The Jordan Canonical Form: Part 1

Let V be a finite-dimensional vector space over a field K and let T be a linear operator on V which satisfies a polynomial identity of the form

$$(T - a_1)^{k_1} (T - a_2)^{k_2} \cdots (T - a_m)^{k_m} = 0$$

with a_1, a_2, \ldots, a_m distinct scalars. Such an identity always exists if $K = \mathbb{C}$. In this and the following lecture we shall prove the following result

Theorem 1. There exists a basis of V such that the matrix of T is in block-diagonal form with Jordan blocks. If a is an eigenvalue of T, t the sequence $(t_0, t_1, ..., t_n, ...)$ with $t_i = \dim \ker(T-a)^i$ and

$$(s_0, s_1, \dots, s_n, \dots) = -R(L-1)^2(t)$$

where R, L are the left and right-shift operators on \mathbb{R}^{∞} , then s_i is the number of Jordan blocks of size *i* with eigenvalue *a*.

By way of an example, Let T be the linear operator on \mathbb{F}_2^6 whose matrix with respect the standard basis of \mathbb{F}_2^6 is

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

We have

It follows that $(T-1)^3 = 0$ and 1 is the only eigenvalue of T. We also have $\operatorname{rank}(T-1) = 3$, $\operatorname{rank}(T-1)^2 = 1$, $\operatorname{rank}(T-1)^3 = 0$ so that

$$t_1 = \dim \ker(T-1) = 3, \ t_2 = \dim \ker(T-1)^2 = 5, \ t_3 = \dim \ker(T-1)^3 = 6.$$

Hence t is the sequence (0, 3, 5, 6, 6, ..., 6, ...). Now

$$(L-1)(t) = (3, 2, 1, 0, 0, ..., 0, ...), \quad (L-1)^2(t) = (-1, -1, -1, 0, 0, ..., 0, ...)$$

and so $-R(L-1)^2(t) = (0, 1, 1, 1, 0, 0, ..., 0, ...)$ which, according to Theorem 1, implies that there is one Jordan block of size 1, one of size 2 and one of size 3. Hence there is a basis of \mathbb{F}_2^6 such that the matrix of T with respect to this basis is

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

If W is a T-invariant subspace of V and $f = (f_1, f_2, ..., f_n)$ is a basis of W, the matrix (with respect to this basis) of the restriction of T to W is the Jordan matrix $J_n(a)$ iff

$$T(f_1) = af_1, \ T(f_2) = af_2 + f_1, \dots, T(f_i) = af_i + f_{i-1}, \dots, T(f_n) = af_n + f_{n-1}$$

or, equivalently,

$$(T-a)(f_1) = 0, \ (T-a)(f_2) = f_1, ..., (T-a)(f_i) = f_{i-1}, ..., (T-a)(f_n) = f_{n-1}.$$

For such a basis we have $f_i = (T-a)^{n-i}(f_n)$ with $f_n \in \text{Ker}((T-a)^n) - \text{Ker}((T-a)^{n-1})$. Conversely, if $g \in \text{Ker}((T-a)^n) - \text{Ker}((T-a)^{n-1})$ the sequence

$$g, (T-a)(g), (T-a)^2(g), ..., (T-a)^{n-1}(g)$$

is a basis for a T-invariant subspace of V such that the matrix of this mapping with respect to the basis

$$f_1 = (T-a)^{n-1}(g), \ f_2 = (T-a)^{n-2}(g), ..., (T-a)(g), g$$

is the Jordan matrix $J_n(a)$. The vector g is called a **cyclic vector of cycle length n** for the eigenvalue a. Each Jordan block corresponds a cyclic vector. The subspace generated by a cyclic vector g and its images under the powers of T is called the **cyclic subspace generated by** g.

We now illustrate how to find cyclic vectors that give a decomposition into a direct sum of cyclic subspaces in the case of Example 1. We first find bases for $\ker(T-1)$, $\ker(T-1)^2$, $\ker(T-1)^3$:

$$\begin{split} & \operatorname{Ker}(T-1) = \operatorname{Span}(e_1, e_3 + e_4, e_2 + e_3 + e_5 + e_6), \\ & \operatorname{Ker}((T-1)^2) = \operatorname{Span}(e_1, e_2, e_5, e_3 + e_4, e_3 + e_6), \\ & \operatorname{Ker}((T-1)^3) = \operatorname{Span}(e_1, e_2, e_3, e_4, e_5, e_6). \end{split}$$

