

MATH 598: TOPICS IN STATISTICS

BAYESIAN MIXTURE MODELLING OF THE GALAXY DATA

The finite mixture model with K components has density

$$f(y; \omega, \theta, K) = \sum_{k=1}^K \omega_k f_k(y; \theta_k)$$

where θ_k are the parameters for component density k , and $0 < \omega_k < 1, k = 1, \dots, K$ with $\sum_{k=1}^K \omega_k = 1$. Most typically the component densities are from the same parametric location-scale family (say Gaussian) which differ in location and scale. The model can be represented by introducing latent component indicators z_1, \dots, z_n , so that

$$f(y_i; \omega, \theta, K) = \sum_{k=1}^K f(y|Z_i = k; \theta) \Pr[Z_i = k]$$

and $\Pr[Z_i = k] = \omega_k$ for $k = 1, \dots, K$.

For exchangeable data (y_1, \dots, y_n) from this model, the likelihood arising from this model does not permit analytical calculation of the posterior distribution, so MCMC is commonly used.

- If K is **known**, MCMC is typically implemented using a completed data model

- Auxiliary variables z_1, \dots, z_n ,

$$f(y, z; \omega, \theta, K) = \omega_z f_z(y; \theta_z) \quad z \in \{1, 2, \dots, K\}$$

- Gibbs sampler strategy updates the z and (ω, θ) from their full conditional posterior distributions.

- Conditional on (ω, θ) , the posterior distribution for each z_i is a discrete distribution on $\{1, 2, \dots, K\}$, whereas conditional on the z , the posterior for the mixture weights ω is a density on the K dimensional simplex, and the posterior for the components of θ_k proceeds using only those y_i for which $z_i = k$, for $k = 1, \dots, K$.

- If K is **unknown**, then transdimensional MCMC is also needed.

- A discrete prior on K , typically on some finite set, completes the posterior specification, and yields a posterior distribution $\pi_n(K, \theta^{(K)}, \omega^{(K)})$.
- In this model, dimension-changing moves correspond to changing the value of K , and in order to construct an efficient and tunable MCMC algorithm, moves which perturb K by ± 1 are typically considered.
- For example, moves of type $K \rightarrow K + 1$ are termed “birth” moves, and $K \rightarrow K - 1$ are termed “death” moves.
- The forward/reverse move pairs are then births from K and deaths from $K + 1$.
- Inference about the parameter K may be of primary interest in a given application.

Normal Model: For a Normal mixture model:

- If y is one dimensional, each component density has two parameters, so a birth/death pair requires the introduction of three latent variables u , a new mean and variance, and also a parameter to introduce a new component weight.
- If y is d -dimensional, $d + d(d+1)/2 + 1$ new scalar parameters are needed, that is, a new mean and covariance matrix, and a new component weight parameter.
- **New location/scale parameters:** Either these new parameters are generated independently of the current model parameters from proposal distribution, or a subset of the current components are selected and used to generate a new additional component.
- **New weight parameters:** A random split or rescaling of the currently existing weights is used.

Galaxies Data: The galaxies data are commonly used to illustrate mixture modelling. From the R help:

```
galaxies           package:MASS          R Documentation
```

```
Velocities for 82 Galaxies
```

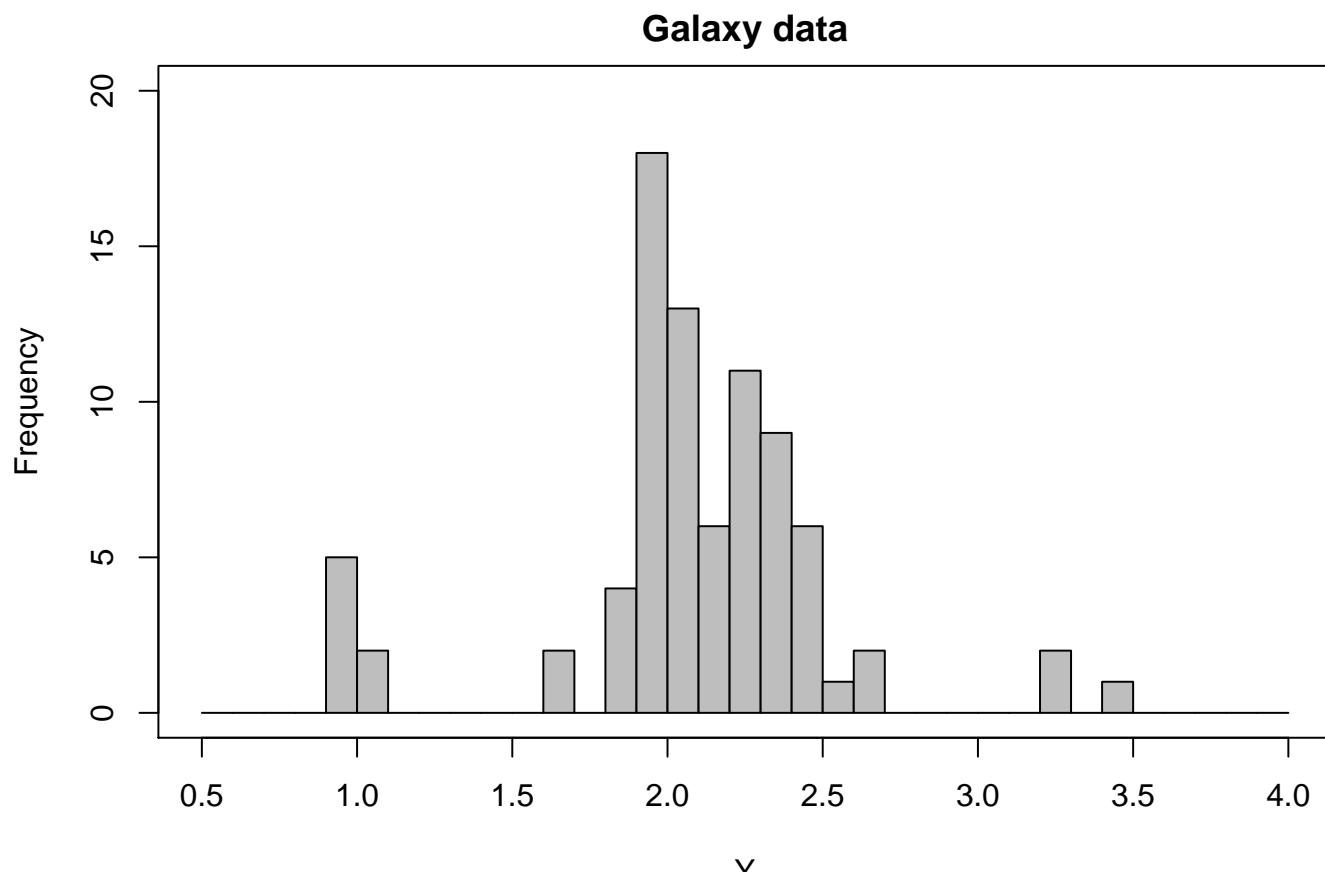
Description:

