s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^4) & \text{if } n = 5. \end{cases} \end{aligned} \quad (3.26)$$

Finally (2.7) and (2.8) follow from (3.10)–(3.12), (3.16)–(3.21), and (3.26). \square

4. PROOF OF THE C^1 –ENERGY ESTIMATES

This section is devoted to the proof of Proposition 2.3.

Proof of Proposition 2.3. Throughout this proof, we identify the tangent space $T_\xi M$ with \mathbb{R}^n for all points ξ in a neighborhood of ξ_0 by using a smooth, local, orthonormal frame. For any $x \in M$, $(\tau, s, t) \in Y \times \mathbb{R} \times (0, \infty)^k$, $i \in \{1, \dots, k\}$, and $j \in \{1, \dots, n\}$, we define

$$Z_{\varepsilon, \tau_i, s, t_i, j}(x) := \chi(d_g(x, \xi_{\varepsilon, \tau_i})) \mu_{\varepsilon, s, t_i}^{\frac{2-n}{2}} V_j(\mu_{\varepsilon, s, t_i}^{-1} \exp_{\xi_{\varepsilon, \tau_i}}^{-1}(x)),$$

where

$$V_0(y) := \frac{|y|^2 - 1}{(1 + |y|^2)^{n/2}} \quad \text{and} \quad V_j(y) := \frac{y_j}{(1 + |y|^2)^{n/2}} \quad \text{if } j \in \{1, \dots, n\}$$

for all $y \in \mathbb{R}^n$. From Robert and Vétois [35], we know that the function $\phi_{\varepsilon, \tau, s, t}$ given by Proposition 2.1 is such that $\phi_{\varepsilon, \tau, s, t} \in K_{\varepsilon, \tau, s, t}^\perp$ and $DJ_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) \in K_{\varepsilon, \tau, s, t}$, where

$$K_{\varepsilon, \tau, s, t} := \text{span}(\{1\} \cup \{Z_{\varepsilon, \tau_i, s, t_i, j} : i \in \{1, \dots, k\} \text{ and } j \in \{0, \dots, n\}\})$$

and

$$K_{\varepsilon, \tau, s, t}^\perp := \left\{ \phi \in H^1(M) : \langle \phi, \psi \rangle_{H^1(M)} = 0 \quad \forall \psi \in K_{\varepsilon, \tau, s, t} \right\}.$$

Let $\lambda_{\varepsilon,\tau,s,t,0}$ and $\lambda_{\varepsilon,\tau,s,t,i,j}$ be real numbers such that

$$\begin{aligned} DJ_{\varepsilon}(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}) &= \lambda_{\varepsilon,\tau,s,t,0} \left(\frac{d}{d\hat{s}} [z_{\varepsilon,s}] \right)^{-1} \langle 1, \cdot \rangle_{H^1(M)} \\ &\quad + \sum_{i=1}^k \sum_{j=0}^n \lambda_{\varepsilon,\tau,s,t,i,j} \delta_{\varepsilon}^{-1} \langle Z_{\varepsilon,\tau_i,s,t_i,j}, \cdot \rangle_{H^1(M)}. \end{aligned} \quad (4.1)$$

In particular, for any $i_0 \in \{1, \dots, k\}$, we obtain

$$\begin{aligned} &\frac{d}{d\hat{t}_{i_0}} [J_{\varepsilon}(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})] \\ &= \lambda_{\varepsilon,\tau,s,t,0} \left(\frac{d}{d\hat{s}} [z_{\varepsilon,s}] \right)^{-1} \left\langle 1, \frac{d}{d\hat{t}_{i_0}} [u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}] \right\rangle_{H^1(M)} \\ &\quad + \sum_{i=1}^k \sum_{j=0}^n \lambda_{\varepsilon,\tau,s,t,i,j} \delta_{\varepsilon}^{-1} \left\langle Z_{\varepsilon,\tau_i,s,t_i,j}, \frac{d}{d\hat{t}_{i_0}} [u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}] \right\rangle_{H^1(M)}. \end{aligned} \quad (4.2)$$

