## Least Squares and the Generalized Inverse

An important problem is to find a polynomial curve y = f(x) which 'best fits' a given set of m data points  $(x_1, y_1), (x_2, y_2), \ldots, (x_m, y_m)$ . If  $f(x) = a_0 + a_1 x + \cdots + a_{n-1} x^{n-1}$  then the given points lie on the curve y = f(x) if and only if  $y_i = f(x_i)$  for  $1 \le i \le m$  which is equivalent to the system of equations

$$a_{0} + a_{1}x_{1} + a_{2}x_{1}^{2} + \dots + a_{n-1}x_{1}^{n-1} = y_{1}$$

$$a_{0} + a_{1}x_{2} + a_{2}x_{2}^{2} + \dots + a_{n-1}x_{2}^{n-1} = y_{2}$$

$$\dots$$

$$a_{0} + a_{1}x_{m} + a_{2}x_{m}^{2} + \dots + a_{n-1}x_{m}^{n-1} = y_{m}$$

having a solution  $(a_0, a_1, \ldots, a_{n-1})$ . In general this system does not have a solution and we therefore try to find  $(a_0, a_1, \ldots, a_{n-1})$  which minimizes

$$\sum_{i=1}^{m} (y_i - f(x_i))^2$$

Such a vector is called a **least squares solution** of our system of equations. If  $m \ge n$  and at least n of the numbers  $x_1, \ldots, x_m$  are distinct then we will show that there is only one least squares solution. This gives a unique polynomial curve y = f(x) of degree n which best fits our data in the sense of least squares.

More generally, if A is a real  $m \times n$  matrix and  $Y \in \mathbb{R}^{n \times 1}$  then by a **least squares solution** of the system of equations AX = Y we mean any  $X \in \mathbb{R}^{n \times 1}$  which minimizes ||AX - Y||, the norm being the usual norm in  $\mathbb{R}^{m \times 1}$ . It follows that AX is the orthogonal projection B of Y on the column space of A. Thus, the least squares solutions of AX = Y are those column vectors X with AX = B. If rank(A)  $\neq$  n then the a squares solution is not unique. In the above example of finding a polynomial curve of best fit the matrix

$$A = \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & x_m^2 & \cdots & x_m^{n-1} \end{bmatrix}$$

which is of rank n if  $m \ge n$  and at least n of  $x_1, \ldots, x_m$  are distinct.

If AX = B and Z is the orthogonal projection of X on the column space of  $A^t$  then Z is the unique solution of AX = B which is in the column space of  $A^t$ . Indeed,  $X - Z \in \text{Null}(A)$  since the orthogonal complement of the column space of  $A^t$  is the null space of A so that AZ = AX = B. If  $Z_1$  is any vector in the column space of  $A^t$  with  $AZ_1 = B$  then  $Z - Z_1$  is in the intersection of the null space of A and the column space of  $A^t$  and so must be the zero vector. Since  $||Z|| \leq ||X||$  with equality if and only if X = Z, we see that Z is also the unique vector X of smallest norm with AX = B.

The function  $T : \mathbb{R}^{m \times 1} \to \mathbb{R}^{n \times 1}$  defined by T(Y) = Z is a linear mapping and so  $T = T_{A^+}$  for a unique  $n \times m$  matrix  $A^+$ . This matrix is called the **generalized inverse** of A. It is characterized by the property that  $A^+Y$  is the least squares solution of AX = Y of smallest norm.

