

SEMIPARAMETRIC THEORY FOR THE LINEAR MODEL

For the $p \times 1$ system of estimating equations

$$\sum_{i=1}^n \mathbf{U}_i(\theta) = \mathbf{0}$$

with $\mathbb{E}[\mathbf{U}(\theta_0)] = \mathbf{0}$, we have that

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \text{Normal}_p(\mathbf{0}, \mathbf{V})$$

where

$$\mathbf{V} = \mathcal{J}^{-1} \mathcal{I} \mathcal{J}^{-\top}$$

with

$$\mathcal{I} = \mathbb{E}[\mathbf{U}(\theta_0) \mathbf{U}(\theta_0)^\top] \quad \mathcal{J} = \mathbb{E}[\dot{\mathbf{U}}(\theta_0)]$$

both $(p \times p)$ matrices, and

$$\dot{\mathbf{U}}(\theta_0) = - \left. \frac{\partial \mathbf{U}(\theta)}{\partial \theta^\top} \right|_{\theta=\theta_0}$$

We proceed by computing estimates, $\hat{I}_n$ and $\hat{J}_n$, of the two matrices based on the observed data,

$$\hat{I}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{U}_i(\hat{\theta}_n) \{\mathbf{U}_i(\hat{\theta}_n)\}^\top \quad \hat{J}_n = - \frac{1}{n} \sum_{i=1}^n \dot{\mathbf{U}}_i(\hat{\theta}_n)$$

and then computing

$$\hat{\mathbf{V}} = \hat{J}_n^{-1} \hat{I}_n \hat{J}_n^{-\top}$$

to estimate the asymptotic variance.

In the linear model, suppose that we have parameter $\theta = (\psi^\top, \beta^\top)^\top$, with parameter of interest ψ ($q \times 1$) and nuisance parameter β ($r \times 1$). The estimating function (for a single data point) is

$$\mathbf{U}(\theta) = \mathbf{x}^\top (Y - \mathbf{x}\theta) = \begin{bmatrix} \mathbf{x}_2^\top \\ \mathbf{x}_1^\top \end{bmatrix} (Y - \mathbf{x}_2\psi - \mathbf{x}_1\beta)$$

where $\mathbf{x}_1$ and $\mathbf{x}_2$ are $1 \times r$ and $1 \times q$ row vectors, respectively, with $\mathbf{x} = (\mathbf{x}_2, \mathbf{x}_1)$ is $1 \times p$. We have

$$\dot{\mathbf{U}}(\theta) = \begin{bmatrix} \mathbf{x}_2^\top \mathbf{x}_2 & \mathbf{x}_2^\top \mathbf{x}_1 \\ \mathbf{x}_1^\top \mathbf{x}_2 & \mathbf{x}_1^\top \mathbf{x}_1 \end{bmatrix} = \mathbf{x}^\top \mathbf{x} \equiv \dot{\mathbf{U}}$$

is a $p \times p$ symmetric block matrix that does not depend on θ . We have that

$$\mathcal{I}(\theta_0) = \mathbb{E}[\mathbf{x}^\top (Y - \mathbf{x}\theta)^2 \mathbf{x}] = \mathbb{E}[(Y - \mathbf{x}\theta)^2 \mathbf{x}^\top \mathbf{x}]$$

as $(Y - \mathbf{x}\theta)$ is a scalar quantity, and

$$\mathcal{J} = \mathbb{E}[\mathbf{x}^\top \mathbf{x}].$$

The estimators would be

$$\hat{I}_n = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{x}_i \hat{\theta}_n)^2 \mathbf{x}_i^\top \mathbf{x}_i \quad \hat{J}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i^\top \mathbf{x}_i$$

with $\hat{\theta}_n$ solving the OLS system.

1. Under the most common (correct specification) homoscedastic (ie constant variance) model, for iid samples from the joint distribution,

$$\mathbb{E}_{Y|X}[Y - \mathbf{x}\theta_0 | \mathbf{x}] = 0 \quad \mathbb{E}_{Y|X}[(Y - \mathbf{x}\theta_0)^2 | \mathbf{x}] = \sigma^2$$

so that by iterated expectation

$$\mathcal{I}(\theta_0) = \sigma^2 \mathbb{E}[\mathbf{x}^\top \mathbf{x}]$$

and hence

$$\mathbf{V} = \sigma^2 \{\mathbb{E}[\mathbf{x}^\top \mathbf{x}]\}^{-1}$$

For the influence function for θ , we have from the theory of m -estimation that

$$\varphi(X, Y) = \{\mathcal{J}(\theta_0)\}^{-1} \mathbf{U}(\theta_0) = \{\mathbb{E}[\mathbf{x}^\top \mathbf{x}]\}^{-1} \mathbf{x}^\top (Y - \mathbf{x}\theta_0)$$

