

Differential Categories II

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(joint work with Rick Blute & Robin Cockett)

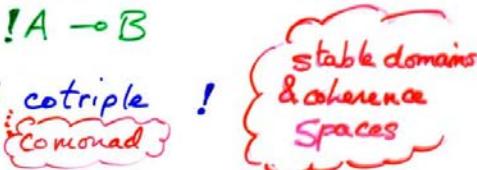
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Introduction

- Motivating example of linear logic

$$A \Rightarrow B = !A \multimap B$$

- cokleisli category of cotriple $!$


stable domains
& coherence
Spaces

- Differential λ -calculus of Ehrhard & Regnier


Köthe spaces
Finiteness spaces

Our aim:

Categorically "reconstruct" the E-R differential structure

symmetric

Basic setting: monoidal category with comonad on it

Intuition: The "base category" maps are "linear"

Cokleisli maps are "smooth"

An illustration of how this works

$$\text{A smooth map } f: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \quad f(x,y,z) = \langle x^2 + xyz, z^3 - xy \rangle$$

$$\text{Its Jacobian} \begin{pmatrix} 2x+yz & xz & xy \\ -y & -x & 3z^2 \end{pmatrix}$$

For chosen $\langle x, y, z \rangle$ this is a linear map $\mathbb{R}^3 \rightarrow \mathbb{R}^2$

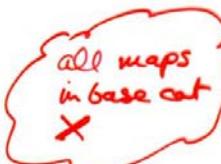
i.e. from $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$
we get $D[f]: A \rightarrow \text{Lin}(\mathbb{R}^n, \mathbb{R}^m)$


These are
both smooth
ie Cokleisli
maps

So: in our setting we would have this:

$$\begin{array}{c} f: !A \rightarrow B \\ \hline D[f]: !A \rightarrow (A \multimap B) \end{array}$$


all maps
in base cat


Linear
Hom

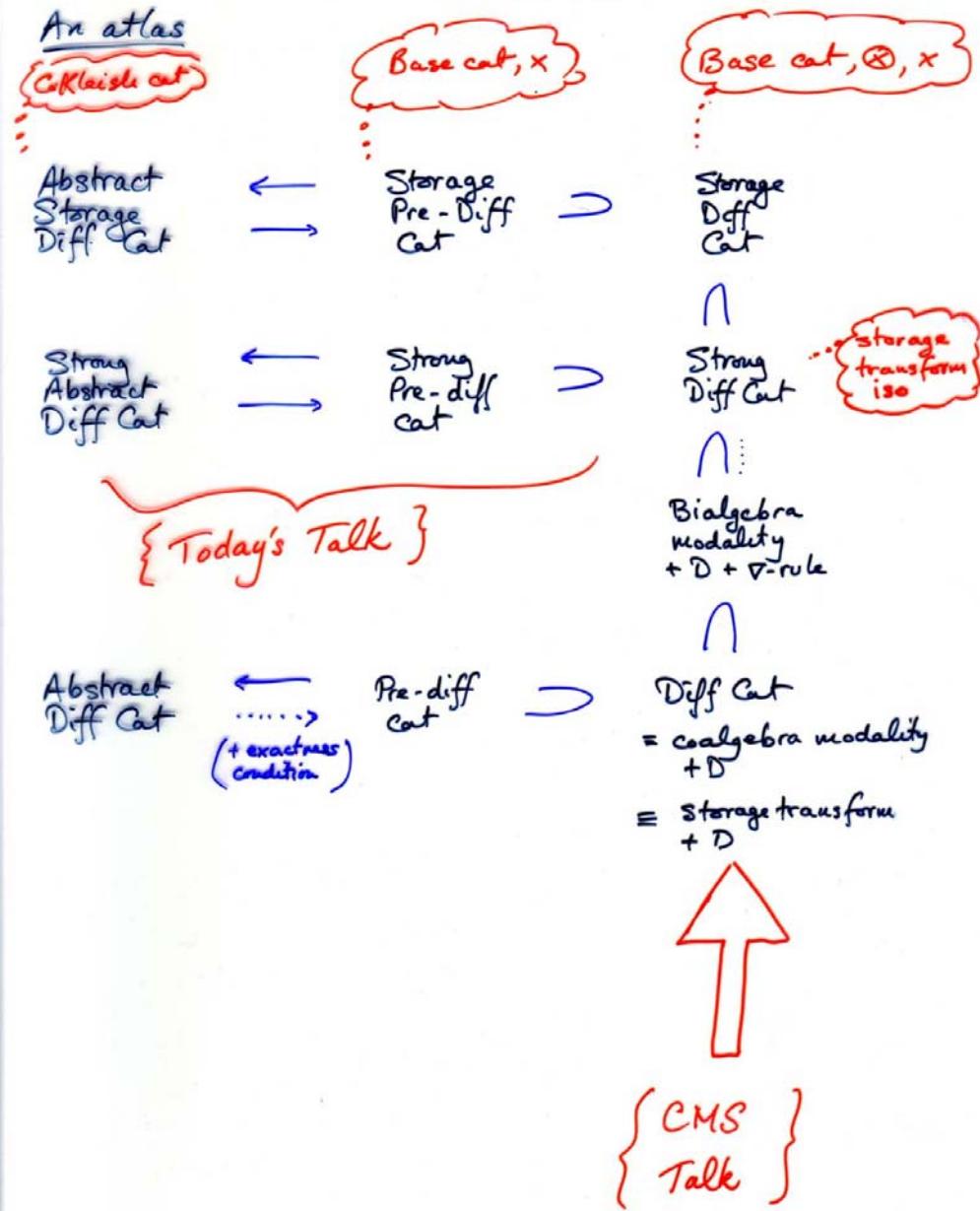
To avoid the need for closed structure, we shall take