Observe that

$$\frac{d}{d\hat{t}_{i_0}} [u_{\varepsilon,\tau,s,t}] = \frac{d}{d\hat{t}_{i_0}} [W_{\varepsilon,\tau_{i_0},s,t_{i_0}}] = \frac{n^{\frac{n-2}{4}} (n-2)^{\frac{n+2}{4}}}{2t_{i_0}} \delta_{\varepsilon} Z_{\varepsilon,\tau_{i_0},s,t_{i_0},0}. \quad (4.3)$$

From now on we fix a compact subset A of $Y \times \mathbb{R}^{k+1}$. All the estimates below will be uniform in $(\tau, \hat{s}, \hat{t}) \in A$. As $\varepsilon \rightarrow 0$, rough estimates give

$$\langle 1, Z_{\varepsilon,\tau_{i_1},s,t_{i_1},j_1} \rangle_{H^1(M)} = O\left(\mu_{\varepsilon,\hat{s}}^{\frac{n-2}{2}}\right) \quad (4.4)$$

and

$$\langle Z_{\varepsilon,\tau_{i_1},s,t_{i_1},j_1}, Z_{\varepsilon,\tau_{i_2},s,t_{i_2},j_2} \rangle_{H^1(M)} = \|V_{j_1}\|_{H^1(M)}^2 \delta_{i_1}^{i_2} \delta_{j_1}^{j_2} + o(\delta_{\varepsilon}) \quad (4.5)$$

for all $i_1, i_2 \in \{1, \dots, k\}$ and $j_1, j_2 \in \{0, \dots, n\}$, where $\delta_a^b = 0$ if $a \neq b$ and $\delta_a^a = 1$ if $a = b$. On the other hand, since $\phi_{\varepsilon,\tau,s,t} \in K_{\varepsilon,\tau,s,t}^{\perp}$, we obtain

$$\left\langle 1, \frac{d}{d\hat{t}_{i_0}} [\phi_{\varepsilon,\tau,s,t}] \right\rangle_{H^1(M)} = 0 \quad (4.6)$$

and

$$\begin{aligned} &\left\langle Z_{\varepsilon,\tau_i,s,t_i,j}, \frac{d}{d\hat{t}_{i_0}} [\phi_{\varepsilon,\tau,s,t}] \right\rangle_{H^1(M)} \\ &= - \left\langle \frac{d}{d\hat{t}_{i_0}} [Z_{\varepsilon,\tau_i,s,t_i,j}], \phi_{\varepsilon,\tau,s,t} \right\rangle_{H^1(M)} \end{aligned} \quad (4.7)$$

for all $i \in \{1, \dots, k\}$ and $j \in \{0, \dots, n\}$. A straightforward computation gives

$$\left\| \frac{d}{d\hat{t}_{i_0}} [Z_{\varepsilon,\tau_i,s,t_i,j}] \right\|_{H^1(M)} = O(\delta_{\varepsilon}). \quad (4.8)$$

It follows from Cauchy–Schwarz inequality, (2.2), (3.1), (4.7), and (4.8) that

$$\left\langle Z_{\varepsilon, \tau_i, s, t, i, j}, \frac{d}{d\hat{t}_{i_0}} [\phi_{\varepsilon, \tau, s, t}] \right\rangle_{H^1(M)} = o(\delta_\varepsilon). \quad (4.9)$$

Putting together (4.2)–(4.6) and (4.9), we obtain

$$\begin{aligned} \frac{d}{d\hat{t}_{i_0}} [J_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t})] &= \frac{n^{\frac{n-2}{4}} (n-2)^{\frac{n+2}{4}}}{2t_{i_0}} \|V_0\|_{H^1(M)}^2 \lambda_{\varepsilon, \tau, s, t, i_0, j} \\ &+ O\left(\left(\frac{d}{d\hat{s}} [z_{\varepsilon, s}]\right)^{-1} \delta_\varepsilon \mu_{\varepsilon, s}^{\frac{n-2}{2}} |\lambda_{\varepsilon, \tau, s, t, 0}|\right) + o\left(\delta_\varepsilon \sum_{i=1}^k \sum_{j=0}^n |\lambda_{\varepsilon, \tau, s, t, i, j}|\right). \end{aligned} \quad (4.10)$$