A numeric vector of velocities in km/sec of 82 galaxies from 6 well-separated conic sections of an 'unfilled' survey of the Corona Borealis region. Multimodality in such surveys is evidence for voids and superclusters in the far universe.

```
(Y<-MASS::galaxies/10000);n<-length(Y)
```

```
+ [1] 0.9172 0.9350 0.9483 0.9558 0.9775 1.0227 1.0406 1.6084 1.6170 1.8419  
+ [11] 1.8552 1.8600 1.8927 1.9052 1.9070 1.9330 1.9343 1.9349 1.9440 1.9473  
+ [21] 1.9529 1.9541 1.9547 1.9663 1.9846 1.9856 1.9863 1.9914 1.9918 1.9973  
+ [31] 1.9989 2.0166 2.0175 2.0179 2.0196 2.0215 2.0221 2.0415 2.0629 2.0795  
+ [41] 2.0821 2.0846 2.0875 2.0986 2.1137 2.1492 2.1701 2.1814 2.1921 2.1960  
+ [51] 2.2185 2.2209 2.2242 2.2249 2.2314 2.2374 2.2495 2.2746 2.2747 2.2888  
+ [61] 2.2914 2.3206 2.3241 2.3263 2.3484 2.3538 2.3542 2.3666 2.3706 2.3711  
+ [71] 2.4129 2.4285 2.4289 2.4366 2.4717 2.4990 2.5633 2.6690 2.6995 3.2065  
+ [81] 3.2789 3.4279
```

```
par(mar=c(4,4,2,0))  
low<-0.5;high<-4;del<-0.1  
hist(Y,breaks=seq(low,high,by=del),col='gray',ylim=range(0,20),main='Galaxy data')  
box()
```



We can analyze these data using the EM algorithm

```

mix.like<-function(muv,sigv,omv,yv){
  dvec<-rep(0,length(yv))
  for(i in 1:length(yv)){
    dvec[i]<-sum(omv*dnorm(yv[i],muv,sigv))
  }
  return(sum(log(dvec)))
}

em.analysis<-function(Yv,Kv,tolv=1e-10,iseed=10101){
  nv<-length(Yv)
  #Starting values
  omega.r<-omega.r1<-rep(1/Kv,Kv)
  if(iseed == 0){
    mu.vec.r<-mu.vec.r1<-quantile(Yv,prob=c(1:Kv)/(Kv+1))
  }else{
    set.seed(iseed)
    mu.vec.r<-mu.vec.r1<-runif(Kv,min(Yv),max(Yv))
  }
  sig.vec.r<-sig.vec.r1<-rep(sqrt(var(Yv)),Kv)
  varomega.r<-matrix(0,nrow=nv,ncol=Kv)

  Ym<-matrix(Yv,ncol=1)
  #Run the EM algorithm until convergence.
  del<-1
  while(del > tolv){
    for(i in 1:nv){
      for(k in 1:Kv){
        varomega.r[i,k]<-omega.r[k]*dnorm(Yv[i],mu.vec.r[k],sig.vec.r[k])
      }
      varomega.r[i,]<-varomega.r[i,]/sum(varomega.r[i,])
    }

    omega.r1<-apply(varomega.r,2,sum)
    omega.r1<-omega.r1/sum(omega.r1)
    for(k in 1:Kv){
      mu.vec.r1[k]<-sum(varomega.r[,k]*Yv)/sum(varomega.r[,k])
      sig.vec.r1[k]<-sqrt(sum(varomega.r[,k]*(Yv-mu.vec.r1[k])^2)/sum(varomega.r[,k]))
    }
    del<-sum((omega.r-omega.r1)^2)+sum((mu.vec.r-mu.vec.r1)^2)+sum((sig.vec.r-sig.vec.r1)^2)
    omega.r<-omega.r1
    mu.vec.r<-mu.vec.r1
    sig.vec.r<-sig.vec.r1
    like<-mix.like(mu.vec.r,sig.vec.r,omega.r,Yv)
  }
  return(list(mu=mu.vec.r,sig=sig.vec.r,omega=omega.r,Like=like))
}

```

The EM algorithm exploits the complete data likelihood obtained by including the latent component indicator variables $\mathbf{Z} = (Z_1, \dots, Z_n)$, and recursively solves

$$\theta^{(r+1)} = \arg \max_{\theta} Q(\theta; \theta^{(r)}) = \arg \max_{\theta} \mathbb{E}_{\mathbf{Z}|\mathbf{Y}} \left[\log f(\mathbf{Y}, \mathbf{Z}; \theta) | \mathbf{y}; \theta^{(r)} \right]$$

for $r = 1, 2, \dots$, where

$$f(\mathbf{y}, \mathbf{z}; \theta) = \prod_{i=1}^n \prod_{k=1}^K \left\{ \omega_k f(y_i; \mu_k, \sigma_k^2) \right\}^{\mathbb{1}_{\{k\}}(z_i)}$$

is the complete data likelihood.