$$D[f]: A \otimes !A \rightarrow B$$

Outline of talk

- Basic definition of differential category
 - coalgebra modality on a (semi) additive symmetric monoidal category
 - differential combinator
- Question: how can we characterize the cokleisli category of such a diff cat?
 - we shall drop the tensor structure
 - define two secondary notions:
 - Cartesian differential categories ... "cokleisli cats"
 - Pre differential categories \otimes -free diff cats
 - examine the connection between these & between prediff cats & diff cats

[Technical remark: all this is "cleanest" in the "strong" case - our focus today]



Basic context

- (semi) additive symmetric monoidal category \mathcal{X}
 - commutative monoid enriched
no assumption of biproducts - yet!
 - Eg sets & relations
in (semi)additive but not AbGrp-enriched

- coalgebra modality!
 - a cotriple (comonad)
 - $T \xleftarrow{\epsilon} !X \xrightarrow{\Delta} !X \otimes !X$ natural coalgebra str.
 - $(!X, \Delta, \epsilon)$ is a comonoid

$$\begin{array}{c} !X \xrightarrow{\Delta} !X \otimes !X \\ \Delta \downarrow \quad \downarrow \Delta \circ \epsilon \\ !X \otimes !X \xrightarrow{\text{coa}} !X \otimes !X \end{array}$$

$$\begin{array}{c} !X \xrightarrow{\epsilon} !X \otimes !X \\ \epsilon \downarrow \quad \downarrow \epsilon \circ \Delta \\ !X \xleftarrow{\text{coe}} !X \otimes !X \end{array}$$

commute
 - $\delta: !X \rightarrow !!X$ is a comonoid morphism

$$\begin{array}{ccc} !X & \xrightarrow{\delta} & !!X \\ \epsilon \downarrow & & \downarrow \epsilon \\ T & \xrightarrow{\epsilon} & !X \otimes !X \\ & \downarrow \delta \circ \epsilon & \\ & !X \otimes !X & \xrightarrow{\text{coa}} !!X \otimes !!X \end{array}$$

commute

[we don't assume that δ , or any of these transformations are monoidal - yet]

Intuition: $!A \rightarrow B$ is "a differentiable map $A \rightarrow B$ "
(but we need more structure to realize this)