It remains to estimate the real numbers $\lambda_{\varepsilon, \tau, s, t, 0}$ and $\lambda_{\varepsilon, \tau, s, t, i, j}$. We begin with estimating $\lambda_{\varepsilon, \tau, s, t, 0}$. From (4.1) and (4.4), we obtain

$$\begin{aligned} \lambda_{\varepsilon, \tau, s, t, 0} &= \text{Vol}_g(M)^{-1} DJ_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) \cdot \frac{d}{d\hat{s}} [z_{\varepsilon, s}] \\ &+ O\left(\delta_\varepsilon^{-1} \mu_{\varepsilon, s}^{\frac{n-2}{2}} \frac{d}{d\hat{s}} [z_{\varepsilon, s}] \sum_{i=1}^k \sum_{j=0}^n |\lambda_{\varepsilon, \tau, s, t, i, j}|\right). \end{aligned} \quad (4.11)$$

By observing that

$$\int_M \phi_{\varepsilon, \tau, s, t} dv_g = \langle 1, \phi_{\varepsilon, \tau, s, t} \rangle_{H^1(M)} = 0,$$

we obtain

$$\begin{aligned} DJ_\varepsilon(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t}) \cdot 1 &= DJ_\varepsilon(u_{\varepsilon, \tau, s, t}) \cdot 1 - \int_M [(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t})^{2^*-1} \\ &- u_{\varepsilon, \tau, s, t}^{2^*-1} - (2^* - 1) z_{\varepsilon, s}^{2^*-2} \phi_{\varepsilon, \tau, s, t}] dv_g. \end{aligned} \quad (4.12)$$

Moreover, by using Cauchy–Schwarz and Sobolev inequalities, we obtain

$$\begin{aligned} &\int_M [(u_{\varepsilon, \tau, s, t} + \phi_{\varepsilon, \tau, s, t})^{2^*-1} - u_{\varepsilon, \tau, s, t}^{2^*-1} - (2^* - 1) z_{\varepsilon, s}^{2^*-2} \phi_{\varepsilon, \tau, s, t}] dv_g \\ &= O\left(z_{\varepsilon, s}^{2^*-3} \int_M \phi_{\varepsilon, \tau, s, t}^2 dv_g + z_{\varepsilon, s}^{2^*-3} \sum_{i=1}^k \int_M W_{\varepsilon, \tau_i, s, t_i} |\phi_{\varepsilon, \tau, s, t}| dv_g \right. \\ &\quad \left. + \sum_{i=1}^k \int_M W_{\varepsilon, \tau_i, s, t_i}^{2^*-2} |\phi_{\varepsilon, \tau, s, t}| dv_g + \int_M |\phi_{\varepsilon, \tau, s, t}|^{2^*-1} dv_g\right) \\ &= O\left(z_{\varepsilon, s}^{2^*-3} \|\phi_{\varepsilon, \tau, s, t}\|_{H^1(M)}^2 + z_{\varepsilon, s}^{2^*-3} \sum_{i=1}^k \|W_{\varepsilon, \tau_i, s, t_i}\|_{L^{\frac{2n}{n+2}}(M)} \|\phi_{\varepsilon, \tau, s, t}\|_{H^1(M)} \right. \\ &\quad \left. + \sum_{i=1}^k \|W_{\varepsilon, \tau_i, s, t_i}^{2^*-2}\|_{L^{\frac{2n}{n+2}}(M)} \|\phi_{\varepsilon, \tau, s, t}\|_{H^1(M)} + \|\phi_{\varepsilon, \tau, s, t}\|_{H^1(M)}^{2^*-1}\right). \end{aligned} \quad (4.13)$$

It follows from (2.2), (3.1), (3.6), (3.7), and (4.13) that

$$\begin{aligned} \int_M [(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} - (2^* - 1) z_{\varepsilon,s}^{2^*-2} \phi_{\varepsilon,\tau,s,t}] dv_g \\ = O(\mu_{\varepsilon,s}^{n-2}). \end{aligned} \quad (4.14)$$

