

*Derivative operators with non-local boundary conditions:*  
*Pseudospectral approximation of eigenvalues*

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## Outline of talk - part I

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The “prototype” problem:

- from a retarded functional differential equation...
- ...to a derivative operator  $\mathcal{A}$  with boundary conditions
- asymptotic stability and eigenvalues of  $\mathcal{A}$

## Outline of talk - part II

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Derivative operators with non-local boundary conditions:

- linear autonomous differential systems with multiple discrete and distributed delays
- linear autonomous neutral retarded functional differential equations
- linear abstract functional differential equations
- age-structured population models
- mixed-type functional differential equations

## Outline of talk - part III

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### Numerical methods:

- general structure
- pseudospectral differencing approach
- convergence analysis
- numerical results
- conclusions

## Collaboration

Research activity with

**R. Vermiglio** - Università di Udine

**S. Maset** - Università di Trieste

## I - RFDEs

*“A retarded functional differential equation (RFDE) consists of a **rule to extend** the initial function beyond its original domain of definition”*

[Diekmann *et al*, 1994]

## I - The prototype problem

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- consider the initial value problem for the linear autonomous RFDE

$$\begin{cases} x'(t) = L_0 x(t) + L_1 x(t - \tau), & L_0, L_1 \in \mathbb{C}^{m \times m}, \quad t \geq 0 \\ x(t) = \phi(t), & \phi \in \mathcal{C}, \quad t \in [-\tau, 0] \end{cases}$$

- constant delay  $\tau > 0$



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From a dynamical system point of view:

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$$x_t(\theta) := x(t + \theta), \quad \theta \in [-\tau, 0]$$

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- state space:  $\mathcal{C}$
- state at time  $t \geq 0$ :  $x_t \in \mathcal{C}$

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- analyze behavior of solution following time evolution of initial state in  $\mathcal{C}$
- description by the **abstract Cauchy problem**

$$\begin{cases} \frac{d}{dt}u(t) = \mathcal{A}u(t), & t > 0 \\ u(0) = \phi, \end{cases}$$

where...

# I - derivative operator with boundary conditions

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- ... $\mathcal{A} : D(\mathcal{A}) \subset \mathcal{C} \rightarrow \mathcal{C}$  linear unbounded operator

$$\mathcal{A}\psi = \psi' \text{ shift} = \text{derivative}$$

$$D(\mathcal{A}) = \left\{ \psi \in \mathcal{C} \mid \psi' \in \mathcal{C}, \quad \psi'(0) = L_0\psi(0) + L_1\psi(-\tau) \right\}$$

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**NOTE:**  $\mathcal{A}$  is the **infinitesimal generator** of the  $\mathcal{C}_0$ -semigroup  $\{T(t)\}_{t \geq 0}$  of linear bounded operators on  $\mathcal{C}$  where  $T(t)$  is the **solution operator** associated to the problem and defined by  $T(t)\varphi = x_t, t \geq 0$

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- $\lambda$  is **eigenvalue** of  $\mathcal{A}$  iff there exists **eigenvector**  $\psi \in D(\mathcal{A}) \setminus \{0\}$  st  $(\lambda, \psi)$  satisfies the **characteristic equation**

$$\lambda \in \sigma(\mathcal{A}), \psi \in M_\lambda \Leftrightarrow \mathcal{D}(\lambda)\psi = 0$$

## I - Prototype problem: characteristic equation

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- i.e. there exists  $\psi(0) \in \mathbb{C}^m \setminus \{0\}$  such that

$$(\lambda I - L_0 - L_1 e^{-\lambda\tau}) \psi(0) = 0$$



$$\det(\lambda I - L_0 - L_1 e^{-\lambda\tau}) = 0$$

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Let  $\rho$  be the smallest real number such that

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The zero solution is asymptotically stable iff  $\rho < 0$

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*This theory represents an important mathematical tool to investigate the behavior of solutions of **more general classes** of linear autonomous RFDEs and other types of functional differential systems.*