The EM algorithm can be sensitive to starting values due to the multi-modal nature of the likelihood, so we choose 20 random collections of starting means, and take the maximum value achieved across the different runs.

```
Like.mat<-matrix(0,nrow=8,ncol=20)
Like.vec<-j.vec<-rep(0,8)
for(k in 1:8){
  rmax<--Inf
  for(j in 1:20){
    f.em<-em.analysis(Y,tol=1e-10,Kv=k,iseed=j^3+j^2+j+1)
    Like.mat[k,j]<-f.em$Like
    if(f.em$Like > rmax){
      Like.vec[k]<-f.em$Like
      rmax<-f.em$Like
      j.vec[k]<-j
    }
  }
}
```

We can perform model selection using AIC or BIC

$$\text{AIC} := -2 \log \mathcal{L}_n^{(K)}(\hat{\theta}^{(K)}) + 2d_K$$

$$\text{BIC} := -2 \log \mathcal{L}_n^{(K)}(\hat{\theta}^{(K)}) + d_K \log n$$

where $d_K = 3K - 1$ – we select the model for which each quantity is smallest.

```
np<-3*c(1:8)-1
Res<-rbind(Like.vec,-2*Like.vec+np*2,-2*Like.vec+np*log(n))
colnames(Res)<-1:8
row.names(Res)<-c("Max logLik.", "AIC", "BIC")
round(Res,3)

+           1       2       3       4       5       6       7       8
+ Max logLik. -51.526 -31.246 -14.367 -8.642 -1.259  1.945  4.714  7.822
+ AIC         107.052  72.492  44.735 39.284 30.518 30.111 30.571 30.355
+ BIC         111.865  84.526  63.988 65.757 64.212 71.025 78.706 85.710
```

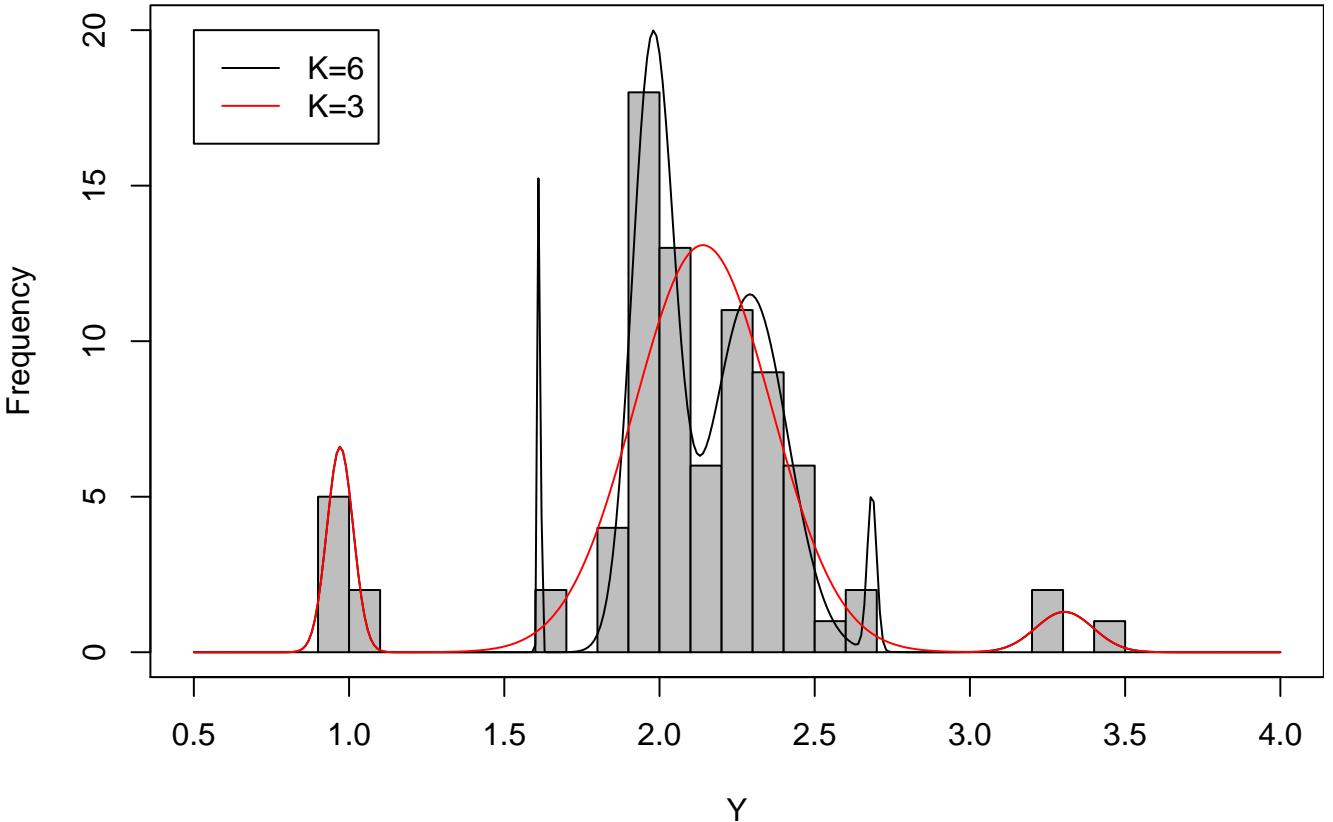
By AIC, there is little difference between fits for $k = 5, 6, 7, 8$, whereas for BIC, $k = 3$ seems optimal.

```
mix.like.par<-function(muv,sigv,omv,yv,Kv){

  dvec<-rep(0,length(yv))
  for(k in 1:Kv){
    dvec<-dvec+omv[k]*dnorm(yv,muv[k],sigv[k])
  }
  return(sum(log(dvec)))
}

f.emA<-em.analysis(Y,tolv=1e-10,Kv=6,iseed=j.vec[6]^3+j.vec[6]^2+j.vec[6]+1)
f.emB<-em.analysis(Y,tolv=1e-10,Kv=3,iseed=j.vec[3]^3+j.vec[3]^2+j.vec[3]+1)
xvec<-seq(low,high,by=0.01)
yvec.A<-yvec.B<-xvec*0
for(k in 1:6){
  yvec.A<-yvec.A+f.emA$omega[k]*dnorm(xvec,f.emA$mu[k],f.emA$sig[k])
}
for(k in 1:3){
  yvec.B<-yvec.B+f.emB$omega[k]*dnorm(xvec,f.emB$mu[k],f.emB$sig[k])
}
par(mar=c(4,4,2,0))
low<-0.5;high<-4;del<-0.1
hist(Y,breaks=seq(low,high,by=del),col='gray',main='Galaxy data',ylim=range(0,20));box()
lines(xvec,yvec.A*n*del)
lines(xvec,yvec.B*n*del,col='red')
legend(0.5,20,c('K=6','K=3'),lty=1,col=c('black','red'))
```