Putting together (4.11), (4.12), and (4.14), we obtain

$$\begin{aligned} \lambda_{\varepsilon,\tau,s,t,0} = \text{Vol}_g(M)^{-1} DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot \frac{d}{d\hat{s}} [z_{\varepsilon,s}] + O\left(\mu_{\varepsilon,s}^{n-2} \frac{d}{d\hat{s}} [z_{\varepsilon,s}]\right) \\ + O\left(\delta_\varepsilon^{-1} \mu_{\varepsilon,s}^{\frac{n-2}{2}} \frac{d}{d\hat{s}} [z_{\varepsilon,s}] \sum_{i=1}^k \sum_{j=0}^n |\lambda_{\varepsilon,\tau,s,t,i,j}|\right). \end{aligned} \quad (4.15)$$

Now we estimate the real numbers $\lambda_{\varepsilon,\tau,s,t,i,j}$ for all $i \in \{1, \dots, k\}$ and $j \in \{0, \dots, n\}$. From (4.1), (4.4), and (4.5), we obtain

$$\begin{aligned} \lambda_{\varepsilon,\tau,s,t,i,j} = \|V_j\|_{H^1(M)}^{-2} DJ_\varepsilon(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}) \cdot (\delta_\varepsilon Z_{\varepsilon,\tau_i,s,t_i,j}) \\ + O\left(\left(\frac{d}{d\hat{s}} [z_{\varepsilon,s}]\right)^{-1} \delta_\varepsilon \mu_{\varepsilon,s}^{\frac{n-2}{2}} |\lambda_{\varepsilon,\tau,s,t,0}|\right) + o\left(\delta_\varepsilon \sum_{i'=1}^k \sum_{j'=0}^n |\lambda_{\varepsilon,\tau,s,t,i',j'}|\right). \end{aligned} \quad (4.16)$$

By integrating by parts, we obtain

$$\begin{aligned} DJ_\varepsilon(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t}) \cdot Z_{\varepsilon,\tau_i,s,t_i,j} = DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot Z_{\varepsilon,\tau_i,s,t_i,j} \\ + \int_M [\Delta_g Z_{\varepsilon,\tau_i,s,t_i,j} + \varepsilon Z_{\varepsilon,\tau_i,s,t_i,j} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} Z_{\varepsilon,\tau_i,s,t_i,j}] \phi_{\varepsilon,\tau,s,t} dv_g \\ - \int_M [(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} \\ - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} \phi_{\varepsilon,\tau,s,t}] Z_{\varepsilon,\tau_i,s,t_i,j} dv_g. \end{aligned} \quad (4.17)$$

By using Cauchy–Schwarz and Sobolev inequalities, we obtain

$$\begin{aligned} \int_M [\Delta_g Z_{\varepsilon,\tau_i,s,t_i,j} + \varepsilon Z_{\varepsilon,\tau_i,s,t_i,j} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} Z_{\varepsilon,\tau_i,s,t_i,j}] \phi_{\varepsilon,\tau,s,t} dv_g \\ = O\left(\left\| \Delta_g Z_{\varepsilon,\tau_i,s,t_i,j} + \varepsilon Z_{\varepsilon,\tau_i,s,t_i,j} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} Z_{\varepsilon,\tau_i,s,t_i,j} \right\|_{L^{\frac{2n}{n+2}}(M)} \right. \\ \left. \times \|\phi_{\varepsilon,\tau,s,t}\|_{H^1(M)}\right). \end{aligned} \quad (4.18)$$

By observing that

$$\Delta_g Z_{\varepsilon,\tau_i,s,t_i,j} + \varepsilon Z_{\varepsilon,\tau_i,s,t_i,j} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} Z_{\varepsilon,\tau_i,s,t_i,j} = O(W_{\varepsilon,\tau_i,s,t_i}),$$

and using (2.2), (3.1), (3.6), and (4.18), we obtain

$$\begin{aligned} \int_M [\Delta_g Z_{\varepsilon,\tau_i,s,t_i,j} + \varepsilon Z_{\varepsilon,\tau_i,s,t_i,j} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} Z_{\varepsilon,\tau_i,s,t_i,j}] \phi_{\varepsilon,\tau,s,t} dv_g \\ = O(\mu_{\varepsilon,s}^{n-2}). \end{aligned} \quad (4.19)$$