## II - Delay differential equations (DDEs)

Let  $\mathcal{C} = C([- \tau, 0], \mathbb{C}^m)$  and consider the linear autonomous system of DDEs

$$x'(t) = \mathcal{L}(x_t), \quad t \geq 0,$$

with  $\mathcal{L} : \mathcal{C} \rightarrow \mathbb{C}^m$  given by

$$\mathcal{L}(\psi) = L_0\psi(0) + \sum_{l=1}^k \left( L_l\psi(-\tau_l) + \int_{-\tau_{l-1}}^{-\tau_l} M_l(\theta)\psi(\theta)d\theta \right)$$

with  $0 = \tau_0 < \dots < \tau_k = \tau$ ,  $L_l \in \mathbb{C}^{m \times m}$  and  $M_l : [-\tau_{l-1}, -\tau_l] \rightarrow \mathbb{C}^{m \times m}$  suff. smooth for  $l = 1, \dots, k$

## II - DDEs

- **State space:**  $\mathcal{C}$  with supremum norm
- **State:**  $x_t \in \mathcal{C}, \quad t \geq 0$
- **Operator:**  $\mathcal{A} : D(\mathcal{A}) \subset \mathcal{C} \rightarrow \mathcal{C}$  given by

$$\mathcal{A}\psi = \psi'$$

$$D(\mathcal{A}) = \left\{ \psi \in \mathcal{C} \mid \psi' \in \mathcal{C}, \psi'(0) = \mathcal{L}(\psi) \right\}$$

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**NOTE:**  $\mathcal{A}$  is the **infinitesimal generator** of the  $\mathcal{C}_0$ -semigroup  $\{T(t)\}_{t \geq 0}$  of **solution operators** on  $\mathcal{C}$  given by  $T(t)x_0 = x_t, t \geq 0$



## II - Neutral RFDEs

Let  $\mathcal{C} = C([- \tau, 0], \mathbb{C}^m)$  and consider the linear autonomous system of neutral RFDEs

$$\frac{d}{dt} [x(t) + \mathcal{N}(x_t)] = \mathcal{L}(x_t), \quad t \geq 0,$$

with  $\mathcal{N}, \mathcal{L} : \mathcal{C} \rightarrow \mathbb{C}^m$  continuous, linear and  $\mathcal{N}$  atomic at zero given by

$$\mathcal{N}(\psi) = \int_{-\tau}^0 d\eta(\theta)\psi(\theta), \quad \mathcal{L}(\psi) = \int_{-\tau}^0 d\mu(\theta)\psi(\theta)$$

where  $\eta, \mu$  have not singular part

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## II - Abstract FDEs

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Let  $X$  and  $\mathcal{C} = C([- \tau, 0], X)$  be Banach spaces and consider the system of linear abstract FDEs

$$\frac{dx(t)}{dt} = \mathcal{A}_T x(t) + \mathcal{L}(x_t), \quad t \geq 0,$$

where  $\mathcal{A}_T : D(\mathcal{A}_T) \subset X \rightarrow X$  is the infinitesimal generator of a  $\mathcal{C}_0$ -semigroup of linear bounded operators on  $X$  and  $\mathcal{L} : \mathcal{C} \rightarrow X$  is a linear mapping

## II - Abstract FDEs

- **State space:**  $\mathcal{C}$  with supremum norm

$$\|\psi\| = \sup_{\theta \in [-\tau, 0]} |\psi(\theta)|, \quad |\cdot| \text{ norm of } X$$

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NOTE:  $\mathcal{A}$  is the **infinitesimal generator** of...

## II - Age-structured population models

Let  $\mathcal{C} = C([0, a_+], \mathbb{C}^m)$  and consider the age-structured population model

$$\begin{cases} \frac{\partial x}{\partial t}(a, t) + \frac{\partial x}{\partial a}(a, t) = 0, & a \in [0, a_+], \quad t \geq 0, \\ x(0, t) = Kx(\cdot, t), & t \geq 0, \\ x(a, 0) = \varphi(a), & a \in [0, a_+], \end{cases}$$

where  $x \in C([0, a_+] \times [0, +\infty), \mathbb{C}^m)$ ,  $\varphi \in \mathcal{C}$  and  $K : \mathcal{C} \rightarrow \mathbb{C}^m$ :

