From Representation Theory to Geometric Discretizations

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Representation Theory and Geometry

A Brief History: Structure and Discretization

• Whitney (1957), Geometric Integration Theory

$$C: \Omega^{p}(M) \to C^{p}(K, \mathbb{Z}), \quad C(\omega) := \sigma \mapsto \langle \omega, \sigma \rangle$$
$$\mathcal{W}: C^{0}(K, \mathbb{Z}) \to \Omega^{0}(M), \quad \mathcal{W}(x_{i}) = \lambda_{i}$$

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• Harlow and Welch, MAC grid (1965), K. Yee, Yee's lattice (1966)

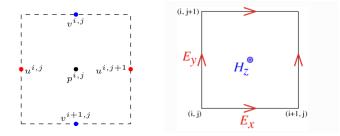


Figure: MAC grid (left) and Yee's lattice (right).

Damien Tageddine

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• Arnold et al. (2000's) Finite Element Exterior Calculus

$$\begin{array}{ccc} W_1 & \stackrel{d}{\longrightarrow} & W_2 \\ \downarrow^{\pi} & & \downarrow^{\pi'} \\ W_1^h & \stackrel{d}{\longrightarrow} & W_2^h \end{array}$$

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• Hirani (2003), Desbrun, Hirani, Leok, Marsden et al. (2005) *Discrete Exterior Calculus*

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Question: Identify a unifying picture ?

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- An algebra of "functions" : A
- A differential map d: Leibniz rule, self-adjoint, exterior algebra ...
- 2) This differential structure is an approximation of the continuous one.

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Image: A matrix

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Let A be an associative k-algebra, then one can define the multiplication map

$$\mu: A \otimes A \rightarrow A, \quad \mu(a \otimes b) = ab$$

Then one can define the universal graded differential algebra as follow:

$$\Omega^{1}(A) = \ker(\mu), \quad da := 1 \otimes a - a \otimes 1,$$
$$\Omega^{k}(A) = \{a_{1}da_{2}da_{3}\cdots da_{k}, a_{i} \in A\}, \quad \Omega^{*}(A) = \bigoplus_{k} \Omega^{k}(A).$$

If in addition, we require that A is equipped with an involution *

$$(da)^* = d(a^*).$$

$$\|a^*a\| = \|a\|^2 \quad \forall a \in A.$$

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Theorem (Gelfand-Naimark-Seagal)

Any C^* -algebra A can be identified as a closed *-subalgebra of the algebra of bounded operator B(H) on a separable Hilbert space H.

One then needs to introduce a derivation map d on B(H) such that:

$$(da)^* = d(a^*)$$
 (self-adjoint),
 $d(ab) = d(a)b + ad(b)$ (Leibniz rule).

For that purpose, we define a self-adjoint operator $D: H \to H$ and extend the representation $\pi: A \to B(H)$ to a representation of $\Omega(A)$ in B(H): One then needs to introduce a derivation map d on B(H) such that:

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$$\pi(da) = [D, \pi(a)]$$

The data (A, H, D) is called a *spectral triple*, and D a *Dirac operator*. The definition of a spectral triple has been introduced by A. Connes *Noncommutative Geometry* (1994).

1) Describe a differential calculus using the following ingredients

- An algebra of "functions" : A
- A differential map d: Leibniz rule, self-adjoint, exterior algebra ...
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Theorem (Whitney)

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Lemma

The topological space M is homeomorphic to the subspace of all the maximal points of the inverse limit of the system (K_i, ϕ_{ij}) .

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C*-Algebra and Space

We recall the interplay between C^* -algebra and topological spaces:

Theorem (Gelfand)

Let A be a commutative unital C^* -algebra, then there exists a compact Hausdorff topological space X such that:

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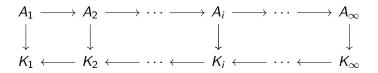
Claim

One can associate to every C^* -algebra A a topological space X, namely its spectrum Spec(A).

