McGill University Math 247B: Linear Algebra Solution Sheet for Assignment 4

- 1. (a) Let a, b, c be scalars with $a \sin(x) + b \sin(2x) + c \sin(3x) = 0$ for all $x \in \mathbb{R}$. Setting $x = \pi/2$, we get a c = 0. Differentiating both sides of the above dependence relation, we get $a \cos(x) + 2b \cos(2x) + 2c \cos(3x) = 0$ for all x. Setting $x = 0, \pi/2$, we get a + 2b + 3c = 0, -2b = 0. Hence a, b, c satisfy a - c = 0 = 0, b = 0, a + 3c = 0 which implies that a = b = c = 0 and hence that $\sin(x), \sin(2x), \sin(3x)$ are linearly independent.
 - (b) The given functions are linearly dependent since the four given functions are in $\text{Span}(1, x, x^2)$, a subspace spanned by three functions.
 - (c) The given functions are linearly dependent since $\sin^2(x) \cos^2(x) + \cos(2x) = 0$ for all x.

2. (a) We have
$$a \begin{bmatrix} 1 & -5 \\ -4 & 2 \end{bmatrix} + b \begin{bmatrix} 1 & 1 \\ -1 & 5 \end{bmatrix} + c \begin{bmatrix} 2 & -4 \\ -5 & 7 \end{bmatrix} + d \begin{bmatrix} 1 & -7 \\ -5 & 1 \end{bmatrix} = 0$$
 iff
 $a + b + 2c + d = 0, -5a + b - 4c - 7d = 0, -4a - b - 5c - 5d = 0, 2a + 5b + 7c + d = 0$

which is equivalent to a + b + 2c + d = 0, 6b + 6c - d = 0. Since there are solutions with c = 1, d = 0 and c = 0, d = 1 we see the first two of the given matrices span V and hence are a basis for V since they are also linearly independent. Since the matrices

$$\begin{bmatrix} 1 & -5 \\ -4 & 2 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ -1 & 5 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

span $\mathbb{R}^{2 \times 2}$ they must be linearly independent and hence a basis for V.

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(b) Since $X = a \begin{bmatrix} 1 & -5 \\ -4 & 2 \end{bmatrix} + b \begin{bmatrix} 1 & 1 \\ -1 & 5 \end{bmatrix} = \begin{bmatrix} a+b & -5a+b \\ -4a-b & 2a+5b \end{bmatrix}$ we see that a matrix X in V has trace zero iff 3a+6b=0 iff a = -2b iff $X = b \begin{bmatrix} -1 & 11 \\ 7 & 1 \end{bmatrix}$. Hence $\begin{bmatrix} -1 & 11 \\ 7 & 1 \end{bmatrix}$ is the required basis.

3. (a) If
$$A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$$
 we have $T(aX + bY) = A(aX + bY) - (aX + bY)A = aAX = bAY - aXA - bYA = a(AX - XA) + b(AY - YA) = aT(X) + bT(Y)$. Hence T is linear. If $X = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ we have

$$T(X) = \begin{bmatrix} -4b + 2c & -2a - 2b + 2d \\ 4a + 2c - 4d & 4b - 2c \end{bmatrix} = a\begin{bmatrix} 0 & -2 \\ 4 & 0 \end{bmatrix} + b\begin{bmatrix} -4 & -2 \\ 0 & 4 \end{bmatrix} + c\begin{bmatrix} 2 & 0 \\ 2 & -2 \end{bmatrix} + d\begin{bmatrix} 0 & 2 \\ -4 & 0 \end{bmatrix}.$$
Hence $T(X) = 0$ iff $-4b + 2c = -2a - 2b + 2d = 4a + 2c - 4d = 4b - 2c = 0$ iff $a + b - d = 2b - c = 0$ iff $a = -c/2 + d, \ b = c/2$. Hence $\begin{bmatrix} -1 & 1 \\ 2 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is a basis for Ker(T). We also have

$$\operatorname{Im}(\mathbf{T}) = \operatorname{Span}\begin{pmatrix} 0 & -2\\ 4 & 0 \end{bmatrix}, \begin{bmatrix} -4 & -2\\ 0 & 4 \end{bmatrix}, \begin{bmatrix} 2 & 0\\ 2 & -2 \end{bmatrix}, \begin{bmatrix} 0 & 2\\ -4 & 0 \end{bmatrix}) = \operatorname{Span}\begin{pmatrix} 0 & -2\\ 4 & 0 \end{bmatrix}, \begin{bmatrix} -4 & -2\\ 0 & 4 \end{bmatrix})$$

which shows that $\begin{bmatrix} 0 & -2 \\ 4 & 0 \end{bmatrix}$, $\begin{bmatrix} -4 & -2 \\ 0 & 4 \end{bmatrix}$ is a basis for Im(T) since these two matrices are also linearly independent. (b) Since $T(e_1) = -2e_2 + 4e_3$, $T(e_2) = -4e_1 - 2e_2 + 4e_4$, $T(e_3) = 2e_1 + 2e_3 - 2e_4$, $T(e_4) = 2e_2 - 4e_3$, we have

$$A = [T]_e = [T]_{e,e} = \begin{bmatrix} 0 & -4 & 2 & 0 \\ -2 & -2 & 0 & 2 \\ 4 & 0 & 2 & -4 \\ 0 & 4 & -2 & 0 \end{bmatrix}$$