Galaxy data



For the Bayesian solution, we specify the following hierarchical prior

$$\pi_0(K)\pi_0(\sigma_{K1}^2, \dots, \sigma_{KK}^2|K)\pi_0(\mu_{K1}^2, \dots, \mu_{KK}^2|\sigma_{K1}^2, \dots, \sigma_{KK}^2, K)\pi_0(\omega_{K1}, \dots, \omega_{KK}^2|K)$$

- Prior for K : we specify a $Poisson(\gamma)$ prior restricted to the positive integers, with pmf

$$\pi_0(K) = \frac{\gamma^K \exp\{-\gamma\}}{(1 - \exp\{-\gamma\})K!} \quad K = 1, 2, \dots$$

for parameter $\gamma > 0$.

- Prior for σ_{Kk}^2 : we specify independent priors

$$\pi_0(\sigma_{K1}^2, \dots, \sigma_{KK}^2|K) = \prod_{k=1}^K \pi_0(\sigma_{Kk}^2)$$

where $\pi_0(\sigma_{Kk}^2) \equiv InverseGamma(a/2, b/2)$ for hyperparameters $a, b > 0$.

- Prior for μ_{Kk} given σ_{Kk}^2 : we specify conditionally independent priors

$$\pi_0(\mu_{K1}^2, \dots, \mu_{KK}^2|\sigma_{K1}^2, \dots, \sigma_{KK}^2, K) = \prod_{k=1}^K \pi_0(\mu_{Kk}|\sigma_{Kk}^2)$$

where $\pi_0(\mu_{Kk}|\sigma_{Kk}^2) \equiv Normal(\eta, \sigma_{Kk}^2/\lambda)$ for hyperparameters η and $\lambda > 0$.

- Prior for $\omega_{(K)} = (\omega_1^{(K)}, \dots, \omega_K^{(K)})$: we specify a symmetric Dirichlet prior

$$\pi_0(\omega_{K1}, \dots, \omega_{KK}|K) = \frac{\Gamma(K\alpha)}{\{\Gamma(\alpha)\}^K} \prod_{k=1}^K \omega_{Kk}^{\alpha-1}$$

on the K -dimensional unit simplex.

For a reversible jump MCMC solution, we consider Birth and Death move pairs for the transdimensional moves:

- **Birth Move:** We consider an update that changes $K \rightarrow K + 1$, requiring the need to generate a new component. We simulate the new mean and variance parameters from the prior distribution:

$$\sigma_{(K+1)(K+1)}^2 \sim \text{InverseGamma}(a/2, b/2)$$

$$\mu_{(K+1)(K+1)} \sim \text{Normal}(\eta, \sigma_{(K+1)(K+1)}^2 / \lambda)$$

For the new component weight we generate $\psi \sim \text{Beta}(1, K)$, and then set the new component weight vector $\omega_{(K+1)}$ as

$$(\omega_{(K+1)1}, \dots, \omega_{(K+1)(K+1)}) = ((1 - \psi)\omega_{K1}, \dots, (1 - \psi)\omega_{KK}, \psi).$$

The Jacobian of the transform is

$$\frac{1}{(1 - \omega_{(K+1)(K+1)})^K}$$

and therefore the acceptance probability for the Birth move is the minimum of 1 and

$$\frac{\pi_n(K + 1, \mu_{(K+1)}, \sigma_{(K+1)}^2, \omega_{(K+1)})}{\pi_n(K, \mu_K, \sigma_K^2, \omega_K) p(\mu_{(K+1)(K+1)}, \sigma_{(K+1)(K+1)}^2) p(\psi)} \times \frac{1}{(1 - \omega_{(K+1)(K+1)})^K}$$