We have the following identification:

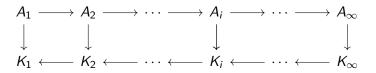
$$Spec(A) \xrightarrow{\simeq} K$$

We can draw the following commuting diagram:



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Theorem A

The limit C^{*}-algebra A_{∞} is isometrically *-isomorphic to C^{*}-algebra of the complex valued continuous sections $\Gamma(M, A_{\infty})$ over the manifold M. The center $Z(A_{\infty})$ is isomorphic to $C(M, \mathbb{C})$.

We extend this construction to the representation H_i of the algebra A_i . We have the following sequence:

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Theorem B

The Hilbert space $L^2(M)$ of square integrable functions over the manifold M is a subspace of H_{∞} :

$$H_{\infty}=L^2(M)\oplus H.$$

We have introduced the following:

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• A sequence of C^* -algebras A_i with limit C(M)

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- A sequence of representations H_i with limit $L^2(M)$

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If (M,g) is a compact spin manifold then data $(C^{\infty}(M), L^{2}(S), \partial_{M})$ is enough to recover the geometric structure.

We define the following algebra A and Dirac operator D:

$$A = M_{2m}(\mathbb{C}), \quad H = \mathbb{C}^{2m}, \quad D = \frac{i}{h} \left(egin{array}{c} 0 & D^- \\ D^+ & 0 \end{array}
ight)$$

with $(D^+)^* = -D^-$ and where D^- is given by

$$D^{-} = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & \ddots & 0 \\ \vdots & & & \ddots & 1 \\ 0 & \cdots & \cdots & 0 \end{pmatrix}$$

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Proposition 1

For every element $da \in \Omega^1_D(A)$, we have

$$\sigma(da) = \left\{ \pm \frac{i}{h} (\lambda_{i+1} - \lambda_i) : 0 \le i \le d - 1 \right\}$$

Moreover, we have the commutativity relation

$$[da, db] = 0, \quad \forall a, b \in A.$$

Case
$$n = 2$$

Let $a = (a_1, a_2) \in M_2(\mathbb{C})$ and the Dirac operator:

$$D=\frac{i}{h}\left(\begin{array}{cc}0&1\\-1&0\end{array}\right),\quad da=\frac{i}{h}\left(\begin{array}{cc}0&a_2-a_1\\a_1-a_2&0\end{array}\right).$$

If we define the following distance:

$$d(x, y) = \sup_{a \in A} \{ |a(x) - a(y)| : ||[D, a]|| \le 1 \}$$

then one can show that for $X = \{x, y\}$

$$d(x,y)=h.$$

Without prior assumption, we see the emergence of a small parameter h in place of the usual distance Δx .

Let ρ be a positive matrix with positive eigenvalues (μ_k) such that

$$Tr(
ho) = \sum_{k} \mu_{k} = 1$$

Then ρ is called a density matrix.

Proposition 2

Let ρ be a density matrix, then the expectation value is given by

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 da $>_{
ho}=$ Tr(ho da) $=rac{i}{h}\sum_{k}\mu_{k}(a_{k+1}-a_{k})$

for any element $da \in \Omega^1_D(A)$.

General Case and Direct Limits

In the general case of a triangulation K_i , we define D_i as the block matrix

$$D_i = rac{i}{h} \left(egin{array}{cc} 0 & D_i^- \ D_i^+ & 0 \end{array}
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where D_i^- is the adjacency matrix associated to K_i . Then the limit operator D_∞ acts on A_∞ by the commutator:

$$[D_{\infty}, a] = ([D_0, a_0], [D_1, a_1], \cdots, [D_i, a_i], \cdots) \in \prod_{i \in I} M^-_{2m_i}(\mathbb{C}).$$

Proposition 3 (lattice)

i)
$$\sigma_{A_{\infty}}([D_{\infty}, a]) = \overline{\bigcup_i \sigma_{A_i}([D_i, a_i])}$$

ii) $\|[D_{\infty}, a]\| = \|d_c a\|_{\infty}$

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Image: A matrix and a matrix

We have the following results: given a compact spin manifold (M, g),

- associate to each K_i a C^* -algebra A_i with limit C(M),
- define a differential structure $da = [D_i, a]$ on each A_i ,
- for the lattice, (D_i) converges to the usual Dirac operator ∂_M .
- Using the same tools than the continuous case $(C^{\infty}, L^2(M), \partial_M)$!

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Future works:

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Stay tuned !

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