Since $T(f_1) = 0$, $T(f_2) = -2e_1 - 2e_2 + 2e_3 + 2e_4$, $T(f_3) = -2e_1 - 4e_2 + 6e_3 + 2e_4$, $T(f_4) = 2e_1 + 2e_2 - 2e_3 - 2e_4$) we have

$$C = [T]_{f,e} = \begin{bmatrix} 0 & -2 & -2 & 2\\ 0 & -2 & -4 & 2\\ 0 & 2 & 6 & -2\\ 0 & 2 & 2 & -2 \end{bmatrix}$$

Since $f_1 = e_1 + e_4$, $f_2 = e_2 + e_3$, $f_3 = e_1 + e_2 + e_3$, $f_4 = e_3 + e_4$ we have

$$P = [I]_{f,e} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

Since $e_1 = -f_2 + f_3$, $e_2 = f_1 + 2f_2 - f_3 - f_4$, $e_3 = -f_1 - f_2 + f_3 + f_4$, $e_4 = f_1 + f_2 - f_3$ we have

$$Q = [I]_{e,f} = \begin{bmatrix} 0 & 1 & -1 & 1 \\ -1 & 2 & -1 & 1 \\ 1 & -1 & 1 & -1 \\ 0 & -1 & 1 & 0 \end{bmatrix}.$$

Since $T(e_1) = -6f_1 - 8f_2 + 6f_3 + 6f_4$, $T(e_2) = 2f_1 + 4f_2 - 6f_3 + 2f_4$, $T(e_3) = -4f_1 - 6f_2 + 6f_3 + 2f_4$ we have

$$B = [T]_{e,f} = \begin{bmatrix} -6 & 2 & -4 & 6\\ -8 & 4 & -6 & 8\\ 6 & -6 & 6 & -6\\ 6 & 2 & 2 & -6 \end{bmatrix}.$$

Since $T(f_1) = 0$, $T(f_2) = -2f_1 - 2f_2 + 4f_4$, $T(f_3) = -8f_1 - 10f_2 + 6f_3 + 10f_4$, $T(f_4) = 2f_1 + 2f_2 - 4f_4$ we have

$$D = [T]_f = [T]_{f,f} = \begin{bmatrix} 0 & -2 & -8 & 2\\ 0 & -2 & -10 & 2\\ 0 & 0 & 6 & 0\\ 0 & 4 & 10 & -4 \end{bmatrix}$$

We have $A = [T]_e = [IT]_e = [I]_{f,e}[T]_{e,f} = PB$, $A = [T]_e = [TI]_e = [T]_{f,e}[I]_{e,f} = CQ$, $A = [T]_e = [ITI]_e = [I]_{f,e}[T]_{f,e}[T]_f[I]_{e,f} = PDQ$, $B = [T]_{e,f} = [T]_f[I]_{e,f} = DQ$, $C = [T]_{f,e} = [I]_{f,e}[T]_f = PD$, $I = [I]_e = [I]_{f,e}[I]_{e,f} = PQ$, $I = [I]_f = [I]_{f,e}[I]_{f,e} = QP$.

- 4. (a) V is a subspace of $C^{\infty}(\mathbb{R})$ since $V = \text{Ker}(\mathbb{D}^4)$. A basis for V is $1, x, x^2, x^3$ since they are linearly independent an span V.
 - (b) T is linear since T(af + bg)(x) = (af + bg)(x) + (af + bg)(1 x) = af(x) + bg(x) + af(1 x) + bg(1 x) = a(f(x) + f(1 x)) + b(g(x) + g(1 x)) = aT(f)(x) + bT(g)(x) = (aT(f) + bT(g)(x). Since $T^2(f)(x) = T(T(f))(x) = T(f)(x) + T(f)(1 x) = f(x) + f(1 x) + f(1 (x) + f(1 (1 x))) = 2(f(x) + f(1 x)) = 2T(f)(x)$ we see that $T^2 = 2T$. If $f \in V$ we have $f(x) = a + bx + cx^2 + dx^3$ so that $f(1 x) = a + b(1 x) + c(1 x)^2 + d(1 x)^3 = a + b + c + d + (-b 2c 3d)x + (c + 3d)x^2 dx^3$. This implies that $T(f) \in V$ and hence that $T(V) \subseteq V$.
 - (c) If $f_1(x) = 1$, $f_2(x) = x$, $f_3(x) = x_2$, $f_4(x) = x^3$ then $f = (f_1, f_2, f_3, f_4)$ is a basis for V. Since $S(f_1) = 2f_1$, $S(f_2) = f_1$, $S(f_3) = f_1 2f_2 + 2f_3$, $S(f_4) = f_1 3f_2 + 3f_2$ we have

$$A = [S]_f = \begin{bmatrix} 2 & 1 & 1 & 1 \\ 0 & 0 & -2 & -3 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

We have $A^2 = [S]_f^2 = [S^2]_f = [2S]_f = 2[S]_f = 2A$ since $T^2 = 2T$ implies $S^2 = 2S$.