## McGill University Solution Sheet for MATH 236 Assignment 3

1. (a) Since  $(D-a)(x^k e^{ax}) = D(x^k e^{ax}) - ax^k e^{ax} = kx^{k-1}e^{ax} + ax^k e^{ax} - ax^k e^{ax} = kx^{k-1}e^{ax}$  we have, by induction,  $(D-a)^k(x^k e^{ax}) = k!e^{ax}$  which implies  $(D-a)^{k+1}(e^{ax}) = 0$  and hence that  $(D-a)^n(x^k e^{ax}) = 0$  for n > k. Hence  $U = \text{Span}(e^{ax}, \dots, x^{k-1}e^{ax}) \subseteq \text{Ker}((D-a)^n)$ . Since dim $(\text{Ker}((D-a)^n)) = n$  we have equality if dim(U) = n. To prove the latter we have to show that  $(e^{ax}, \ldots, x^{k-1}e^{ax})$  is linearly independent. If  $a_0, \ldots, a_{n-1}$  are scalars with  $a_0e^{ax} + a_1xe^{ax} + \dots + a_{n-1}x^{n-1}e^{ax} = 0$  for all x we have  $a_0 + a_1x + \dots + a_{n-1}x^{n-1} = 0$  for all x. Differentiating n times and setting x = 0 in the resulting equations, we get  $a_i = 0$  for all i.

Second Solution. If P is the operator on V defined by  $P(f)(x) = e^{ax} f(x)$  we have (D-a)P = PD so that D-a = PD $P^{-1}DP$ . Hence  $(D-a)^n = PD^nP^{-1}$ . It follows that  $f \in \operatorname{Ker}((D-a)^n)$  if and only if  $P^{-1}(f) \in \operatorname{Ker}(D^n)$ . Using the fact that  $\operatorname{Ker}(D^n) = \operatorname{Span}(1, x, \dots, x^{n-1})$ , we get  $f \in \operatorname{Ker}((D-a)^n)$  if and only if  $e^{-ax}f(x) \in \operatorname{Span}(1, x, \dots, x^{n-1})$ .

- (b) We have  $f^{(iv)}(x) 2f''(x) + f(x) = 0$  if and only if  $f \in \text{Ker}(D^4 2D^2 + 1) = \text{Ker}((D-1)^2(D+1)^2 \supseteq \text{Ker}((D-a)^2) + 1)$  $\operatorname{Ker}((D+1)^2)$ . Since  $\dim(W) = 4$  we have to show  $\dim(\operatorname{Ker}((D-a)^2) + \operatorname{Ker}((D+1)^2)) = 4$  in order to show equality. Since  $\operatorname{Ker}((D-a)^2) + \operatorname{Ker}((D+1)^2) = \operatorname{Span}(e^x, xe^x) + \operatorname{Span}(e^{-x}, xe^{-x}) = \operatorname{Span}(e^x, xe^x, e^{-x}, xe^{-x})$  we have to show that  $(e^x, xe^x, e^{-x}, xe^{-x})$  is linearly independent. But  $ae^x + bxe^x + ce^{-x} + dxe^{-x} = 0$  for all x yields on differentiation 3 times the identities  $(a+b)e^x + bxe^x + (-c+d)e^{-x} - dxe^{-x} = 0$ ,  $(a+2b)e^x + bxe^x + (c-2d)e^{-x} + dxe^{-x} = 0$ ,  $(a+3b)e^x + bxe^x + (-c+3d)e^{-x} - dxe^{-x} = 0$  which gives on setting x = 0 the equations a+c = 0, a+b-c+d = 00, a + 2b + c - 2d = 0, a + 3b - c + 3d = 0 which implies a = b = c = d = 0 by Gaussian elimination. This also shows that  $\text{Ker}((D-1)^2) \cap \text{Ker}((D+1)^2) = \{0\}$  and hence that  $W = \text{Ker}((D-1)^2) \oplus \text{Ker}((D+1)^2)$ .
- (c) From (b) we have  $f(x) = ae^x + cxe^x + ce^{-x} + dxe^{-x}$ . Hence f(0) = a + c = 1, f'(0) = a + b c + d = 2, f''(0) = a + 2b + c - 2d = 3, f'''(0) = a + 3b - c + 3d = 4 from which a = b = 1, c = d = 0 and hence  $f(x) = e^x + xe^x.$
- 2. (a) We have  $A \in \text{Ker}(T) \iff 2A + A^t = 0 \iff A^t = -2A \iff A = 0$  so that  $\text{Ker}(T) = \{0\}$  with basis the empty list. Since T is 1 1 is onto as  $\dim(V) = 4$  with basis  $\begin{pmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \end{pmatrix}$  which is therefore also a basis for Im(T).
  - (b) We have  $T^2(A) = T(T(A)) = 4A + 2T(A)^t = 4A + 2(2A + A^t)^t = 5A + 4A^t$  so that  $T^2(A) 4T(A) + 3A = 4A + 2(2A + A^t)^t = 5A + 4A^t$  $5A + 4A^t - 8A - 4A^t + 3A = 0$  which gives  $T^2 - 4T + 3 = 0$ . Hence, if  $\lambda$  is an eigenvalue of T, we must have  $\lambda^2 - 4\lambda + 3 = 0$  from which  $\lambda = 1, 3$ . Since  $T(A) = A \iff A^t = -A$  we see that  $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$  is an eigenvector of T with eigenvalue 1. Since  $T(A) = 3A \iff A^t = A$  we see that  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  is an eigenvector of T with eigenvalue 3. Hence 1.3 are the eigenvalues of T.
  - (c) We have  $V = \operatorname{Ker}(T^2 4T + 3) = \operatorname{Ker}((T 1)(T 3)) = \operatorname{Ker}(T 1) \oplus \operatorname{Ker}(T 3)$  and  $\operatorname{Ker}(T 1) = \operatorname{Span}\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ ,  $\operatorname{Ker}(T 3) = \operatorname{Span}\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ ) which yields the basis  $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ ) of V consisting of simulations of V. consisting of eigenvectors of

