

MATH 579 - ASSIGNMENT 2

Posted Mar 4th 2012
Due Mar 13th 2012

Write the following assignment using \LaTeX or the (very easy to use) \LaTeX editor: LyX available for free at <http://www.lyx.org/>

1. LINEAR ADVECTION EQUATION

Consider the linear advection equation (in 1D),

$$\begin{aligned}u_t + u_x &= 0 \\ u(x, t = 0) &= u_0(x)\end{aligned}$$

with $x \in [0, 2\pi]$ periodic, and $t \in]0, T]$.

- (1) Find the solution at $T = 1$.
- (2) Consider $u_0(x) = \cos(x)$. Implement (e.g. using Matlab) each of the following scheme. For each scheme, state (or derive) the expected GTE and verify it by producing a convergence plot (use the l_1, l_2 , and the l_∞ norm).
 - (a) Lax-Friedrichs
 - (b) Lax-Wendroff
 - (c) RK3-TVD - WENO5
- (3) Repeat the above question using,

$$u_0(x) = \begin{cases} 1, & x < \frac{\pi}{4} \\ 2, & \frac{\pi}{4} \leq x < \frac{\pi}{2} \\ 1, & x \geq \frac{\pi}{2} \end{cases}.$$

- (4) From the 2 questions above, you have 6 set of convergence plots (6×3 curves total). Explain the differences in a concise and synthetic way.

2. LINEAR ADVECTION EQUATION - SEMI-LAGRANGIAN APPROACH

The semi-Lagrangian approach discussed in class consisted in tracing back the characteristics in time (from $t + \Delta t$ to t). the intersection of the characteristics with time level t defines the foot-points. This leads naturally to an interpolation problem since the foot point is not *in general* located on a grid point.

Assuming that $\Delta t = 0.5\Delta x$, trace the characteristics from the point x_j^{n+1} to the foot point x_0 . The foot-point will fall in the neighborhood of x_j^n .

- (1) Consider linear interpolation, quadratic interpolation (using and additional point to the left), and quadratic interpolation (using and additional point to the right) and write the equivalent finite-difference scheme, i.e. $u_j^{n+1} = \dots$.
- (2) Consider now a high-order (i.e. higher than quadratic) interpolation. Write the equivalent finite-difference scheme, study its stability and accuracy.

- (3) Code and test the scheme obtained in question (2) in the same way you studied the schemes in Problem (1) for the same initial conditions ($u_0(x) = \cos(x)$, and $u_0(x) = \begin{cases} 1, & x < \frac{\pi}{4} \\ 2, & \frac{\pi}{4} \leq x < \frac{\pi}{2} \\ 1, & x \geq \frac{\pi}{2} \end{cases}$.) What can you conclude?
- (4) (Bonus question) Come up with another interpolation scheme that will allow to achieve high order for the box initial condition above. Code it and produce a convergence plot that demonstrate that.