$$K\psi = \sum_{l=1}^d \int_{a_{l-1}}^{a_l} k^{(l)}(a)\psi(a)da, \quad 0 = a_0 < a_1 < \cdots < a_d = a_+,$$

with sufficiently smooth matrix kernels  $k^{(l)}$ ,  $l = 1, \dots, d$

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## II - Mixed-type FDEs

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Let  $\mathcal{C} = C([-p, q], \mathbb{C}^m)$ ,  $p, q > 0$ , and consider the system of linear autonomous FDEs of mixed-type (i.e. advanced and retarded)

$$\frac{dx(t)}{dt} = \int_{-p}^q dk(\theta)x(t + \theta),$$

where  $x(t) \in \mathbb{C}^m$  and  $dk(\theta)$  is an  $m \times m$  matrix of Lebesgue-Stieltjes measures on  $[-p, q]$ .

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Although such equations do not generate semigroups, it is still useful to take...

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NOTE: under suitable hypothesis on  $\sigma(\mathcal{A})$ ,  $\mathcal{A}$  is **exponential dichotomous**, i.e. there exists a direct sum  $\mathcal{C} = P \oplus Q$ , such that  $\mathcal{A}_P : D(\mathcal{A}) \cap P \rightarrow P$ ,  $\mathcal{A}_Q : D(\mathcal{A}) \cap Q \rightarrow Q$  are infinitesimal generators of (exp.ly stable) semigroups.

### III - General structure

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- asymptotic behavior of solutions depends on the position on  $\mathbb{C}$  of the eigenvalues of a derivative operator  $\mathcal{A}$
- $\mathcal{A}$  has non-local boundary conditions contained in its domain



### III - General structure

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- **State space:**  $\mathcal{C} := C([\alpha, \beta], X)$  with supremum norm

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- **Derivative operator:**  $\mathcal{A} : D(\mathcal{A}) \subset \mathcal{C} \rightarrow \mathcal{C}$  given by

$$\mathcal{A}\psi = (\pm)\psi'$$

$$D(\mathcal{A}) = \left\{ \psi \in \mathcal{C} \mid \psi' \in \mathcal{C}, \right.$$

$$\left. \psi'(\bar{\theta}) + \mathcal{N}(\psi') = \mathcal{L}(\psi) \text{ or } \psi(\bar{\theta}) = \mathcal{L}(\psi) \right\}$$

with  $\bar{\theta} \in [\alpha, \beta]$  and  $\mathcal{L}, \mathcal{N} : \mathcal{C} \rightarrow X$  linear

### III - Infinite dimension

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- need of numerical approximation

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- **Proposal:** discretize  $\mathcal{A}$  into  $\mathcal{A}_N$  by **pseudospectral differencing methods:**
  - approximate functions of  $\mathcal{C}$  by interpolating polynomials on certain nodes
  - approximate exact derivative with that of interpolating polynomials
  - use boundary condition applied to the polynomials

### III - Mesh

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Given a positive integer  $N$ , discretize  $[\alpha, \beta]$  with the mesh

$$\Omega_N = \{\theta_i \mid i = 0, \dots, N\}$$

of  $N + 1$  distinct points

### III - State space

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- replace the continuous space  $\mathcal{C}$  by the space  $\mathcal{C}_N = (\mathbb{C}^m)^{\Omega_N} \cong \mathbb{C}^{m(N+1)}$  of the discrete functions defined on the mesh  $\Omega_N$

### III - State space

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- replace the continuous space  $\mathcal{C}$  by the space  $\mathcal{C}_N = (\mathbb{C}^m)^{\Omega_N} \cong \mathbb{C}^{m(N+1)}$  of the discrete functions defined on the mesh  $\Omega_N$
- i.e. any  $\psi \in \mathcal{C}$  is discretized into the block-vector  $x \in \mathcal{C}_N$  of components

$$x_i = \psi(\theta_i) \in \mathbb{C}^m, \quad i = 0, \dots, N$$

### III - Operator: $\psi'(\bar{\theta}) + \mathcal{N}(\psi') = \mathcal{L}(\psi)$

---

- assume  $\bar{\theta} \in \Omega_N$ , i.e.  $\theta_{\bar{i}} = \bar{\theta}$  for some  $\bar{i} \in \{0, 1, \dots, N\}$