With regard to the last term in the right-hand side of (4.17), by observing that $Z_{\varepsilon,\tau_i,s,t_i,j} = O(W_{\varepsilon,\tau_i,s,t_i})$ and using Cauchy–Schwarz and Sobolev inequalities, we obtain

$$\begin{aligned}
& \int_M \left[(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} \phi_{\varepsilon,\tau,s,t} \right] \\
& \quad \times Z_{\varepsilon,\tau_i,s,t_i,j} dv_g = O \left(\int_M \left(W_{\varepsilon,\tau_i,s,t_i}^{2^*-3} |\phi_{\varepsilon,\tau,s,t}| + z_{\varepsilon,s} W_{\varepsilon,\tau_i,s,t_i}^{2^*-3} \right. \right. \\
& \quad \left. \left. + \sum_{l \neq i} W_{\varepsilon,\tau_l,s,t_l} W_{\varepsilon,\tau_i,s,t_i}^{2^*-3} + z_{\varepsilon,s}^{2^*-2} + \sum_{l \neq i} W_{\varepsilon,\tau_l,s,t_l}^{2^*-2} + |\phi_{\varepsilon,\tau,s,t}|^{2^*-2} \right) \right. \\
& \quad \left. \times W_{\varepsilon,\tau_i,s,t_i} |\phi_{\varepsilon,\tau,s,t}| dv_g \right) = O \left(\left(\|W_{\varepsilon,\tau_i,s,t_i}\|_{H^1(M)}^{2^*-2} \|\phi_{\varepsilon,\tau,s,t}\|_{H^1(M)} \right. \right. \\
& \quad \left. \left. + z_{\varepsilon,s} \|W_{\varepsilon,\tau_i,s,t_i}^{2^*-2}\|_{L^{\frac{2n}{n+2}}(M)} + \sum_{l \neq i} \|W_{\varepsilon,\tau_l,s,t_l} W_{\varepsilon,\tau_i,s,t_i}^{2^*-2}\|_{L^{\frac{2n}{n+2}}(M)} \right. \right. \\
& \quad \left. \left. + z_{\varepsilon,s}^{2^*-2} \|W_{\varepsilon,\tau_i,s,t_i}\|_{L^{\frac{2n}{n+2}}(M)} + \sum_{l \neq i} \|W_{\varepsilon,\tau_l,s,t_l} W_{\varepsilon,\tau_i,s,t_i}\|_{L^{\frac{2n}{n+2}}(M)} \right. \right. \\
& \quad \left. \left. + \|W_{\varepsilon,\tau_i,s,t_i}\|_{H^1(M)} \|\phi_{\varepsilon,\tau,s,t}\|_{H^1(M)}^{2^*-2} \right) \|\phi_{\varepsilon,\tau,s,t}\|_{H^1(M)} \right). \quad (4.20)
\end{aligned}$$

From (2.2), (3.1), (3.6)–(3.8), (4.20), and since $\|W_{\varepsilon,\tau_i,s,t_i}\|_{H^1(M)} = O(1)$, we obtain

$$\begin{aligned}
& \int_M \left[(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})^{2^*-1} - u_{\varepsilon,\tau,s,t}^{2^*-1} - (2^* - 1) W_{\varepsilon,\tau_i,s,t_i}^{2^*-2} \phi_{\varepsilon,\tau,s,t} \right] \\
& \quad \times Z_{\varepsilon,\tau_i,s,t_i,j} dv_g = O(\mu_{\varepsilon,s}^{n-2}). \quad (4.21)
\end{aligned}$$

Putting together (4.16), (4.17), (4.19), and (4.21), we obtain

$$\begin{aligned}
& \lambda_{\varepsilon,\tau,s,t,i,j} = \|V_j\|_{H^1(M)}^{-2} DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot (\delta_\varepsilon Z_{\varepsilon,\tau_i,s,t_i,j}) + O(\delta_\varepsilon \mu_{\varepsilon,s}^{n-2}) \\
& \quad + O \left(\left(\frac{d}{d\hat{s}} [z_{\varepsilon,s}] \right)^{-1} \delta_\varepsilon \mu_{\varepsilon,s}^{\frac{n-2}{2}} |\lambda_{\varepsilon,\tau,s,t,0}| \right) + o \left(\delta_\varepsilon \sum_{i'=1}^k \sum_{j'=0}^n |\lambda_{\varepsilon,\tau,s,t,i',j'}| \right). \quad (4.22)
\end{aligned}$$

