

Lecture¹ 9

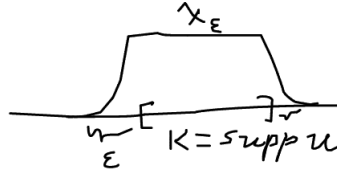
Theorem 1. Let $u \in \mathcal{E}^m(\Omega)$ be of order m , $\phi \in C^m(\Omega)$ satisfying

$$\partial^\alpha \phi = 0 \quad \text{on} \quad \text{supp } u, \quad \forall |\alpha| \leq m \implies u(\phi) = 0.$$

Proof. Denote $\chi_\epsilon \in \mathcal{D}(\Omega)$ cut off function such

$$\chi_\epsilon \begin{cases} 1 & \text{on nbhd } K \\ 0 & \text{outside } K + B_\epsilon. \end{cases}$$

We will use a known property that, $|\partial^\alpha \chi_\epsilon| \leq C\epsilon^{-|\alpha|} \quad \forall |\alpha| \leq m$.



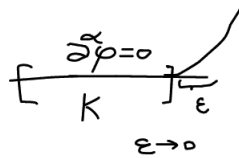
Now by boundedness of distribution u and $u(\phi) = u(\chi_\epsilon \phi)$ in K ,

$$|u(\phi)| \leq C \sum_{|\alpha| \leq m} \sup |\partial^\alpha (\chi_\epsilon \phi)| \quad (1)$$

$$\leq C' \sum_{|\alpha| \leq m} \|\partial^\alpha \phi\|_{C(K+B_\epsilon)} \|\chi_\epsilon\|_{C^{m-|\alpha|}} \quad (2)$$

$$\leq C'' \sum_{|\alpha| \leq m} \epsilon^{|\alpha|-m} \|\partial^\alpha \phi\|_{C(K+B_\epsilon)}. \quad (3)$$

It is necessary to check for the nontrivial cases. For $|\alpha| = m$



$$\partial^\alpha \phi(y) = \partial^\alpha \phi(x) + o(|y-x|) = \partial^\alpha \phi(x) + o(\epsilon).$$

For case $|\alpha| < m$, we make use of the Taylor expansion. Let $\partial^\alpha \phi = \psi$,

$$\psi(y) = \psi(x) + \sum_{|\alpha| \leq m-|\alpha|} (y-x)^\beta \partial^\beta \psi(x) / \alpha! + R$$

¹Notes by Ibrahim Al Balushi

R denoting the remainder terms. Note that since $x \in \text{supp } \phi$, then all but the remainder term vanishes in the expansion above.

$$|\psi(y)| = |R| \leq C \sum_{|\beta|=m-|\alpha|} |\partial^\beta \alpha \phi(\xi)| \epsilon^{m-|\alpha|} \quad \epsilon \approx |x - y|.$$

□

Corollary 1. *Let $u \in \mathcal{D}'(\Omega)$, with $\text{supp } u = \{y\}$ for some $y \in \Omega$. Then,*

$$u(\phi) = \sum_{|\alpha| \leq m} a_\alpha \partial^\alpha \phi(y)$$

for some m and $\{a_\alpha\}$. That is, $u = \sum a_\alpha \partial^\alpha \delta_y$ a finite sum.

Proof.

$$\phi(x) = \sum_{|\alpha| \leq m} \partial^\alpha \phi(y) \underbrace{(x - y)^\alpha / \alpha!}_{\xi_\alpha(x)} + \psi(x)$$

then,

$$u(\phi) = \sum_{|\alpha| \leq m} u(\xi_\alpha) \partial^\alpha \phi(y) + u(\psi).$$

Since $\partial^\alpha \psi(y) = 0$ for $|\alpha| \leq m$ then the remainder term is zero.

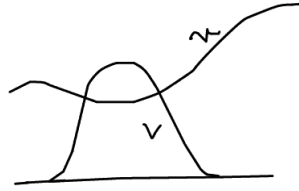
□

Convolutions

The convolution is defined on regular space function as follows:

$$(u * v)(x) = \int u(y)v(x - y)dy = \int u(x - y)v(y)dy = (v * u)(x)$$

There are some conditions which must be imposed on u and v so that the integral above exists. For example this would hold for $v \in L_c^1(\mathbb{R}^n)$ and $u \in L_{loc}^\infty(\mathbb{R}^n)$. Another option is when $u, v \in L^1(\mathbb{R}^n)$



which holds since

$$\|u * v\|_{L^1} \leq \|u\|_{L^1} \|v\|_{L^1}.$$

Moreover, the convolution possesses the following property:

$$\partial^\alpha (u * v) = (\partial^\alpha u) * v,$$

if $|\alpha| \leq m$, $u \in C^m$ and $v \in L_c^1$. The key is to notice that this product rule exists provided *only one* of the functions satisfies regularity conditions in the classical sense.

In order to define the convolution in the distributional sense, we define the following.

Definition 1. For $v \in L_c^1(\mathbb{R}^n)$, define $C_v : \mathcal{D}(\mathbb{R}^n) \rightarrow \mathcal{D}'(\mathbb{R}^n)$ by

$$C_v u : u \mapsto v * u$$

The support of $u * v \subset \text{supp } u + \text{supp } v$.

Theorem 2. The operator $C_v : C^m(\mathbb{R}^n) \rightarrow C^m(\mathbb{R}^n)$, for $0 \leq m \leq \infty$ is continuous.

Proof. $P_k(\phi) = \|\phi\|_{C^l(K)}$ for K compact, l nonnegative integer,

$$\|u * v\|_{C^l(K)} \leq \|v\|_{L^1} \|u\|_{C^l(K - \text{supp } v)}$$

$$\int u(x - y)v(y) dy, \quad x - y \in K - \text{supp } v$$

so let $K' = K - \text{supp } v$. □

Corollary 2. $C_v : \mathcal{D}(\mathbb{R}^n) \rightarrow \mathbb{R}^n$ is continuous.

Proof. Suffices to show for every K compact $C_v : \mathcal{D}_K \rightarrow \mathbb{R}^n$ is continuous. By using

$$C_v \mathcal{D}_K = C_v \mathcal{D}(K) \subset \mathcal{D}(K + \text{supp } u)$$

we have it. □

We now define the convolutions in the sense of distributions. Consider the following:

$$\begin{aligned} \langle C_v u, \phi \rangle &= \int (u * v)\phi = \int \int u(z)v(x - z) dz \cdot \phi(x) dx \\ &= \int u(z)\tilde{v}(z - x)\phi(x) \\ \text{Define reflection } \tilde{v}(y) &= v(-y) \\ &= \int (\tilde{v} * \phi)u \end{aligned}$$

Formally,

Definition 2. Let $v \in L_c^1(\mathbb{R}^n)$. Define for $u \in \mathcal{D}'(\mathbb{R}^n)$

$$\langle v * u, \phi \rangle = \langle C_v u, \phi \rangle := \langle u, C_{\tilde{v}} \phi \rangle = \langle u, \tilde{v} * \phi \rangle$$

We have, $C_u : v \mapsto u * v$, for $u \in \mathcal{D}'(\mathbb{R}^n)$.