## MATH 556 - ASSIGNMENT 1

## To be handed in not later than 5pm, 28th September 2006.

Please hand in during lectures, to Burnside 1235, or to the Mathematics Office Burnside 1005

1. Suppose $X$ and $Y$ are discrete random variables having joint pmf given by

$$
f_{X, Y}(x, y)=c \frac{(x+y) \phi^{x+y}}{x!y!} \quad x, y \geq 0
$$

and zero otherwise, for constant $c$ and parameter $\phi>0$.
Find expressions for each of the following quantities.
(a) The constant $c$.
(b) The marginal pmf for $X, f_{X}$.
(c) The probability

$$
P[X+Y=r]
$$

for general $r \geq 0$.
(d) The expectation of $X$.

10 MARKS
2. Two points $A_{1}$ and $A_{2}$ are selected independently from the interior of the unit disc $\mathcal{D}$ (the disc centered at the origin, with radius 1 ), according to the following probability law; a point $A$ is identified using polar coordinate random variables $(R, T)$ ( $R$ is the radius, $T$ the angle in radians measured from the $x$-axis), and the joint pdf of $(R, T)$ is given by

$$
f_{R, T}(r, t)=\frac{r}{\pi} \quad 0 \leq t<2 \pi, 0<r<1
$$

and zero otherwise.
Find the probability that the circle centered at $A_{1}$ with radius $\left|A_{1} A_{2}\right|$ (that is, the distance between $A_{1}$ and $A_{2}$ ) is contained entirely within $\mathcal{D}$.
Hint: For random point $A$ and set $\mathcal{B}$,

$$
P[A \in B]=\int_{\mathcal{B}} \int f_{R, T}(r, t) d r d t \equiv \int_{\mathcal{B}} \int g(x, y) d x d y
$$

where the second integral is obtained after changing variables to Cartesian coordinates, for some integrand $g(x, y)$.

10 MARKS
3. A pmf for discrete random variable $X$ taking values on the non-negative integers $\{0,1,2, \ldots\}$ is specified by the countable set of probabilities $\left\{p_{0}, p_{1}, p_{2}, \ldots\right\}$, where $P[X=j]=p_{j}$ for each $j$. An equivalent specification in terms of the hazard probabilities, $\left\{h_{0}, h_{1}, h_{2}, \ldots\right\}$, is also possible, where

$$
h_{j}=h_{X}(j)=P[X=j \mid X \geq j]
$$

Find expressions for
(a) $p_{j}, j \geq 0$,
(b) the survivor function, $S_{X}(x)=P[X>x]$.
in terms of $\left\{h_{0}, h_{1}, h_{2}, \ldots\right\}$