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- assume  $\bar{\theta} \in \Omega_N$ , i.e.  $\theta_{\bar{i}} = \bar{\theta}$  for some  $\bar{i} \in \{0, 1, \dots, N\}$
- let  $\mathcal{P}_N x$ ,  $x \in \mathcal{C}_N$ , be the unique  $\mathbb{C}^m$ -valued **interpolating polynomial of degree  $\leq N$**  such that

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$$\begin{cases} (\mathcal{A}_N x)_{\bar{i}} = \mathcal{L}_N(\mathcal{P}_N x) - \mathcal{N}_N((\mathcal{P}_N x)') \\ (\mathcal{A}_N x)_i = (\mathcal{P}_N x)'(\theta_i), \quad i = 0, 1, \dots, N, \quad i \neq \bar{i} \end{cases}$$

with  $\mathcal{L}_N$  and  $\mathcal{N}_N$  possibly approximating  $\mathcal{L}$  and  $\mathcal{N}$



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- use Lagrange representation

$$(\mathcal{P}_N x)(\theta) = \sum_{j=0}^N l_j(\theta) x_j, \quad \theta \in [\alpha, \beta],$$

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$$\left\{ \begin{array}{l} (\mathcal{P}_N x)'(\theta_{\bar{i}}) = \sum_{j=0}^N (\mathcal{L}_N ((l_j(\cdot)I) - \mathcal{N}_N ((l'_j(\cdot)I))) x_j \\ (\mathcal{P}_N x)'(\theta_i) = \sum_{j=0}^N l'_j(\theta_i) x_j, \quad i = 0, 1, \dots, N, \quad i \neq \bar{i} \end{array} \right.$$

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### III - Convergence assumptions

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- possibly assume

$$\sup_{N \in \mathbb{N}} \|\mathcal{L}_N\| < +\infty$$

and

$$\sup_{N \in \mathbb{N}} \|\mathcal{N}_N\| < +\infty$$

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- $\mathcal{A}_N$  has  $\nu$  eigenvalues  $\lambda_i, i = 1, \dots, \nu$ , such that

$$\max_{i=1, \dots, \nu} |\bar{\lambda} - \lambda_i| \leq C_2^{1/\nu} \left( \varepsilon_N(\mathcal{L}) + \varepsilon_N(\mathcal{N}) + \frac{1}{\sqrt{N}} \left( \frac{C_1}{N} \right)^N \right)^{1/\nu}$$

$$\varepsilon_N(\mathcal{L}) = \sup_{\lambda \in B(\bar{\lambda}, r)} \frac{|\mathcal{L}(e^{-\lambda \cdot u}) - \mathcal{L}_N(e^{-\lambda \cdot u})|}{|u|}, \quad u \in \mathbb{C}^m$$

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- $C_1 = C_1(\bar{\lambda}), C_2 = C_2(\bar{\lambda})$  constants independent of  $N$

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- let  $\{\Omega_{N^{(i)}}\}_{i \geq 1}$  be a sequence of meshes on  $[\alpha, \beta]$  such that  $N^{(i)} \rightarrow \infty$  as  $i \rightarrow \infty$
- if  $\lambda^{(i)} \rightarrow \bar{\lambda}$  as  $i \rightarrow \infty$  for  $\lambda^{(i)}$  eigenvalue of  $\mathcal{A}_N^{(i)}$ , then  $\bar{\lambda}$  is eigenvalue of  $\mathcal{A}$