- **Death Move:** For the (reverse) Death move we consider the dimension change $K + 1 \rightarrow K$ by picking a component at random from the $K + 1$ existing components to eliminate, and then reversing the transformation from the Birth move to set

$$(\omega_{K1}, \dots, \omega_{KK}, \psi) = \frac{1}{(1 - \psi)} (\omega_{(K+1)1}, \dots, \omega_{(K+1)K})$$

for which the Jacobian is $(1 - \psi)^K$, and the acceptance probability is the minimum of 1 and

$$\frac{\pi_n(K, \mu_K, \sigma_K^2, \omega_K) p(\mu_{(K+1)(K+1)}, \sigma_{(K+1)(K+1)}^2) p(\psi)}{\pi_n(K + 1, \mu_{(K+1)}, \sigma_{(K+1)}^2, \omega_{(K+1)})} \times (1 - \psi)^K$$

```

mix.like.par<-function(muv,sigv,omv,yv,Kv){
  dvec<-rep(0,length(yv))
  for(k in 1:Kv){
    dvec<-dvec+omv[k]*dnorm(yv,muv[k],sigv[k])
  }
  return(sum(log(dvec)))
}

dinvgamma<-function(xv,a,b,log=F){
  lv<-a*log(b)-lgamma(a)-(a+1)*log(xv)-b/xv
  if(log){
    return(lv)
  }else{
    return(exp(lv))
  }
}

dpois0<-function(xv, lam, log=F){ #Poisson pmf with zero removed.
  fv<-dpois(xv, lam, log=log)-log(1-exp(-lam))
  if(log){return(fv)}
  }else{return(exp(fv))}
}

```

Choosing the hyperparameters for this conjugate prior can be achieved using simulation methods.

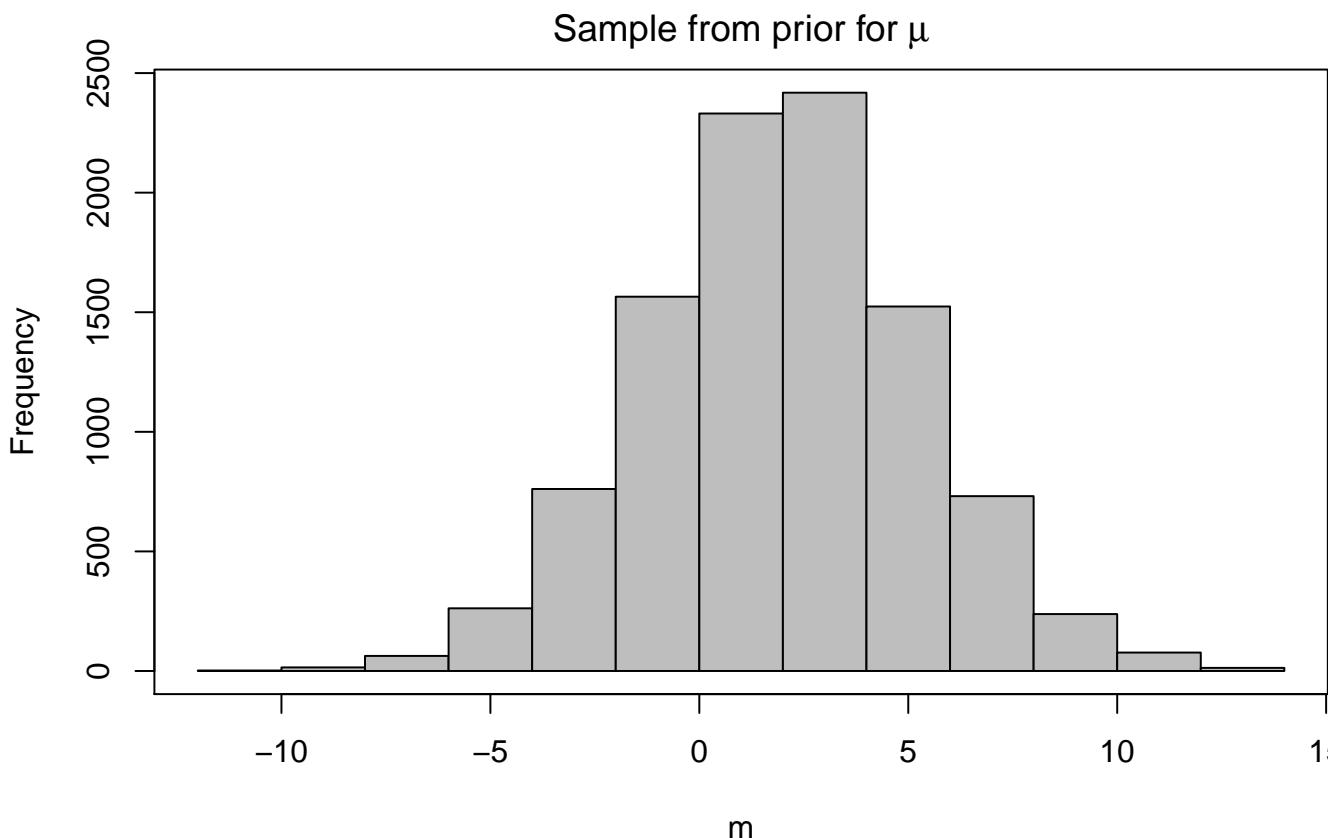
```

#Prior elicitation
prior.al<-1
prior.eta<-2
prior.lam<-0.01
prior.a<-40
prior.b<-4
prior.K.gam<-2

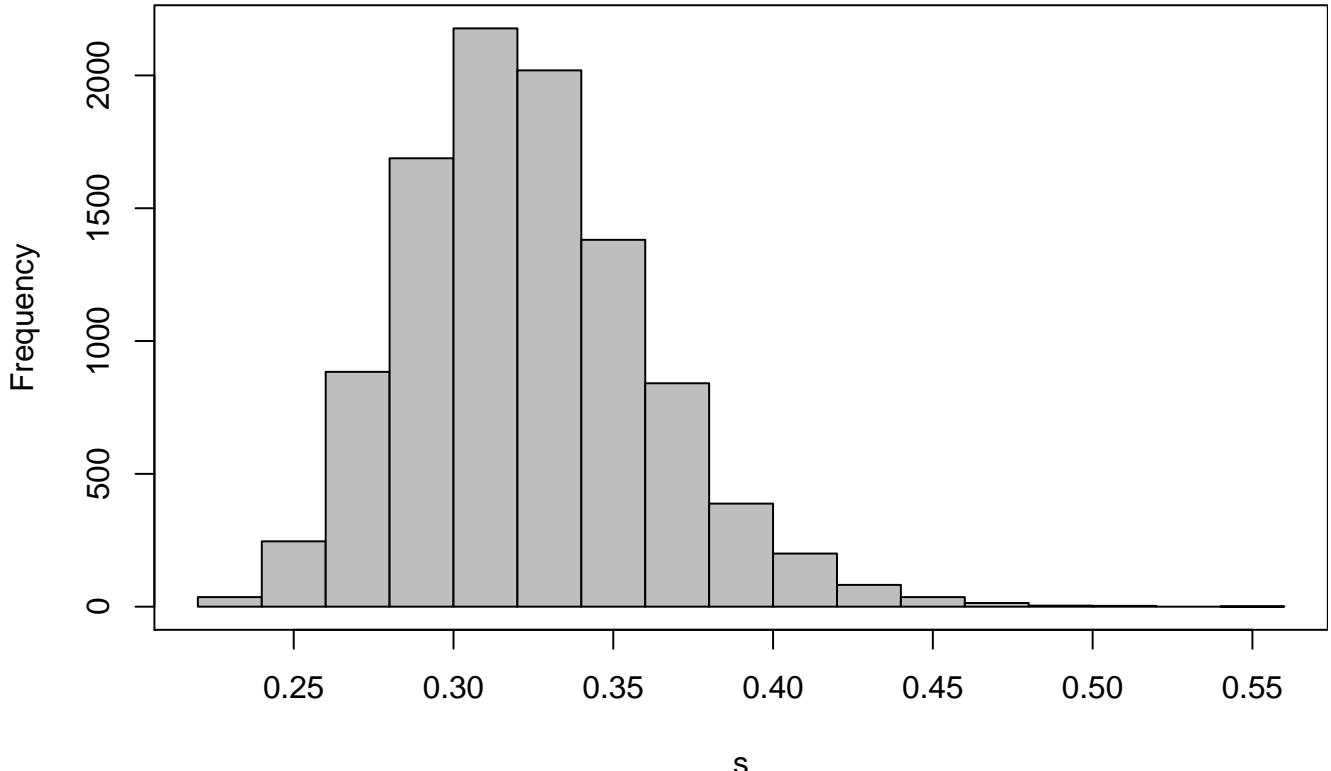
s1<-1
a1<-1

s<-(1/sqrt(rgamma(10000,prior.a/2,prior.b/2)))
m<-rnorm(10000)*s/sqrt(prior.lam)+prior.eta
par(mar=c(4,4,2,0))
hist(m,col='gray',main=expression(paste('Sample from prior for ',mu)));box()