Also, therefore, we have that

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \text{Normal}_p(0, \sigma^2 \{\mathbb{E}[\mathbf{x}^\top \mathbf{x}]\}^{-1}).$$

2. Focussing on the parameter of interest alone, we seek now a suitable influence or estimating function for estimating ψ . As this is a q -dimensional parameter, we seek a q -dimensional function.

The theory from lectures suggests that we can derive a suitable estimating equation by projecting the estimating function for ψ onto the nuisance tangent space and taking the residual. In this case, the nuisance tangent space is merely the linear space Λ spanned by $\mathbf{x}_1^\top$, that is

$$\Lambda = \{\mathbf{B}\mathbf{x}_1^\top : \mathbf{B} \text{ a } q \times r \text{ matrix}\}$$

Write $\varepsilon = Y - \mathbf{x}_2^\top \psi_0 - \mathbf{x}_1^\top \theta_0$, and

$$\mathbf{U}(\theta_0) = \begin{bmatrix} \mathbf{U}_\psi(\theta_0) \\ \mathbf{U}_\beta(\theta_0) \end{bmatrix} = \begin{bmatrix} \mathbf{x}_2^\top \varepsilon \\ \mathbf{x}_1^\top \varepsilon \end{bmatrix}$$

The projection of $\mathbf{U}_\psi(\theta_0)$ onto Λ is computed by finding $\mathbf{B}_0$ (a $q \times r$ matrix) such that

$$\mathbb{E}[(\mathbf{x}_2^\top \varepsilon - \mathbf{B}_0 \mathbf{x}_1^\top \varepsilon)^\top \mathbf{B} \mathbf{x}_1^\top \varepsilon] = 0$$

for all $\mathbf{B}$. As per the results on slide p389, we can write explicitly

$$\mathbf{B}_0 = \mathbb{E}[\varepsilon^2 \mathbf{x}_2^\top \mathbf{x}_1] \{\mathbb{E}[\varepsilon^2 \mathbf{x}_1^\top \mathbf{x}_1]\}^{-1}$$

and hence the projection as

$$\mathbf{B}_0 \mathbf{x}_1^\top \varepsilon = \mathbb{E}[\varepsilon^2 \mathbf{x}_2^\top \mathbf{x}_1] \{\mathbb{E}[\varepsilon^2 \mathbf{x}_1^\top \mathbf{x}_1]\}^{-1} \mathbf{x}_1^\top \varepsilon$$

Therefore the residual is

$$\mathbf{x}_2^\top \varepsilon - \mathbb{E}[\varepsilon^2 \mathbf{x}_2^\top \mathbf{x}_1] \{\mathbb{E}[\varepsilon^2 \mathbf{x}_1^\top \mathbf{x}_1]\}^{-1} \mathbf{x}_1^\top \varepsilon.$$

3. Under the homoscedastic model, by iterated expectation, the residual becomes

$$\mathbf{x}_2^\top \varepsilon - \mathbb{E}[\mathbf{x}_2^\top \mathbf{x}_1] \{\mathbb{E}[\mathbf{x}_1^\top \mathbf{x}_1]\}^{-1} \mathbf{x}_1^\top \varepsilon.$$

We can estimate the two expectations using sample averages

$$\hat{\mathbb{E}}[\mathbf{x}_2^\top \mathbf{x}_1] = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_{i2}^\top \mathbf{x}_{i1} = \frac{1}{n} \mathbf{X}_2^\top \mathbf{X}_1$$

and

$$\hat{\mathbb{E}}[\mathbf{x}_1^\top \mathbf{x}_1] = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_{i1}^\top \mathbf{x}_{i1} = \frac{1}{n} \mathbf{X}_1^\top \mathbf{X}_1$$

where

$$\mathbf{X}_1 = \begin{bmatrix} \mathbf{x}_{11} \\ \vdots \\ \mathbf{x}_{n1} \end{bmatrix} \quad \mathbf{X}_2 = \begin{bmatrix} \mathbf{x}_{12} \\ \vdots \\ \mathbf{x}_{n2} \end{bmatrix}$$

which are $n \times r$ and $n \times q$ matrixes respectively. This inspires the estimating equation