Storage

Given a s.m.cat with products and a comonad!
a comonoidal transformation $s: ! \rightarrow !$
from $(\mathcal{X}, \times, 1)$ to $(\mathcal{X}, \otimes, T)$ amounts to
 $s_0: !(1) \rightarrow T$ and $s_2: !(X \times Y) \rightarrow !X \otimes !Y$

$$\begin{array}{ccccc} \text{st} & !(X \times Y \times Z) & \xrightarrow{s_2} & !(X \times Y) \otimes !Z & \xrightarrow{s_2 \otimes 1} (!X \otimes !Y) \otimes !Z \\ & \downarrow !(\alpha_x) & & \downarrow !\alpha_\otimes & \\ & !(X \times (Y \times Z)) & \xrightarrow{s_2} & !X \otimes !(Y \times Z) & \xrightarrow{!s_2} !X \otimes (!Y \otimes !Z) \\ & & & & \\ & !(1 \times X) & \xrightarrow{s_2} & !(1) \otimes !X & \xrightarrow{s_2 \otimes 1} !X \otimes !(1) \\ & \downarrow !\pi_1 & & \downarrow !s_0 \otimes 1 & \downarrow !s_0 \\ & !X & \xleftarrow{u_0} & T \otimes !X & \xleftarrow{u_0} !X \otimes T \end{array}$$

(+ diagram for symmetry if appropriate)

(as a comonad)

In our setting, requiring that $!$ be comonoidal is too strong - we'd want δ to be so, but not ϵ (The Id functor is not comonoidal)

$$\begin{array}{ccc} F(X \times Y) & \xrightarrow{\alpha} & G(X \times Y) \\ \downarrow \delta^F & & \downarrow \delta^G \\ FX \otimes FY & \xrightarrow{\alpha \otimes \alpha} & GX \otimes GY \end{array}$$

$F(1) \xrightarrow{\epsilon} G(1)$

$$\begin{array}{ccc} \delta^F & \swarrow & \downarrow \delta^G \\ & T & \end{array}$$

no such δ^G for $G = \text{Id}$

A (sym)cat \mathcal{X} with comonad $!$, products has a storage transformation if there is a comonoidal transformation

$$s : ! \rightarrow ! : (\mathcal{X}, \times, 1) \rightarrow (\mathcal{X}, \otimes, T)$$

so that s is comonoidal

(using the canonical
comonoidal trans $(\mathcal{X}, \times, 1) \leftrightarrow$
ie $!(X \times Y) \rightarrow !X \times !Y$
 $!(1) \rightarrow 1$)

Key Fact:

For a (symm) monoidal cat with products:
to have a comonad with (symm) storage trans is equiv.
to having a (cocommutative) coalgebra modality.

$$\begin{aligned} (\Downarrow) \text{ Define } \Delta : !X &\xrightarrow{\Delta_X} !(X \times X) \xrightarrow{s_2} !X \otimes !X \\ e : !X &\xrightarrow{!e} !(1) \xrightarrow{s_0} T \end{aligned}$$

$$\begin{aligned} (\Uparrow) \text{ Define } s_2 : !(X \times Y) &\xrightarrow{\Delta} !(X \times Y) \otimes !(X \times Y) \xrightarrow{!c_0 \otimes !c_1} !X \otimes !Y \\ s_0 : !(1) &\xrightarrow{e} T \end{aligned}$$

This works!

Examples

- id on aug cat with finite products
- $!$ in linear logic
- Dual of "algebra modality"
 - The free algebra $T(X) = \bigoplus_{n=0}^{\infty} X^{\otimes n}$
 - The free symmetric algebra $Sym(X) = \bigoplus_{n=0}^{\infty} X^{\otimes n}/S_n$
 - The "exterior algebra" $\Lambda(X) = \bigoplus_{n=0}^{\infty} X^{\otimes n}/A$
so $xy = -yz$

Differential Combinators

$$D_{AB} : \mathcal{X}(!A, B) \longrightarrow \mathcal{X}(A \otimes !A, B)$$

$$\frac{!A \xrightarrow{f} B}{A \otimes !A \xrightarrow{DEF} B} \quad \dots \quad \text{Think } !A \rightarrow (A \multimap B)$$

This must satisfy:

- naturality (for combinators), additivity
- "constants have deriv = 0" $D[e] = 0$
- product rule $(1 \otimes \Delta)(D[f] \otimes g) + (1 \otimes \Delta)(c_0)(f \circ D[g]) = D[\Delta(f \circ g)]$
- "Linear maps have constant deriv" $D[ef] = (1 \otimes e)f$
- chain rule $D[\delta !fg] = (1 \otimes \Delta)(D[f] \otimes \delta !f)D[g]$

There is a "circuit calculus" for all this ...