It follows from (4.3), (4.10), (4.15), and (4.22) that

$$\begin{aligned}
& \frac{d}{d\hat{t}_{i_0}} [J_\varepsilon(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})] = \frac{d}{d\hat{t}_{i_0}} [J_\varepsilon(u_{\varepsilon,\tau,s,t})] + O(\delta_\varepsilon \mu_{\varepsilon,s}^{n-2}) \\
& \quad + O \left(|DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot 1| \delta_\varepsilon \mu_{\varepsilon,s}^{\frac{n-2}{2}} \right) \\
& \quad + o \left(\delta_\varepsilon \sum_{i=1}^k \sum_{j=0}^n |DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot (\delta_\varepsilon Z_{\varepsilon,\tau_i,s,t_i,j})| \right). \quad (4.23)
\end{aligned}$$

Similar computations as those performed in Section 3 give

$$\frac{d}{d\hat{t}_{i_0}} [J_\varepsilon(u_{\varepsilon,\tau,s,t})] = \begin{cases} \varepsilon^{-1/2} e^{-2s/\varepsilon} \left(\frac{c_2}{t_0} \hat{t}_{i_0} + o(1) \right) & \text{if } n = 4 \\ \varepsilon^{18/5} (-c_7 S_g(\xi_0) \hat{t}_{i_0} + o(1)) & \text{if } n = 5, \end{cases} \quad (4.24)$$

$$DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot 1 = \begin{cases} O(e^{-s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^{23/10}) & \text{if } n = 5, \end{cases} \quad (4.25)$$

and

$$DJ_\varepsilon(u_{\varepsilon,\tau,s,t}) \cdot Z_{\varepsilon,\tau_i,s,t_i,j} = \begin{cases} O(\varepsilon^{-1} e^{-2s/\varepsilon}) & \text{if } n = 4 \\ O(\varepsilon^3) & \text{if } n = 5 \end{cases} \quad (4.26)$$

for all $i \in \{1, \dots, k\}$ and $j \in \{0, \dots, n\}$. From (4.23)–(4.26), we obtain

$$\frac{d}{d\hat{t}_{i_0}} [J_\varepsilon(u_{\varepsilon,\tau,s,t} + \phi_{\varepsilon,\tau,s,t})] = \begin{cases} \varepsilon^{-1/2} e^{-2s/\varepsilon} \left(\frac{c_2}{t_0} \hat{t}_{i_0} + o(1) \right) & \text{if } n = 4 \\ \varepsilon^{18/5} (-c_7 S_g(\xi_0) \hat{t}_{i_0} + o(1)) & \text{if } n = 5. \end{cases}$$

This ends the proof of Proposition 2.3. \square

APPENDIX A. A CRITICAL POINT RESULT FOR PRODUCT SETS

In this appendix, we prove a critical point result which was used in Section 2. This result relies on a deformation argument using a negative gradient-type flow. A similar argument was used by Chen, Wei, and Yan [11] in the case of a function of two real variables.

The Lyapunov–Schmidt method crucially depends on the existence of critical points for families of functions $(F_\varepsilon)_{\varepsilon>0}$ which converge to a function F_0 . In case the limit function F_0 has a saddle point x_0 , if the functions F_ε converge only in C^0 to F_0 , then it is not true in general that there exist critical points of the functions F_ε which converge to x_0 , even when assuming that x_0 is a non-degenerate critical point of F_0 . From degree theory, we know that this property holds true if we replace C^0 –convergence by C^1 –convergence and we assume that the critical point x_0 is non-degenerate. The objective of the result below is to obtain this property under weaker conditions which only involve derivatives in some directions.

Lemma A.1. *Let $n_1, n_2 \geq 1$ be two integers, Ω_1 be a bounded and open subset of \mathbb{R}^{n_1} , Ω_2 be a bounded, open, and smooth subset of \mathbb{R}^{n_2} , and $\Omega := \Omega_1 \times \Omega_2$. Let F be a C^2 –function in a neighborhood of $\bar{\Omega}$ such that*

- (i) *The outward normal derivative of F on $\Omega_1 \times \partial\Omega_2$ is positive.*
- (ii) *There exists $\bar{x} \in \Omega_1$ such that $\inf_{\Omega_2} F(\bar{x}, \cdot) > \sup_{\partial\Omega_1 \times \Omega_2} F$.*

Then F has a critical point in (the interior of) Ω .