```



Sample from prior for σ



In order to facilitate ease of posterior sampling for the component parameters, we again introduce the latent component indicators Z_1, \dots, Z_n , and sample their values from their full conditional posterior distributions as part of the Gibbs sampler. Conditional on the component parameters, we have that

$$\Pr[Z_i = k | \mathbf{y}, \boldsymbol{\theta}, K] = \frac{\omega_{Kk} f_k(y_i; \mu_{Kk}, \sigma_{Kk}^2)}{\sum_{j=1}^K \omega_{Kj} f_j(y_i; \mu_{Kj}, \sigma_{Kj}^2)} \quad k = 1, \dots, K$$

independently for $i = 1, \dots, n$. Conditional on the sampled Z values we have a conjugate model: specifically the posterior distribution of σ_{Kk}^2 is *InverseGamma*($a_{nk}/2, b_{nk}/2$) distribution with parameters

$$a_{nk} = a + n_{Kk} \quad b_{nk} = b + \frac{n_{Kk}\lambda}{n_{Kk} + \lambda} (\bar{y}_{nKk} - \eta)^2 + \sum_{i:z_i=k} (y_i - \bar{y}_{nKk})^2$$

and the conditional posterior for μ_{Kk} is *Normal*($\eta_{nk}, \sigma_{Kk}^2 / \lambda_{nk}$) where

$$\eta_{nk} = \frac{\lambda\eta + \sum_{i:z_i=k} y_i}{\lambda + n_{Kk}} \quad \lambda_{nk} = \lambda + n_{Kk}$$

where

$$n_{Kk} = \sum_{i=1}^n \mathbb{1}_{\{k\}}(z_i) \quad \bar{y}_{nKk} = \frac{\sum_{i=1}^n \mathbb{1}_{\{k\}}(z_i) y_i}{\sum_{i=1}^n \mathbb{1}_{\{k\}}(z_i)}$$

are the component specific sample size and sample mean at the current iteration. Note that these formulae hold if a component is ‘empty’, that is, if no data are allocated to a given cluster, as in such cases the conditional posterior and conditional prior are identical. For ω_K we have a simple conjugate analysis given the latent indicators

$$\omega_K | - \sim \text{Dirichlet}(K; \alpha + n_{K1}, \dots, \alpha + n_{KK})$$