3. (a) Let  $F_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ ,  $F_2 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 2 \end{bmatrix}$ ,  $F_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}$ ,  $F_4 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}$  and let  $E_1, E_2, E_3, E_4$  be the standard basis of  $\mathbb{R}^{4 \times 1}$ . Then  $F_1 = E_1 + E_2 + E_3 + E_4$ ,  $F_2 = E_1 + 2E_2 + E_3 + 2E_4$ ,  $F_3 = E_1 + E_2 + 2E_3 + 2E_4$ ,  $F_4 = E_1 + 2E_2 + 3E_3 + 3E_4$ . Solving for  $E_1, E_2, E_3, E_4, \text{ we get } E_1 = F_1 + F_3 - F_4, E_2 = F_1 - 2F_3 + F_4, E_3 = F_1 - F_2 - F_3 + F_4, E_4 = -2F_1 + F_2 + 2F_3 - F_4.$ Hence the columns of A are  $AE_1 = F_1 - 4F_3 - 2F_4$ ,  $AE_2 = F_1 - 4F_3 + 2F_4$ ,  $AE_3 = F_1 - F_2 - 2F_3 + 2F_4$ , Hence the columns of A are  $AL_1 = I_1 - I_3$   $L_4, III_2$   $I_1$   $AE_4 = -2F_1 + F_2 + 4F_3 - 2F_4$  which gives  $A = \begin{bmatrix} 1 & -1 & 0 & 1 \\ -1 & 1 & 1 & 0 \\ -1 & -1 & 2 & 1 \\ -1 & -1 & 1 & 2 \end{bmatrix}$ . If B is a matrix with  $AF_i = BF_i$  for all i we

would have  $AE_i = BE_i$  for all *i* and hence A =

(b) Since  $A^2 - 3A + 2I = (A - I)(A - 2I) = 0$  we see that the eigenvalues  $\lambda$  of A are roots of  $\lambda^2 - 3\lambda + 2 = 0$  and hence must be 1 or 2. Since  $F_1, F_3$  are eigenvectors of A with eigenvalues 1, 2 respectively we see that the eigenvalues of A are 1, 2.