Proof of Lemma A.1. We assume by contradiction that the function F does not have any critical point in Ω .

We start our proof by constructing a negative gradient-type flow for the function F . From Point (ii) and the continuity of F on $\overline{\Omega}$, we obtain that there exists an open set U such that $\overline{U} \subset \Omega_1$ and

$$\inf_{\Omega_2} F(\overline{x}, \cdot) > \sup_{(\Omega_1 \setminus U) \times \Omega_2} F. \quad (\text{A.1})$$

We let V and W be two open sets such that $\overline{U} \subset V$, $\overline{V} \subset W$, and $\overline{W} \subset \Omega_1$. We let χ be a smooth cutoff function in \mathbb{R}^{n_1} such that $\chi \equiv 1$ in V , $\chi \equiv 0$ in $\mathbb{R}^{n_1} \setminus W$, and $0 \leq \chi \leq 1$ in $W \setminus V$. For $i \in \{1, 2\}$, we let $p_i : \mathbb{R}^{n_1+n_2} \rightarrow \mathbb{R}^{n_i}$ be the canonical projection, namely

$$p_i(x_1, x_2) := x_i \quad \forall x_1 \in \mathbb{R}^{n_1}, x_2 \in \mathbb{R}^{n_2}.$$

By assumption, we have that there exists an open subset D of $\mathbb{R}^{n_1+n_2}$ such that $F \in C^2(D)$ and $\overline{\Omega} \subset D$. From basic theory of ODEs, we then obtain the existence of a lower semi-continuous mapping $T : D \mapsto (0, \infty]$ and a C^2 -mapping $\Phi : D_T \mapsto \mathbb{R}^{n_1+n_2}$, where $D_T := \{(t, x) : x \in D \text{ and } t \in [0, T(x))\}$, such that for any $x \in D$, we have

$$\begin{cases} \frac{\partial \Phi}{\partial t}(t, x) = -\chi(p_1(\Phi(t, x))) \nabla F(\Phi(t, x)) & \forall t \in [0, T(x)) \\ \Phi(0, x) = x \end{cases}$$

and either $T(x) = \infty$ or $\Phi(t, x) \notin \overline{\Omega}$ when t approaches $T(x)$.

We prove that $\Phi(t, x) \in \overline{\Omega}$ for all $x \in \overline{\Omega}$ and $t \in [0, T(x))$, which implies in particular $T(x) = \infty$. We assume by contradiction that the curve $t \mapsto \Phi(t, x)$ leaves the set $\overline{\Omega}$, namely that there exist $t_-, t_+ \in [0, T(x))$ such that $t_- < t_+$, $\Phi(t_-, x) \in \partial\Omega$ and $\Phi(t, x) \notin \overline{\Omega}$ for all $t \in (t_-, t_+)$. Since $\Phi(t, x)$ is not constant in t , we infer from the uniqueness of the flow that $\frac{\partial \Phi}{\partial t}(t_-, x) \neq 0$. It follows that $\chi(p_1(\Phi(t_-, x))) \neq 0$, which gives $\Phi(t_-, x) \in \Omega_1 \times \partial\Omega_2$. From Point (i), we then obtain

$$\frac{d}{dt} \langle \Phi(t_-, x), \nu \rangle = -\chi(p_1(\Phi(t_-, x))) \langle \nabla F(\Phi(t_-, x)), \nu \rangle < 0, \quad (\text{A.2})$$

where $\langle \cdot, \cdot \rangle$ is the Euclidean scalar product and ν is the outward normal vector to $\Omega_1 \times \partial\Omega_2$ at the point $\Phi(t_-, x)$. This contradicts the fact that $\Phi(t, x) \notin \overline{\Omega}$ for all $t \in (t_-, t_+)$. Therefore we have proven that $T(x) = \infty$ and $\Phi(t, x) \in \overline{\Omega}$ for all $x \in \overline{\Omega}$ and $t \in [0, \infty)$.