$$\sum_{i=1}^n (\mathbf{x}_{i2}^\top \varepsilon_i - \mathbf{X}_2^\top \mathbf{X}_1 (\mathbf{X}_1^\top \mathbf{X}_1)^{-1} \mathbf{x}_{i1}^\top \varepsilon_i) = 0$$

or equivalently

$$(\mathbf{X}_2^\top - \mathbf{X}_2^\top \mathbf{X}_1 (\mathbf{X}_1^\top \mathbf{X}_1)^{-1} \mathbf{X}_1^\top) \boldsymbol{\epsilon} = 0$$

where $\boldsymbol{\epsilon} = (\varepsilon_1, \dots, \varepsilon_n)^\top$.

4. Defining

$$\mathbf{H}_1 = \mathbf{X}_1(\mathbf{X}_1^\top \mathbf{X}_1)^{-1} \mathbf{X}_1^\top$$

we see that the estimating equation is

$$(\mathbf{X}_2^\top - \mathbf{X}_2^\top \mathbf{H}_1) \boldsymbol{\epsilon} = \mathbf{0}$$

or equivalently

$$\mathbf{X}_2^\top (\mathbf{I}_n - \mathbf{H}_1) (\mathbf{y} - \mathbf{X}_2 \psi - \mathbf{X}_1 \beta) = \mathbf{0}.$$

This is precisely the estimating equation arrived at by the two-step approach that solves for β for fixed ψ , and then plugs the solution back into the estimating equation to solve for ψ (lecture slides pp 368–378). As

$$(\mathbf{I}_n - \mathbf{H}_1) \mathbf{X}_1 = \mathbf{0} \quad n \times r$$

the equation can also be written

$$\mathbf{X}_2^\top (\mathbf{I}_n - \mathbf{H}_1) (\mathbf{y} - \mathbf{X}_2 \psi) = \mathbf{0}.$$

The solution is

$$\hat{\psi} = (\mathbf{X}_2^\top (\mathbf{I}_n - \mathbf{H}_1) \mathbf{X}_2)^{-1} \mathbf{X}_2^\top (\mathbf{I}_n - \mathbf{H}_1) \mathbf{y}.$$

5. In this case, we get the **same** solution for ψ whether we solve the joint estimating equation or the projected estimating equation. Under the homoscedastic model, using the joint estimating equation, we have asymptotic variance

$$\mathbf{V} = \sigma^2 \{\mathbb{E}[\mathbf{x}^\top \mathbf{x}]\}^{-1}$$

where

$$\mathbb{E}[\mathbf{x}^\top \mathbf{x}] = \mathbb{E} \begin{bmatrix} \mathbf{x}_2^\top \mathbf{x}_2 & \mathbf{x}_2^\top \mathbf{x}_1 \\ \mathbf{x}_1^\top \mathbf{x}_2 & \mathbf{x}_1^\top \mathbf{x}_1 \end{bmatrix} = \begin{bmatrix} \mathbf{V}_{22} & \mathbf{V}_{21} \\ \mathbf{V}_{12} & \mathbf{V}_{11} \end{bmatrix}$$

say, so therefore by results for block matrices, the asymptotic variance for ψ is

$$\sigma^2 (\mathbf{V}_{22} - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{V}_{21})^{-1}.$$

Direct from the projected estimating function,

$$\mathbf{U}_\psi^{\text{proj}}(\theta) = \mathbf{x}_2^\top \boldsymbol{\epsilon} - \mathbb{E}[\boldsymbol{\epsilon}^2 \mathbf{x}_2^\top \mathbf{x}_1] \{\mathbb{E}[\boldsymbol{\epsilon}^2 \mathbf{x}_1^\top \mathbf{x}_1]\}^{-1} \mathbf{x}_1^\top \boldsymbol{\epsilon} = (\mathbf{x}_2^\top - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top) \boldsymbol{\epsilon}$$

we have that the asymptotic variance is

$$\sigma^2 \left\{ \mathbb{E} \left[(\mathbf{x}_2^\top - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top) (\mathbf{x}_2^\top - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top)^\top \right] \right\}^{-1}.$$