### III - Results: DDEs

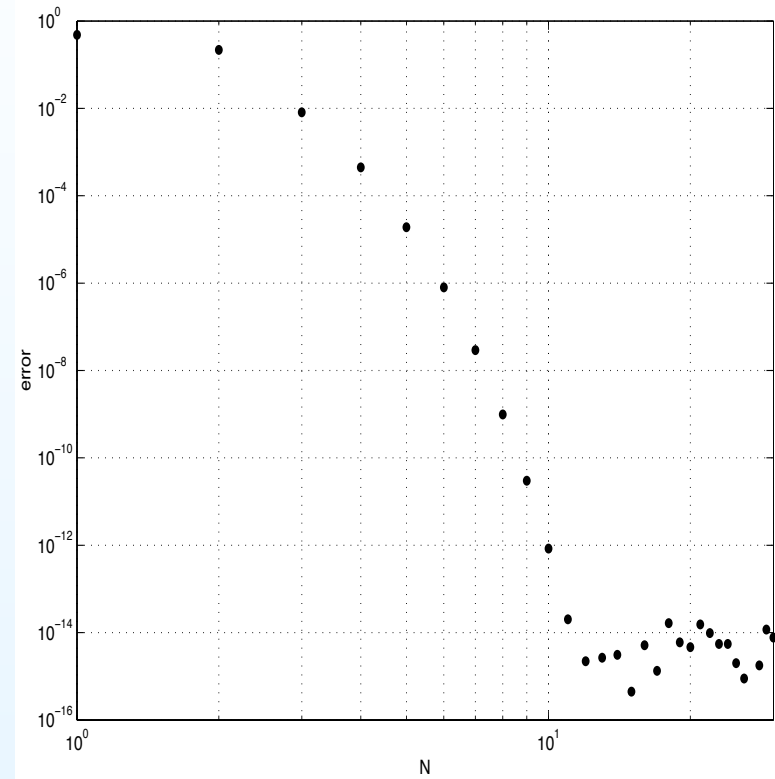
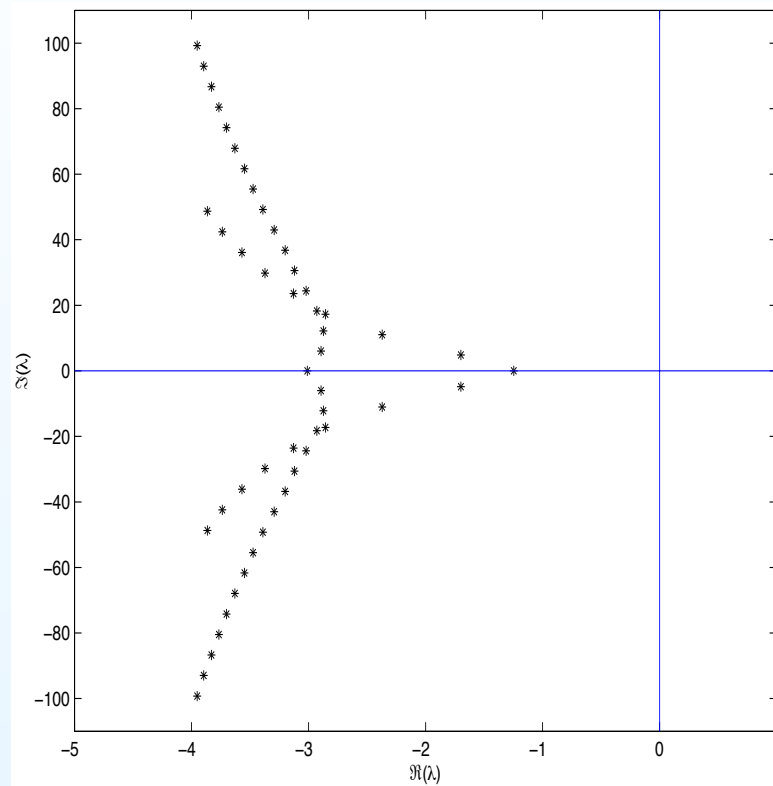
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$$x'(t) = L_0x(t) + L_1x(t-1) + \int_{-0.3}^{-0.1} M_1x(t+\theta)d\theta + \int_{-1}^{-0.5} M_2x(t+\theta)d\theta$$

$$L_0 = \begin{pmatrix} -3 & 1 \\ -24.646 & -35.430 \end{pmatrix}, \quad L_1 = \begin{pmatrix} 1 & 0 \\ 2.35553 & 2.00365 \end{pmatrix}$$

$$M_1 = \begin{pmatrix} 2 & 2.5 \\ 0 & -0.5 \end{pmatrix}, \quad M_2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