Preliminaries (\rightarrow cartesian differential categories)

(semi)

left/additive category : each hom set is a commutative monoid

$$f(g+h) = fg + fh$$

$$f0 = 0$$

diagrammatic order
of composition

A map h is additive if also

$$(fg)h = fh + gh$$

$$0h = 0$$

Prop The additive maps of a left additive category \mathcal{X} form an additive subcategory \mathcal{Y}_+ .

The inclusion $\mathcal{Y}_+ \hookrightarrow \mathcal{X}$ reflects isos.

Eg Commutative monoids with "set" maps

no preservation properties

form a left additive, not additive, category

Left additive: because operations are def'd pointwise

Not additive: because maps need not preserve monoid str.

Those that do are in \mathcal{Y}_+ .

Cartesian Differential categories

- Left additive
- products
- a cartesian differential operator

$$\begin{array}{c} X \xrightarrow{f} Y \\ X \times X \xrightarrow{D_x[f]} Y \end{array}$$

Think: 1st arg t
is "linear";
2nd is "smooth"

satisf several axioms:

$$[CD1] D_x[f+g] = D_x[f] + D_x[g] ; D_x[0] = 0$$

$$[CD2] \langle h+k, v \rangle D_x[f] = \langle h, v \rangle D_x[f] + \langle k, v \rangle D_x[f]$$

$$\langle 0, v \rangle D_x[f] = 0$$

$$[CD3] D_x[1] = \pi_0 ; D_x[\pi_i] = \pi_0 \pi_i \quad (i=0,1)$$

$$[CD4] D_x[\langle f, g \rangle] = \langle D_x[f], D_x[g] \rangle$$

$$[CD5] D_x[fg] = \langle D_x[f], \pi_1 f \rangle D_x[g]$$

Example: Fin dim vector spaces over \mathbb{R} (or \mathbb{C} ...) with ∞^{∞} differentiable maps

- D_x given by Jacobian

"just like" the diff cat eg

"Linear maps"

In a cart diff cat, f is linear if

$$D_x[f] = \pi_0 f$$

Prop: The linear maps form an additive subcat \mathcal{Y}_{lin} of a cart diff cat \mathcal{Y} ; \mathcal{Y}_{lin} has (bi)products; $\mathcal{Y}_{\text{lin}} \hookrightarrow \mathcal{Y}$ reflects isos & creates products

Prop: The cokleisli category of a differential cat with biproducts is a cartesian differential cat

define $D_x[f]$, for $X \xrightarrow{f} Y$, to be:

$$\begin{array}{ccccc} S(X \times X) & \xrightarrow{\Delta} & S(X \times X) \otimes S(X \times X) & \xrightarrow{S\pi_0 \otimes S\pi_1} & S(X) \otimes S(X) \\ & \searrow S_2 & & & \downarrow \epsilon \otimes 1 \\ & & X \otimes S(X) & & \\ & & \downarrow D_0[f] & & \\ & & S(X) & & \end{array}$$

Notation: D_0 is the diff combinator for the diff cat
 $(D_x$ is the cart diff op)
 S is the comonad (called ! in linear logic)

MORE: The cokleisli cat of a diff cat also satisfies

- $D_x[\epsilon] = \pi_0 \epsilon$
- $D_x[S(f)] = \pi_0 S(f)$ (for any f)

STRONG Differential categories

• Diff cats with storage transformations S_0, S_2 iso (without further coherence - this is weaker than what we called "storage diff. cats")

In this context we can define some maps in the cokleisli cat:

$$\varphi: A \rightarrow S(A) \quad (\text{ie } id: S(A) \rightarrow S(A) \text{ in } \mathcal{X})$$

$$\eta: A \rightarrow S(A) := \epsilon(1 \otimes \iota)d_0$$

$$\text{ie } S(A) \xrightarrow{\epsilon_{1A}} A \otimes I \xrightarrow{1 \otimes \iota} A \otimes S(A) \xrightarrow{d_0} S(A) \text{ in } \mathcal{X}$$

$$d_x: A \times A \rightarrow S(A) := D_x[\varphi]$$

$$\text{ie } S(A \times A) \xrightarrow{S_2} S(A) \otimes S(A) \xrightarrow{\epsilon \otimes 1} A \otimes S(A) \xrightarrow{d_0} S(A) \text{ in } \mathcal{X}$$