Now

$$(\mathbf{x}_2^\top - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top) (\mathbf{x}_2^\top - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top)^\top = \mathbf{x}_2^\top \mathbf{x}_2 - \mathbf{x}_2^\top \mathbf{x}_1 \mathbf{V}_{11}^{-1} \mathbf{V}_{12} - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top \mathbf{x}_2 + \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{x}_1^\top \mathbf{x}_1 \mathbf{V}_{11}^{-1} \mathbf{V}_{12}$$

and taking expectations yields

$$\mathbf{V}_{22} - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{V}_{12} - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{V}_{12} + \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{V}_{11} \mathbf{V}_{11}^{-1} \mathbf{V}_{12} = \mathbf{V}_{22} - \mathbf{V}_{21} \mathbf{V}_{11}^{-1} \mathbf{V}_{12}$$

and the two asymptotic variances match.

```
#Numerical verification
set.seed(1293)
library(mvnfast)
muX<-c(-1,2,1)
Sig<-0.9^abs(outer(1:3,1:3,'-'))
n<-1000
X<-rmvn(n,muX,Sig)
th<-c(1,1,1,1)
Xm<-cbind(1,X)
Y<- Xm %*% th + rnorm(n)*2

coef(summary(lm(Y~X)))
```

```

+           Estimate Std. Error  t value    Pr(>|t|)
+ (Intercept) 1.1650961  0.4581732  2.542917  1.114348e-02
+ X1          0.9968153  0.1503912  6.628150  5.559852e-11
+ X2          0.8739335  0.1997438  4.375272  1.340581e-05
+ X3          1.0751411  0.1469218  7.317776  5.184399e-13

X1<-Xm[,1:2] #Take beta to be the first two elements of theta
X2<-Xm[,3:4] #Take psi to be the last two elements of theta

#Joint estimating equation
th.hat<-solve(t(Xm) %*% Xm) %*% (t(Xm) %*% Y)
th.hat

+           [,1]
+ [1,] 1.1650961
+ [2,] 0.9968153
+ [3,] 0.8739335
+ [4,] 1.0751411

Y.hat0<- Xm %*% th.hat
sigsq.hat<-sum((Y-Y.hat0)^2)/(n-length(th.hat))
sigsq.hat

+ [1] 4.079885

#Variance
V<-sigsq.hat * solve((t(Xm) %*% Xm)/n)/n
V

+           [,1]      [,2]      [,3]      [,4]
+ [1,] 0.20992264 0.0629881266 -0.08040989 0.0172747704
+ [2,] 0.06298813 0.0226175095 -0.02011278 -0.0003756986
+ [3,] -0.08040989 -0.0201127803 0.03989759 -0.0194391372
+ [4,] 0.01727477 -0.0003756986 -0.01943914 0.0215860284

sqrt(diag(V)) #Matches the standard error column above

+ [1] 0.4581732 0.1503912 0.1997438 0.1469218

#Variance calc with I and J matrices
Ihat<-(t(Xm) %*% (Xm * matrix(Y-Y.hat0,nrow=n,ncol=4)^2))/n
Jhat<-(t(Xm) %*% Xm)/n
Vhat<-(solve(Jhat) %*% Ihat %*% solve(t(Jhat)))/n
Vhat

+           [,1]      [,2]      [,3]      [,4]
+ [1,] 0.19948463 0.0602972084 -0.07637099 0.0168832616
+ [2,] 0.06029721 0.0220906118 -0.01860799 -0.0009084687
+ [3,] -0.07637099 -0.0186079919 0.03918979 -0.0202802382
+ [4,] 0.01688326 -0.0009084687 -0.02028024 0.0229538245

sqrt(diag(Vhat))

+ [1] 0.4466370 0.1486291 0.1979641 0.1515052

#####
#Projected estimating equation
I.n<-diag(rep(1,n))
H1<- X1 %*% solve(t(X1) %*% X1) %*% t(X1)
psi.hat<-solve(t(X2) %*% (I.n-H1) %*% X2) %*% (( t(X2)%*%(I.n-H1)) %*% Y)
psi.hat

+           [,1]
+ [1,] 0.8739335
+ [2,] 1.0751411

```

```

#Variance estimation
V11<-(t(X1) %*% X1)/n
V12<-(t(X1) %*% X2)/n
V21<-t(V12)
V22<-(t(X2) %*% X2)/n

V<-sigsq.hat*solve(V22-(V21 %*% solve(V11) %*% V12))/n
sqrt(diag(V))

+ [1] 0.1997438 0.1469218

#Check one of the claimed orthogonalities
M<-(I.n-H1) %*% X1
apply(M,2,mean)

+ [1] -3.015206e-16 1.177847e-15

apply(M,2,var)

+ [1] 1.081672e-30 4.425538e-30

```