Now we define

$$c := \inf_{h \in \Gamma} \sup_{x \in \Omega} F(h(x)),$$

where

$$\Gamma := \{h \in C^0(\overline{\Omega}, \overline{\Omega}) : h(x) = x \quad \forall x \in \partial\Omega_1 \times \Omega_2\}.$$

Our aim is to construct a mapping $h_0 \in \Gamma$ such that

$$\sup_{x \in \Omega} F(h_0(x)) < c \quad (\text{A.3})$$

so to obtain a contradiction.

Since $\bar{U} \subset V$ and $\Phi \in C^0([0, \infty) \times \Omega, \Omega)$, we obtain that there exists a real number $t_0 > 0$ such that $\Phi(t, U \times \Omega_2) \subset V \times \Omega_2$ for all $t \in [0, t_0]$. Since $F \in C^1(\bar{\Omega})$, $\bar{V} \subset \Omega_1$, $\nabla F \neq 0$ on $\Omega_1 \times \partial\Omega_2$ according to Point (i), and we have assumed at the beginning of the proof that $\nabla F \neq 0$ in Ω , we obtain the existence of a real number $\delta_0 > 0$ such that $|\nabla F| \geq \delta_0$ in $V \times \Omega_2$. From the definition of c , we obtain that there exists $h \in \Gamma$ such that

$$\sup_{x \in \Omega} F(h(x)) \leq c + \frac{t_0 \delta_0^2}{2}. \quad (\text{A.4})$$

Now we define $h_0 := \Phi(t_0, h)$, and we will prove (A.3). We separate the cases $h(x) \in U \times \Omega_2$ and $h(x) \in (\Omega_1 \setminus U) \times \Omega_2$. In case $h(x) \in U \times \Omega_2$, since $\Phi(t, U \times \Omega_2) \subset V \times \Omega_2$ for all $t \in [0, t_0]$, $\chi \equiv 1$ in V , and $|\nabla F| \geq \delta_0$ in $V \times \Omega_2$, we obtain

$$F(h(x)) - F(h_0(x)) = \int_0^{t_0} |\nabla F(\Phi(t, h(x)))|^2 dt \geq t_0 \delta_0^2. \quad (\text{A.5})$$

It follows from (A.4) and (A.5) that

$$\sup_{x \in h^{-1}(U \times \Omega_2)} F(h_0(x)) \leq c - \frac{t_0 \delta_0^2}{2}. \quad (\text{A.6})$$

On the other hand, since the function $t \mapsto F(\Phi(t, h(x)))$ is nonincreasing for all $x \in h^{-1}((\Omega_1 \setminus U) \times \Omega_2)$, it follows from (A.1) that

$$\sup_{x \in h^{-1}((\Omega_1 \setminus U) \times \Omega_2)} F(h_0(x)) < \inf_{\Omega_2} F(\bar{x}, \cdot). \quad (\text{A.7})$$

It remains to prove

$$\inf_{\Omega_2} F(\bar{x}, \cdot) \leq c. \quad (\text{A.8})$$

We fix a point $\bar{y} \in \Omega_2$. For any mapping $h \in \Gamma$, we define $\bar{h} := p_1(h(\cdot, \bar{y}))$. We infer from the properties of h that $\bar{h} \in C^0(\bar{\Omega}_1, \bar{\Omega}_1)$ and $\bar{h}(x) = x$ for all points $x \in \partial\Omega_1$. We then obtain from degree theory that $\bar{h}(\bar{\Omega}_1) = \bar{\Omega}_1$ (see Poincaré–Bohl theorem in [31]). In particular, we obtain that there exists a point $x_0 \in \Omega_1$ such that $\bar{h}(x_0) = \bar{x}$. From the definition of \bar{h} , it follows that there exists a point $y_0 \in \Omega_2$ such that $h(x_0, \bar{y}) = (\bar{x}, y_0)$. We then obtain

$$\inf_{\Omega_2} F(\bar{x}, \cdot) \leq F(\bar{x}, y_0) = F(h(x_0, \bar{y})) \leq \sup_{x \in \Omega} F(h(x)). \quad (\text{A.9})$$

Since (A.9) holds true for all mappings $h \in \Gamma$, we obtain (A.8).

Finally (A.3) follows from (A.6), (A.7), and (A.8). This ends the proof of Lemma A.1. \square

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