Note that the Birth and Death steps can be implemented on the collapsed form, by summing out over the possible values of the latent component indicators.

```

set.seed(234)

#Starting values
old.K<-4
old.omega<-old.omega1<-rep(1/old.K,old.K)
old.mu<-old.mu1<-as.numeric(quantile(Y,prob=c(1:old.K)/(old.K+1)))
old.sig<-old.sig1<-rep(sqrt(var(Y)),old.K)
old.z<-rep(0,n)

#Run the MCMC algorithm
nburn<-5000
nsamp<-10000
nthin<-5
nits<-nburn+nsamp*nthin

#Galaxy plot
low<-0.5
high<-4
del<-0.1

par(mar=c(4,4,2,1))
hist(Y,breaks=seq(low,high,by=del),ylim=range(0,20),col='gray',
     main='Galaxy data: posterior sampled pdfs');box()

mu.samp<-matrix(0,nrow=nsamp,ncol=100)
sig.samp<-matrix(0,nrow=nsamp,ncol=100)
omega.samp<-matrix(0,nrow=nsamp,ncol=100)
K.samp<-rep(0,nsamp)
ico<-0
for(iter in 1:nits){
  pvec<-rep(0,old.K)
  for(i in 1:n){
    for(k in 1:old.K){
      pvec[k]<-old.omega[k]*dnorm(Y[i],old.mu[k],old.sig[k])
    }
    old.z[i]<-sample(1:old.K,prob=pvec,size=1)
  }

  for(k in 1:old.K){
    old.omega1[k]<-sum(old.z==k)
  }
  old.omega1<-rgamma(old.K,old.omega1+prior.al,1)
  old.omega<-old.omega1/sum(old.omega1)

  for(k in 1:old.K){
    yk<-Y[old.z==k]
    nk<-length(yk)
    if(nk == 0){
      old.sig[k]<-1/sqrt(rgamma(1,prior.a/2,prior.b/2))
      old.mu[k]<-rnorm(1,prior.eta,old.sig[k]/sqrt(prior.lam))
    }else{
      ssq<-sum((yk-mean(yk))^2)
      post.a<-prior.a+nk
      post.b<-prior.b+ssq+(nk*prior.lam)*(mean(yk)-prior.eta)^2/(nk*prior.lam)
      old.sig[k]<-1/sqrt(rgamma(1,post.a/2,post.b/2))
      post.sig<-old.sig[k]/sqrt(nk*prior.lam)
      post.mu<-(sum(yk)+prior.lam*prior.eta)/(nk*prior.lam)
      old.mu[k]<-rnorm(1,post.mu,post.sig)
    }
  }
}

```

```

old.like<-mix.like.par(old.mu,old.sig,old.omega,Y,old.K)
old.prior<-sum(dinvgamma(old.sig^2,prior.a/2,prior.b/2,log=T))+  

    sum(dnorm(old.mu,prior.eta,old.sig/sqrt(prior.lam),log=T))+  

    lgamma(old.K*prior.al)-old.K*lgamma(prior.al)+  

    (prior.al-1)*sum(log(old.omega))+dpois0(old.K,prior.K.gam,log=T)

#Transdimensional moves: Birth and Death
if(runif(1) < 0.5){
  #Death
  new.K<-old.K-1
  if(new.K == 0){ #Cannot remove last component, prior prob is zero
    mh<-Inf
  }else{
    k<-sample(1:old.K,size=1)
    new.mu<-old.mu[-k]
    new.sig<-old.sig[-k]
    new.omega<-old.omega[-k]/sum(old.omega[-k])
    new.like<-mix.like.par(new.mu,new.sig,new.omega,Y,new.K)
    new.prior<-sum(dinvgamma(new.sig^2,prior.a/2,prior.b/2,log=T))+  

    sum(dnorm(new.mu,prior.eta,new.sig/sqrt(prior.lam),log=T))+  

    lgamma(new.K*prior.al)-new.K*lgamma(prior.al)+  

    (prior.al-1)*sum(log(new.omega))+dpois0(new.K,prior.K.gam,log=T)
    new.q<-dnorm(old.mu[k],prior.eta,old.sig[k]/sqrt(prior.lam),log=T)+  

    dinvgamma(old.sig[k]^2,prior.a/2,prior.b/2,log=T)+  

    dbeta(old.omega[k],1,new.K,log=T)
    logJac<-new.K*log(1-old.omega[k])
    mh<-(new.like+new.prior)-(old.like+old.prior)+new.q+logJac
  }
  if(log(runif(1)) < mh){
    old.K<-new.K
    old.mu<-new.mu
    old.sig<-new.sig
    old.omega<-new.omega
    old.like<-new.like
    old.prior<-new.prior
  }
}else{
  #Birth
  new.K<-old.K+1
  new.s<-1/sqrt(rgamma(1,prior.a/2,prior.b/2))
  new.m<-rnorm(1,prior.eta,new.s/sqrt(prior.lam))
  new.mu<-c(old.mu,new.m)
  new.sig<-c(old.sig,new.s)
  psi<-rbeta(1,1,old.K)
  new.omega<-c(old.omega*(1-psi),psi)
  new.like<-mix.like.par(new.mu,new.sig,new.omega,Y,new.K)
  new.prior<-sum(dinvgamma(new.sig^2,prior.a/2,prior.b/2,log=T))+  

  sum(dnorm(new.mu,prior.eta,new.sig/sqrt(prior.lam),log=T))+  

  lgamma(new.K*prior.al)-new.K*lgamma(prior.al)+  

  (prior.al-1)*sum(log(new.omega))+dpois0(new.K,prior.K.gam,log=T)
  new.q<-dnorm(new.m,prior.eta,new.s/sqrt(prior.lam),log=T)+  

  dinvgamma(new.s^2,prior.a/2,prior.b/2,log=T)+  

  dbeta(psi,1,old.K)
  logJac<-old.K*log(1-psi)
  mh<-(new.like+new.prior)-(old.like+old.prior)-new.q+logJac
  if(log(runif(1)) < mh){
    old.K<-new.K
    old.mu<-new.mu
    old.sig<-new.sig
    old.omega<-new.omega
    old.like<-new.like
  }
}