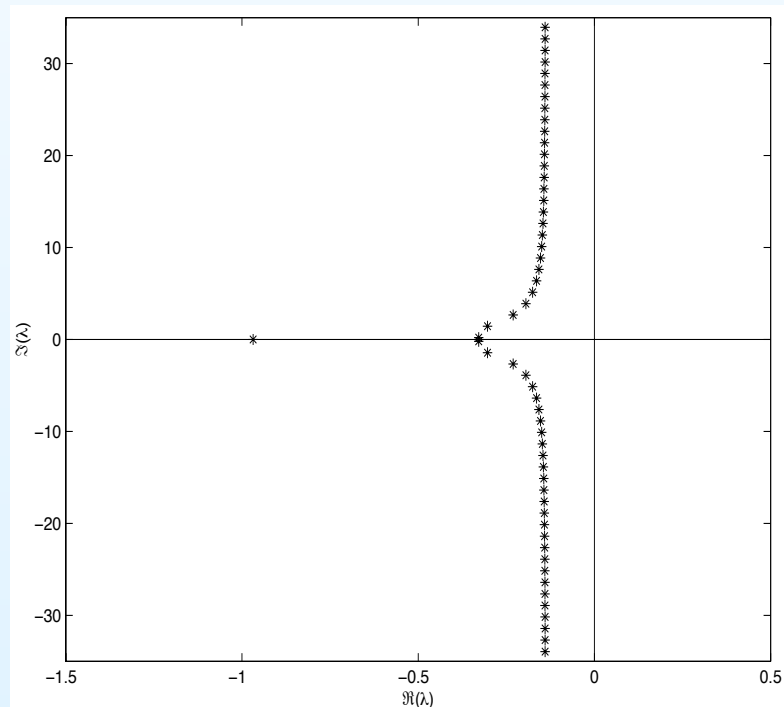
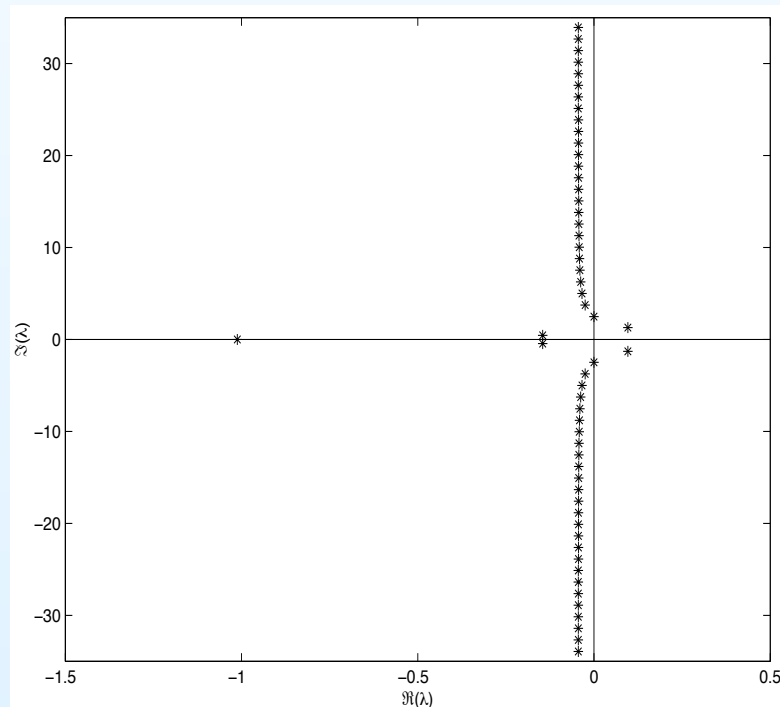
### III - Results: DDEs, spectrum and convergence