Prop: The cokleisli cat of a strong diff cat satisfies:

- η is " ϵ -natural" [$\epsilon\eta = S(\eta)\epsilon$]
- $\eta = \langle 1, 0 \rangle dx$
- $\eta\epsilon = 1$
- " ϵ -natural" \equiv "linear"
- $S(dx)\epsilon = s_2(\epsilon\eta \otimes 1) \nabla$
- $d_\otimes = (\eta \otimes 1) s_2^{-1} S(dx)\epsilon \dots$

NB In the cokleisli cat, ϵ is not a nat. transformation: f is " ϵ -natural" if the ϵ -naturality square with f commutes

So we can recapture d_\otimes from dx as well as vice versa

These are properties we shall want to hold in our characterization of cokleisli cats of (strong) diff cats.

Disclaimer:
The "not strong" case is more "fiddley"!

Abstract co K'leisli category

- cat \mathcal{Y} , functor $S: \mathcal{Y} \rightarrow \mathcal{Y}$
- nat. transf: $\varphi: A \rightarrow S(A)$
- unnatural transf: $\epsilon: S(A) \rightarrow A$
- $\epsilon\epsilon = S(\epsilon)\epsilon$ $\Rightarrow \epsilon$ is " ϵ -natural"
- $\varphi\epsilon = 1_A$ $S(\varphi)\epsilon = 1_{S(A)}$
- $\epsilon_{S(A)}: S(S(A)) \rightarrow S(A)$ is natural in A

... inspired by Carsten Führmann's charact of abstract Kleisli cats

This makes (S, φ, ϵ_S) a monad/triple on \mathcal{Y}

Let \mathcal{Y}_ϵ be the subcat of ϵ -natural maps

Then $(S, \epsilon, S(\varphi))$ is a comonad on \mathcal{Y}_ϵ and \mathcal{Y} is its cokleisli cat $(\mathcal{Y}_\epsilon)_S$

Q: Given a comonad S , what's the connection between X and $(X_S)_\epsilon$?
(for "any" X with a comonad S)

Technical remark

If \mathcal{Y} is an abstract cokleisli cat.

① $A \xrightarrow{\varphi} S(A) \xrightarrow{\varphi} S(S(A))$ is a (split) equalizer (forall A)

② $S(S(A)) \xrightarrow{S(\epsilon)} S(A) \xrightarrow{\epsilon} A$ is a (split) coequalizer ("")

The 2nd diagram is in \mathcal{X} ; it characterizes comonads from abstract cokleisli cats, in this sense:

FACT: The canonical functor (when X carries a comonad)

$X \rightarrow (X_S)_\epsilon$ is an iso iff ② is a coequalizer (forall A)

(call such S an exact comonad)

In the "strong" context, having η forces exactness

since then η makes ② a split coequalizer

$$\left\{ \begin{array}{l} \text{since } \epsilon\epsilon = S(\epsilon)\epsilon \\ \eta\epsilon = 1 \\ \eta S(\epsilon) = \epsilon\eta \end{array} \right\} \quad \text{so absolute}$$

(Without "strength", $X \rightarrow (X_S)_\epsilon$ need not even preserve what structure X has, so things become "fiddly", as we've said before)

\mathcal{Y} is an abstract additive cokleisli category if in addition

- left additive
- $\epsilon, S(f)$ (forall f) are additive

[This guarantees \mathcal{Y}_ϵ is in fact additive]

Furthermore, the cokleisli cat of a comonad on an additive cat satisfies these, so this characterizes cokleisli cats for comonads on additive cats]

\mathcal{Y} is a strong abstract differential category if in addition:

- cartesian diff. cat at π_0, Δ are ϵ -natural,
- $D_x[\epsilon] = \pi_0 \epsilon$
- $D_x[S(f)] = \pi_0 S(f)$ (forall f)
- $\eta := \langle 1, 0 \rangle D_x[\varphi]$ is ϵ -natural

[These guarantee all the properties of the earlier prop.

which hold of cokleisli cats of strong diff cats

- incl. " ϵ -natural" \equiv "linear"

]

Technical note (\leadsto "predifferential categories")