4. (a) Let  $F_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ ,  $F_2 = \begin{bmatrix} 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$  and complete  $F_1, F_2$  to a basis  $F_1, F_2, F_3, F_4$  of  $\mathbb{R}^{4 \times 1}$  where  $F_3 = E_3, F_4 = E_4$ . Then

 $E_1 = \frac{3}{5}F_1 + \frac{2}{5}F_2 + F_3 + 2F_4, E_2 = \frac{4}{5}F_1 - \frac{1}{5}F_2 - 2F_3 - 3F_4, E_3 = F_3, E_4 = F_4.$  Let T be the linear mapping of  $\mathbb{R}^{4\times 1}$  defined by  $T(y_1F_1 + y_2F_2 + y_3F_3 + y_4F_4) = y_3F_1 + y_4F_2.$  Then  $\operatorname{Ker}(T) = \operatorname{Im}(T) = \operatorname{Span}(F_1, F_2).$  The required matrix A is the matrix of T with respect to the usual basis of  $\mathbb{R}^{4\times 1}$ . The columns of A are  $AE_1 = F_1 + 2F_2$ ,

 $AE_2 = -2F_1 - 3F_2, AE_3 = F_1, AE_4 = F_2 \text{ so that } A = \begin{bmatrix} 9 & -14 & 1 & 4 \\ 8 & -13 & 2 & 3 \\ 7 & -12 & 3 & 2 \\ 6 & -11 & 4 & 1 \end{bmatrix}.$  Note that the matrix A is not unique.

Second Solution: If  $[x_1, x_2, x_3, x_4]$  is a row of A we must have  $x_1 + 2x_2 + 3x_3 + 4x_4 = 0$ ,  $4x_1 + 3x_2 + 2x_3 + x_4 = 0$ which, by Gaussian elimination, has the general solution  $x_1 = a + 2b, x_2 = -2a - 3b, x_3 = a, x_4 = b$ . Hence  $A \begin{bmatrix} a_1 + 2b_1 & -2a_1 - 3b_1 & a_1 & b_1 \\ a_2 + 2b_2 & -2a_2 - 3b_2 & a_2 & b_1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_1 \end{bmatrix} \begin{bmatrix} a_1 \\ b_2 \end{bmatrix} \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} \begin{bmatrix} a_1 \\ b_2 \end{bmatrix}$ 

has the form 
$$A = \begin{bmatrix} a_2 + 2b_2 & -2a_2 - 3b_2 & a_2 & b_2 \\ a_3 + 2b_3 & -2a_3 - 3b_3 & a_3 & b_3 \\ a_4 + 2b_4 & -2a_4 - 3b_4 & a_4 & b_4 \end{bmatrix}$$
. Choosing  $\begin{bmatrix} a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$ ,  $\begin{bmatrix} b_2 \\ b_3 \\ b_4 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$ , we obtain the required matrix

matrix.

(b) Since  $A^2 = 0$  and the null space of A is  $\text{Span}(F_1, F_2)$  we see that 0 is the only eigenvalue of A. Since the only eigenvectors of A lie in the null space of A, a two dimensional subspace of  $\mathbb{R}^{4\times 1}$ , we see that  $\mathbb{R}^{4\times 1}$  does not have a basis consisting of eigenvectors of A.

5. (a) Since 
$$A^2 = 1$$
 the possible eigenvalues of  $A$  are 1, -1. Now Null(A - I) = Span( $\begin{bmatrix} 1\\1\\-1\\0\\-1\end{bmatrix}$ ,  $\begin{bmatrix} 1\\1\\0\\-1\end{bmatrix}$ ) and Null(A + I) =  $\begin{bmatrix} 1\\-1\\0\\-1\end{bmatrix}$ ) and Null(A + I) = \begin{bmatrix} 1\\-1\\0\\-1\end{bmatrix})

 $\operatorname{Span}\left(\begin{bmatrix}1\\0\\-1\\0\end{bmatrix},\begin{bmatrix}0\\1\\0\\-1\end{bmatrix}\right)$  so that 1, -1 are the eigenvalues of A and a basis for each eigenspace is given above. (b) The matrix  $P = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \end{bmatrix}$  satisfies AP = PD with  $D = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$ . The matrix P is invertible since its columns are linearly independent. This follows from the fact that  $\mathbb{R}^{4\times 1} = \text{Null}(A^2 - 1) = \mathbb{R}^{4\times 1}$ 

 $\operatorname{Null}((A - I)(A + I)) = \operatorname{Null}(A - I) \oplus \operatorname{Null}(A + I)$ . Hence  $P^{-1}AP = D$ .