### III - Results: NDDEs, spcetrum

$$x'(t) = \begin{pmatrix} 0 & 1 \\ -a & -b \end{pmatrix} x(t) + \begin{pmatrix} 0 & 0 \\ 0 & h \end{pmatrix} x'(t - \tau)$$

$$a = 1, b = 0.5, h = 0.8, \tau = 5, \quad a = 1, b = 4, h = 0.5, \tau = 5$$



### III - Results: abstract RFDEs

---

$$\begin{cases} \frac{\partial x}{\partial t}(a, t) = \frac{\partial^2 x}{\partial a^2}(a, t) - bx(a, t) - cx(a, t - \tau), & a \in [0, \pi], \quad t > 0 \\ x(0, t) = x(\pi, t) = 0, & t \geq 0 \\ x(a, t) = \varphi(t)(a), & a \in [0, \pi], \quad t \in [-\tau, 0], \quad \varphi \in C([-\tau, 0], X) \end{cases}$$

$$X := L^2([0, \pi], \mathbb{R})$$

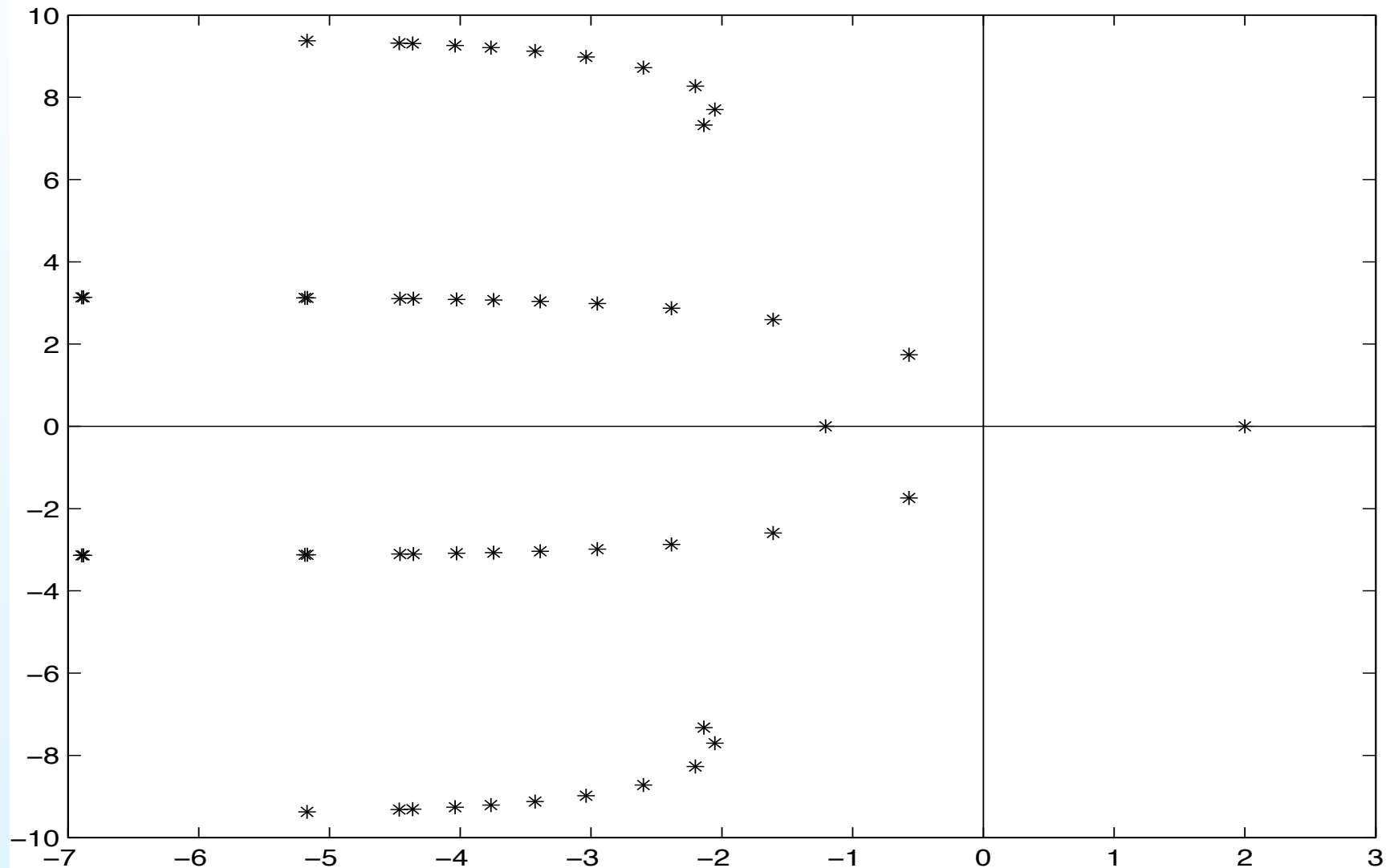
$$\mathcal{A}_T : D(\mathcal{A}_T) \subset X \rightarrow X$$

