## 556: MATHEMATICAL STATISTICS I

## BASIC PROPERTIES OF MULTIVARIATE DISTRIBUTIONS

A random vector (or vector random variable)  $\mathbf{X} = (X_1, \dots, X_d)$  is a *d*-dimensional extension of a random variable. We define

• Joint cdf:  $F_{\mathbf{X}}(\mathbf{x}) = F_{X_1,\dots,X_d}(x_1,\dots,x_d)$  defined by

$$F_{X_1,...,X_d}(x_1,...,x_d) = P_{X_1,...,X_d} \left[ \bigcap_{j=1}^d (X_j \in (-\infty, x_j]) \right] = P_{X_1,...,X_d} \left[ \bigcap_{j=1}^d (X_j \le x_j) \right].$$

This function has the following properties:

(i) Limit behaviour:

$$\lim_{\operatorname{Any} j: x_j \longrightarrow -\infty} F_{X_1, \dots, X_d}(x_1, \dots, x_d) = 0 \qquad \lim_{\operatorname{All} j: x_j \longrightarrow \infty} F_{X_1, \dots, X_d}(x_1, \dots, x_d) = 1$$

(ii) Non-decreasing in each dimension: for all j and any h > 0

$$F_{X_1,\ldots,X_j,\ldots,X_d}(x_1,\ldots,x_j,\ldots,x_d) \le F_{X_1,\ldots,X_j,\ldots,X_d}(x_1,\ldots,x_j+h,\ldots,x_d)$$

(iii) Right-continuous in each dimension: for all j

$$\lim_{h \to 0^+} F_{X_1, \dots, X_j, \dots, X_d}(x_1, \dots, x_j + h, \dots, x_d) = F_{X_1, \dots, X_j, \dots, X_d}(x_1, \dots, x_j, \dots, x_d)$$

(iv) Marginalization: without loss of generality, consider  $x_1 \rightarrow \infty$ . We have from the definition of the joint cdf that

$$\lim_{x_1 \to \infty} F_{X_1, \dots, X_d}(x_1, \dots, x_d) = F_{X_2, \dots, X_d}(x_2, \dots, x_d)$$

where the right-hand side is the joint cdf of  $(X_2, \ldots, X_d)$ . This result holds whichever component we allow to increase to infinity. It also holds if we allow more than one component to increase to infinity.

The joint distribution of  $(X_1, ..., X_d)$  thus defines the marginal distribution of any subset of the components of  $(X_1, ..., X_d)$ .

• Joint pmf: If all the elements of X are discrete, then we can consider the joint pmf denoted  $f_{\mathbf{X}}(\mathbf{x}) = f_{X_1,\dots,X_d}(x_1,\dots,x_d)$  defined by

$$f_{X_1,...,X_d}(x_1,...,x_d) = P_{X_1,...,X_d} \left[ \bigcap_{j=1}^d (X_j = x_j) \right].$$

This function has the following properties:

- (i) Boundedness:  $0 \le f_{X_1,...,X_d}(x_1,...,x_d) \le 1$ .
- (ii) Summability: by the probability axioms, if  $X^{(d)}$  denotes the support of the joint pmf

$$\sum_{\mathbf{x}\in\mathbb{X}^{(d)}}f_{X_1,\ldots,X_d}(x_1,\ldots,x_d)=1.$$

• Joint pdf: If we can represent

$$F_{X_1,\dots,X_d}(x_1,\dots,x_d) = \int_{-\infty}^{x_1} \cdots \int_{-\infty}^{x_d} f_{X_1,\dots,X_d}(t_1,\dots,t_d) \, dt_1\dots dt_d$$

then *X* is absolutely continuous with joint pdf  $f_{\mathbf{X}}(\mathbf{x}) = f_{X_1,...,X_d}(x_1,...,x_d)$ . This function has the following properties:

- (i) Non-negativity:  $f_{X_1,...,X_d}(x_1,...,x_d) \ge 0$ .
- (ii) Integrability:

$$\int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} f_{X_1,\dots,X_d}(x_1,\dots,x_d) \, dx_1\dots dx_d = 1.$$

• Conditional pmf/pdf: for any partition of  $\mathbf{X} = (\mathbf{X}_1, \mathbf{X}_2)$ , we may define the conditional pmf/pdf for  $\mathbf{X}_2$ , given that  $\mathbf{X}_1 = \mathbf{x}_1$  as

$$f_{\mathbf{X}_2|\mathbf{X}_1}(\mathbf{x}_2|\mathbf{x}_1) = \frac{f_{\mathbf{X}}(\mathbf{x})}{f_{\mathbf{X}_1}(\mathbf{x}_1)}$$

provided  $f_{\mathbf{X}_1}(\mathbf{x}_1) > 0$ . This allows us to deduce the chain rule factorization

$$f_{X_1,\dots,X_d}(x_1,\dots,x_d) = f_{X_1}(x_1) \prod_{j=2}^d f_{X_j|X_1,\dots,X_{j-1}}(x_j|x_1,\dots,x_{j-1})$$

provided all the conditional distributions are well-defined. In the factorization, the labelling of the variables is arbitrary.