```

```

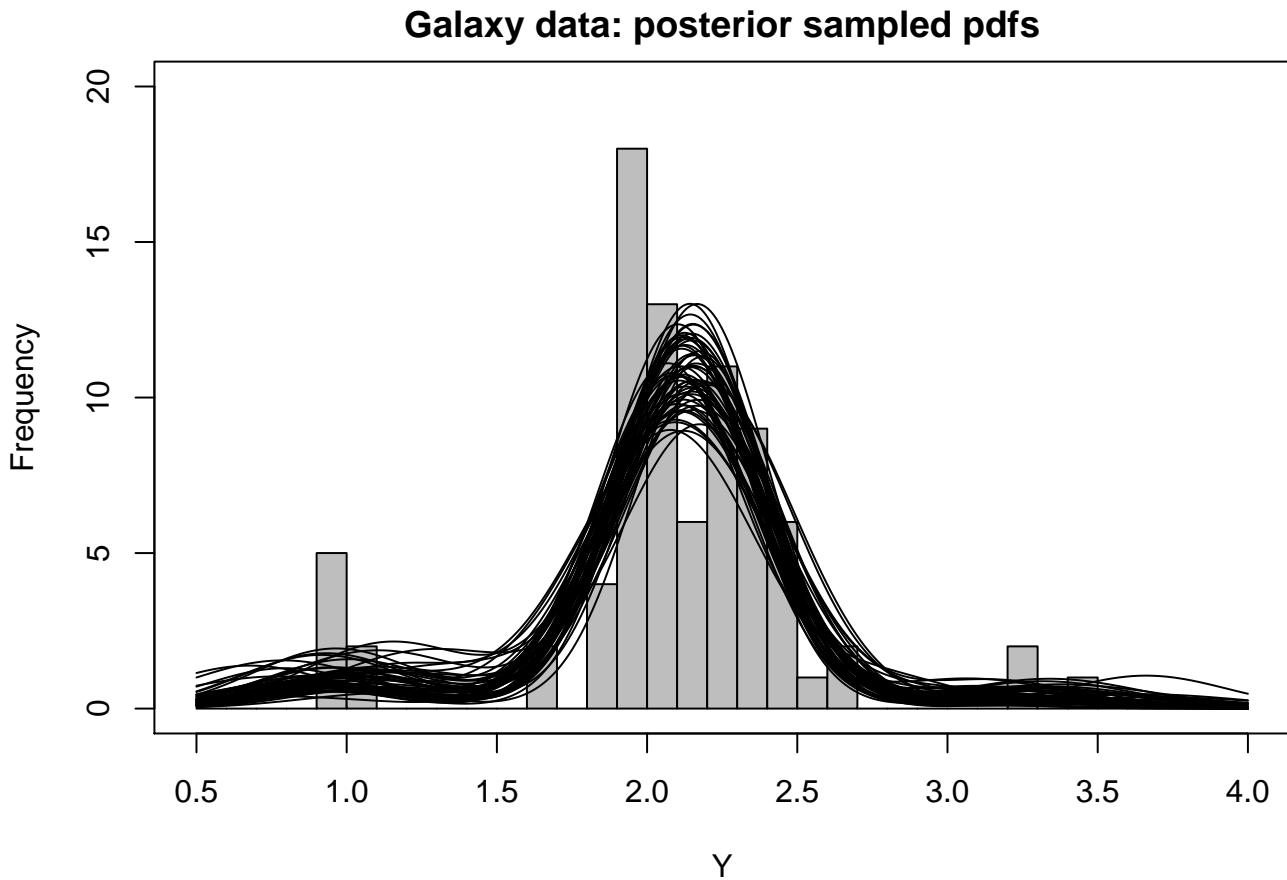
        old.prior<-new.prior
    }
}

if(iter %% 1000 == 0){
  Ly<-mix.like.par(old.mu,old.sig,old.omega,Y,old.K)
  old.Py<-sum(dinvgamma(old.sig^2,prior.a/2,prior.b/2,log=T))+
    sum(dnorm(old.mu,prior.eta,old.sig/sqrt(prior.lam),log=T))+
    lgamma(old.K*prior.al)-old.K*lgamma(prior.al)+
    (prior.al-1)*sum(log(old.omega))+dpois0(old.K,prior.K.gam,log=T)

  xvec<-seq(low,high,by=0.01)
  yvec<-xvec*0
  for(k in 1:old.K){
    yvec<-yvec+old.omega[k]*dnorm(xvec,old.mu[k],old.sig[k])
  }
  lines(xvec,yvec*n*del)
}

if(iter > nburn & iter %% nthin == 0){
  ico<-ico+1
  mu.samp[ico,1:old.K]<-old.mu
  sig.samp[ico,1:old.K]<-old.sig
  omega.samp[ico,1:old.K]<-old.omega
  K.samp[ico]<-old.K
}
}

```



The approximate posterior distribution (under this prior specification) is computed from the sampled values of K .

```
K.post<-table(K.samp)/nsamp  
K.post  
+ K.samp  
+ 2 3 4 5 6  
+ 0.0003 0.9168 0.0795 0.0033 0.0001
```

Therefore the posterior probability on $k = 3$ is 0.916800.