In this context (somewhat less suffices) we can define a "cartesian deriving transformation"

$$d_x : A \times A \longrightarrow S(A)$$

satisfying "the usual axioms", so that this structure is equivalent to having a cartesian differential operator D_x

An impressionist's view of the axioms:

$$[cd1] d_x S(fg) \epsilon = d_x S(f) \epsilon + d_x S(g) \epsilon ; d_x S(0) \epsilon = 0$$

$$[cd2] \langle h+k, v \rangle d_x = \langle h, v \rangle d_x + \langle k, v \rangle d_x ; \langle 0, v \rangle d_x = 0$$

$$[cd3] d_x \epsilon = \pi_0$$

$$[cd4] d_x S(\langle f, g \rangle) \epsilon = d_x \langle S(f) \epsilon, S(g) \epsilon \rangle$$

$$[cd5] \langle d_x S(f) \epsilon, \pi_1 f \rangle d_x S(g) \epsilon = d_x S(fg) \epsilon$$

STRONG

Pre differential Category

\mathbb{X} : additive with biproducts

comonad (S, ϵ, δ)

a "predifferential operator" $d'_x : S(A \times A) \rightarrow S(A)$

Think: this is a cokleisli map
 $A \times A \rightarrow S(A)$ - ie d_x in \mathbb{X}_S

$\eta : A \rightarrow SA$... we're in the "strong" setting

st

$$[pd1] \delta S(\langle h+k, v \rangle) d'_x = \delta [S(\langle h, v \rangle) + S(\langle k, v \rangle)] d'_x$$

$$[pd2] d'_x \epsilon = \epsilon \pi_0$$

$$[pd3] d'_x \delta S(f) g = \delta S(\langle d'_x f, S(\pi_1 f) \rangle) d'_x g$$

$$[spd1] \eta \epsilon = 1$$

$$[spd2] S(\langle 1, 0 \rangle) d'_x = \epsilon \eta$$

These are "cokleisli" translations of the axioms for d_x, η

The point of this:

- The cokleisli cat X_s of a \perp ^{strong} prediff. cat X is a \perp ^{strong} abstract diff cat st $(X_s)_c = X$
must assume some exactness in the "not-strong" case
- If \mathcal{Y} is a \perp ^{strong} abstract diff cat, then \mathcal{Y}_c is a \perp ^{strong} prediff cat [and of course $(\mathcal{Y}_c)_s = \mathcal{Y}$]
 $d'_x = S(d_x) \in$

So we've characterized abstract diff cats as cokleisli cats on prediff cats

- What about diff cats?
- What happened to \otimes ?

- Any ^{strong} differential cat "is" (ie induces) a ^{strong} pre differential cat

via:

$$d'_x := S(A \otimes A) \xrightarrow{s_2} S(A) \otimes S(A) \xrightarrow{e \otimes 1} A \otimes S(A) \xrightarrow{d_0} S(A)$$

whence:

Prop: X is a ^{strong} differential cat iff

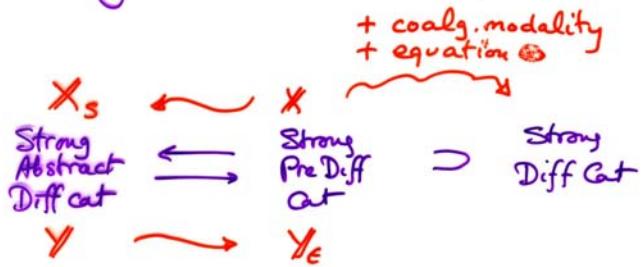
- X carries a ^{strong} coalgebra modality
- X is a ^{strong} predifferential category st

$$d'_x = s_2 ; (e \eta \otimes 1) ; \nabla \dots$$

Recall this property from previous slide.

$$d_0 = (\eta \otimes 1) \nabla$$

Look again at our "atlas":



Comment about "the fiddly bits":

- stepping "down" (dropping "strong") just requires care (& some exactness assumptions at times)
- stepping "up" ("storage" - ie the linear logic!) only affects the "abstract" column: how to describe storage "abstractly" can be done by examining the interaction of \otimes and X in cokleisli cats
[details are in the paper!]

"in preparation"

Future work?

- Examples would be nice ...
- Higher order version of this setting also ...
- Connect to other notions of differentiability ...
- Some of this is in progress, some still just "ambition" ...