• Independence:  $X_1, \ldots, X_d$  are independent if, for all  $(x_1, \ldots, x_d)$ 

$$F_{X_1,...,X_d}(x_1,...,x_d) = \prod_{j=1}^d F_{X_j}(x_j)$$

or equivalently

$$f_{X_1,...,X_d}(x_1,...,x_d) = \prod_{j=1}^d f_{X_j}(x_j)$$

This definition is equivalent to saying that

$$f_{X_1|X_2,\dots,X_d}(x_1|x_2\dots,x_d) = f_{X_1}(x_1)$$

for all possible selections of  $x_1, \ldots, x_d$ ; note that the labelling of the variables is arbitrary, so this definition applies equivalently for any permutation of the labels.

• **Region probabilities:** Let  $A \subseteq \mathbb{R}^d$ . To compute

$$P_{X_1,\ldots,X_d}[(X_1,\ldots,X_d)\in A]$$

we may write

$$P_{X_1,\dots,X_d}[(X_1,\dots,X_d)\in A] = \int \cdots \int dF_{X_1,\dots,X_d}(x_1,\dots,x_d)$$

• 1-1 Transformations: For continuous variables  $(X_1, \ldots, X_d)$  with support  $\mathbb{X}^{(d)}$  and joint pdf  $f_{X_1,\ldots,X_d}$  we can construct the pdf of a transformed set of variables  $(Y_1,\ldots,Y_d)$  using the following steps:

1. Write down the set of transformation functions  $g_1, \ldots, g_d$ 

$$Y_1 = g_1 (X_1, \dots, X_d)$$
  
$$\vdots$$
  
$$Y_d = g_d (X_1, \dots, X_d)$$

2. Write down the set of inverse transformation functions  $g_1^{-1}, \ldots, g_d^{-1}$ 

$$X_{1} = g_{1}^{-1} (Y_{1}, \dots, Y_{d})$$
  
:  
$$X_{d} = g_{d}^{-1} (Y_{1}, \dots, Y_{d})$$

- 3. Consider the joint support of the new variables,  $\mathbb{Y}^{(k)}$ .
- 4. Compute the Jacobian of the transformation: first form the matrix of partial derivatives

$$D_{y} = \begin{bmatrix} \frac{\partial x_{1}}{\partial y_{1}} & \frac{\partial x_{1}}{\partial y_{2}} & \cdots & \frac{\partial x_{1}}{\partial y_{d}} \\ \frac{\partial x_{2}}{\partial y_{1}} & \frac{\partial x_{2}}{\partial y_{2}} & \cdots & \frac{\partial x_{2}}{\partial y_{d}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_{d}}{\partial y_{1}} & \frac{\partial x_{d}}{\partial y_{2}} & \cdots & \frac{\partial x_{d}}{\partial y_{d}} \end{bmatrix}$$

where, for each (i, j)

$$\frac{\partial x_i}{\partial y_j} = \frac{\partial}{\partial y_j} \left\{ g_i^{-1} \left( y_1, \dots, y_d \right) \right\}$$

and then set  $|J(y_1,\ldots,y_d)| = |\det D_y|$ 

Note that

$$\det D_y = \det D_y^\top$$

so that an alternative but equivalent Jacobian calculation can be carried out by forming  $D_y^{\top}$ . Note also that

$$|J(y_1,...,y_d)| = \frac{1}{|J(x_1,...,x_d)|}$$

where  $J(x_1, \ldots, x_d)$  is the Jacobian of the transformation regarded in the reverse direction (that is, if we start with  $(Y_1, \ldots, Y_d)$  and transform to  $(X_1, \ldots, X_d)$ )

5. Write down the joint pdf of  $(Y_1, \ldots, Y_d)$  as

$$f_{Y_1,\dots,Y_d}(y_1,\dots,y_d) = f_{X_1,\dots,X_d}\left(g_1^{-1}(y_1,\dots,y_d),\dots,g_d^{-1}(y_1,\dots,y_d)\right) \times |J(y_1,\dots,y_d)|$$
  
for  $(y_1,\dots,y_d) \in \mathbb{Y}^{(k)}$ 

• **Expectations:** If g(.) is some *k*-dimensional function, then

$$\mathbb{E}_{\mathbf{X}}[g(\mathbf{X})] = \mathbb{E}_{X_1,\dots,X_d}[g(X_1,\dots,X_d)] = \int \cdots \int g(x_1,\dots,x_d) \, dF_{X_1,\dots,X_d}(x_1,\dots,x_d)$$