**Example 1.** Let's find the least squares solution of AX = Y where

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & -1 & 0 \\ 1 & 1 & 2 \end{bmatrix} \quad and \quad Y = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

The first step is to find the orthogonal projection of Y on the column space of A. The matrix A has rank 2 and the first two columns  $A_1, A_2$  are a basis for the column space of A. Since these columns are not orthogonal, we apply the Gram-Schmidt process to to them to get the orthogonal basis

$$A_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad A_2 - \frac{\langle A_2, A_1 \rangle}{\langle A_1, A_1 \rangle} A_1 = \frac{2}{3} \begin{bmatrix} 1\\-2\\1 \end{bmatrix}.$$

Multiplying the second vector by 3/2, we get the orthogonal basis

$$C_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad C_2 = \begin{bmatrix} 1\\-2\\1 \end{bmatrix}$$

for the column space of A. The orthogonal projection of Y on the column space of A is then

$$B = \frac{\langle Y, C_1 \rangle}{\langle C_1, C_1 \rangle} C_1 + \frac{\langle Y, C_2 \rangle}{\langle C_2, C_2 \rangle} C_2 = \frac{1}{3}C_1 + \frac{1}{6}C_2 = \frac{1}{2}\begin{bmatrix} 1\\0\\1 \end{bmatrix}$$

The second step is to find a solution of AX = B. In this case

$$X = \begin{bmatrix} 0\\0\\1/4 \end{bmatrix}$$

is a least squares solution.

The third step is to find the orthogonal projection of this vector X on the column space of

$$A^t = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 2 & 0 & 2 \end{bmatrix}.$$

Here, the first two columns  $D_1, D_2$  are already an orthogonal basis for the column space of  $A^t$  and so the orthogonal projection of X on the column space of  $A^t$  is

$$Z = \frac{\langle X, D_1 \rangle}{\langle D_1, D_1 \rangle} D_1 + \frac{\langle X, D_2 \rangle}{\langle D_2, D_2 \rangle} D_2 = \frac{1}{12} D_1 = \frac{1}{12} \begin{bmatrix} 1\\1\\2 \end{bmatrix}.$$

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Note that  $||Z|| = \frac{\sqrt{6}}{12} < \frac{1}{4} = ||X||.$ 

**Problem 1.** Prove that  $A^+ = \frac{1}{12} \begin{bmatrix} 1 & 6 & 1 \\ 1 & -6 & 1 \\ 2 & 0 & 2 \end{bmatrix}$ .

**Example 2.** Find the line of best fit for the data points (1,1), (2,0), (3,4).

The required line y = a + bx has the property that  $X = [a, b]^t$  is the least squares solution of the system

$$\begin{bmatrix} 1 & 1 \\ 1 & 4 \\ 1 & 9 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}$$

If  $A_1, A_2$  are the columns of the coefficient matrix A then

$$A_{1} = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad A_{2} - \frac{\langle A_{2}, A_{1} \rangle}{\langle A_{1}, A_{1} \rangle} A_{1} = \begin{bmatrix} 1\\4\\9 \end{bmatrix} - \frac{14}{3} \begin{bmatrix} 1\\1\\1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} -11\\-2\\13 \end{bmatrix}$$

are an orthogonal basis for the column space of A. Multiplying the second of these vectors by 3, we get the orthogonal basis

$$C_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad C_2 = \begin{bmatrix} -11\\-2\\13 \end{bmatrix}.$$

The orthogonal projection of  $Y = [1, 0, 4]^t$  on the column space of A is

$$B = \frac{\langle Y, C_1 \rangle}{\langle C_1, C_1 \rangle} C_1 + \frac{\langle Y, C_2 \rangle}{\langle C_2, C_2 \rangle} C_2 = \frac{5}{3} \begin{bmatrix} 1\\1\\1 \end{bmatrix} + \frac{41}{294} \begin{bmatrix} -11\\-2\\13 \end{bmatrix} = \frac{1}{98} \begin{bmatrix} 13\\136\\341 \end{bmatrix}.$$
  
Solving  $\begin{bmatrix} 1 & 1\\1 & 4\\1 & 9 \end{bmatrix} \begin{bmatrix} a\\b \end{bmatrix} = \frac{1}{98} \begin{bmatrix} 13\\136\\341 \end{bmatrix}$ , we get  $a = \frac{-14}{49}, b = \frac{41}{98}$ .