The next step is to complete the basis of $\text{Ker}(T-1)^2$ to a basis of $(T-1)^3$. We find that $g_1 = e_6$ completes the given basis of $\text{Ker}((T-1)^2)$ to a basis of $\text{Ker}((T-1)^3)$. Now $(T-1)(e_6) = e_2 + e_3 + e_4$ is in the kernel of $(T-1)^2$ but not in the kernel of T-1. Thus

$$e_1, e_3 + e_4, e_2 + e_3 + e_5 + e_6, e_2 + e_3 + e_4$$

is linearly independent and we can complete this sequence to a basis of $\text{Ker}((T-1)^2)$ with the vector $g_2 = e_5$. Now $(T-1)^2(g_1) = e_1, (T-1)(g_2) = e_3 + e_4$ are in the kernel of T-1 and are linearly independent. We complete these two vectors to a basis of ker(T-1) by means of the vector $g_3 = e_2 + e_3 + e_5 + e_6$. Now, the sequence of vectors

$$g_1 = e_6, \ (T-1)(g_1) = e_2 + e_3 + e_4, \ (T-1)^2(g_1) = e_1,$$

$$g_2 = e_5, \ (T-1)(g_2) = e_3 + e_4, \ g_3 = e_2 + e_3 + e_5 + e_6$$

is linearly independent and the basis

$$f_1 = g_3, f_2 = (T-1)(g_2), f_3 = g_2, f_4 = (T-1)^2(g_1), f_5 = (T-1)(g_1), f_6 = g_1$$

yields the above Jordan canonical form for T. If $v_1, v_2, ..., v_n \in V$ and W is a subspace of V, we say

that the sequence $v_1, v_2, ..., v_n$ is linearly independent mod W if

$$a_1v_1 + a_2v_2 + \dots + a_nv_n \in W \implies a_1 = a_2 = \dots = a_n = 0.$$

This is equivalent to saying the the images of the vectors v_i in the quotient space V/W form a linearly independent sequence. Similarly, we say that $v_1, v_2, ..., v_n$ generate $V \mod W$ if every $v \in V$ can be written in the form $v = a_1v_1 + a_2v_n + \cdots + a_nv_n$ with $w \in W$. This is equivalent to saying that the images of the vectors v_i in V/W span V/W.

Lemma 2. If $Ker((T-a)^i) = Ker((T-a)^{i+1})$ then $Ker((T-a)^{i+1}) = Ker((T-a)^{i+2})$.

Proof. Let $v \in \operatorname{Ker}((T-a)^{i+2})$. Then $(T-a)(v) \in \operatorname{Ker}((T-a)^{i+1}) = \operatorname{Ker}((T-a)^i)$ which implies that $(T-a)^{i+1}(v) = (T-a)^i(T-a)(v) = 0$ and hence that $v \in \operatorname{Ker}((T-a)^{i+1})$. \Box

This lemma shows that, for an eigenvalue a of T, there is an integer p > 0 such that

$$0 = t_0 < t_1 < \dots < t_p = t_{p+1} = t_{p+2} = \dots ,$$

where $t_i = \dim(T-a)^i$.

Lemma 3. If $i \ge 2$ and $v \in Ker((T-a)^i) - Ker((T-a)^{i-1})$ then

$$(T-a)(v) \in \operatorname{Ker}((T-a)^{i-1}) - \operatorname{ker}((T-a)^{i-2}).$$

Proof. If $v \in \text{Ker}((T - a)^i)$ and $(T - a)(v) \in \text{Ker}((T - a)^{i-2})$ then

$$(T-a)^{i-1}(v) = (T-a)^{i-2}(T-a)(v) = 0$$

which implies that $v \in \text{Ker}((T - a)^{i-1})$.

This Lemma is simply the assertion that the linear mapping

$$S_{i-1} : \operatorname{Ker}((T-a)^{i}) / \operatorname{Ker}((T-a)^{i-1}) \to \operatorname{Ker}((T-a)^{i-1}) / \operatorname{Ker}((T-a)^{i-2})$$

defined by $S_{i-1}(v + \text{Ker}((T - a)^{i-1}) = (T - a)(v) + \text{Ker}((T - a)^{i-1})$ is injective. This yields the following result:

Lemma 4. If $i \ge 2$ and $v_1, v_2, ..., v_n \in \text{Ker}(T-a)^i$ is linearly independent mod $\text{Ker}((T-a)^{i-1})$ then $(T-a)(v_1), \ (T-a)(v_2), ..., (T-a)(v_n) \in \text{Ker}((T-a)^{i-1})$

is a linearly independent sequence mod $\operatorname{Ker}((T-a)^{i-2})$.

If $r = (r_0, r_1, ..., r_i, ...) = (L - 1)(t)$ then

$$r_i = \dim(\operatorname{Ker}(T-a)^{i+1}) - \dim(\operatorname{Ker}(T-a)^i) = \dim(\operatorname{Ker}((T-a)^{i+1})/\operatorname{Ker}((T-a)^i).$$

Lemma 2 shows that r is a decreasing sequence of natural numbers which are zero for i > p, i.e.,

 $r_0 \ge r_1 \ge r_2 \ge \dots \ge r_p = r_{p+1} = r_{p+2} = \dots = 0.$

Theorem 1 states that the number of Jordan blocks of size $i \ge 1$ is

$$-(r_i - r_{i-1}) = r_{i-1} - r_i = \dim(\operatorname{Ker}((T-a)^i) / \operatorname{Ker}((T-a)^{i-1}) - \dim(\operatorname{Ker}((T-a)^{i+1}) / \operatorname{Ker}((T-a)^i)))$$