$$\mathcal{A}_T y = y''$$

$$D(\mathcal{A}_T) : \left\{ y \in C^2([0, \pi], \mathbb{R}) \mid y(0) = y(\pi) = 0 \right\}$$

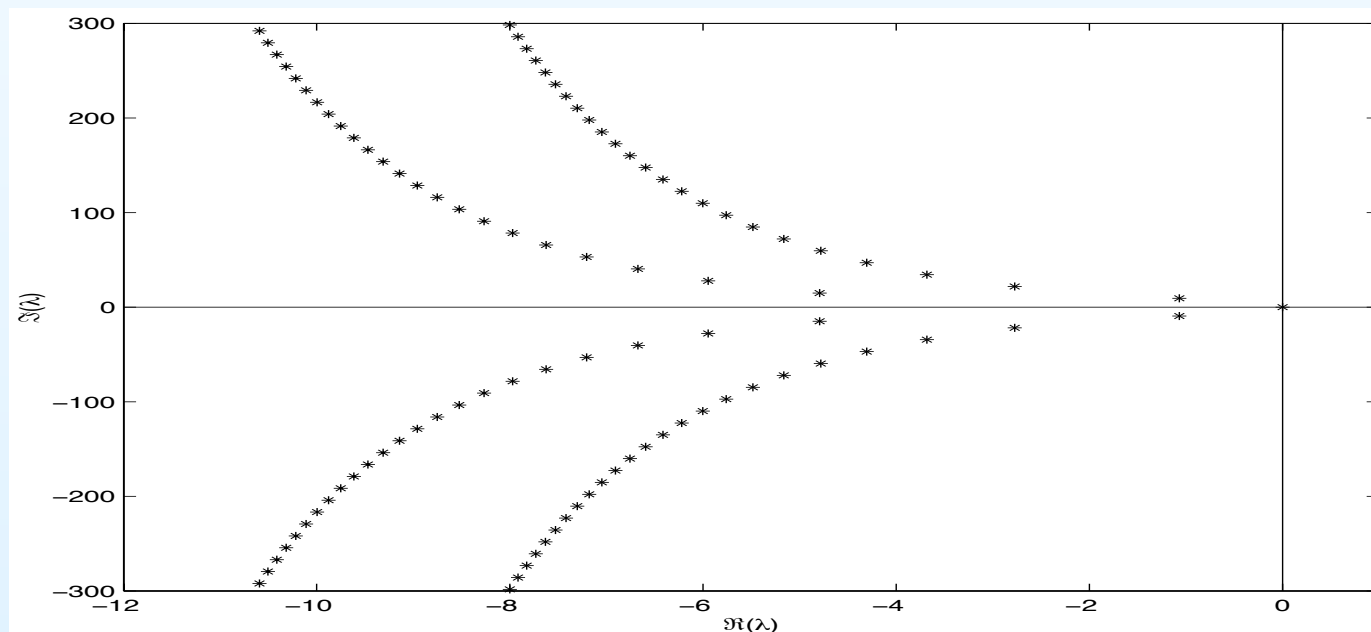
### III - Results: abstract RFDEs, spectrum

$$b = -3 - e^{-2}, c = 1, \tau = 1$$

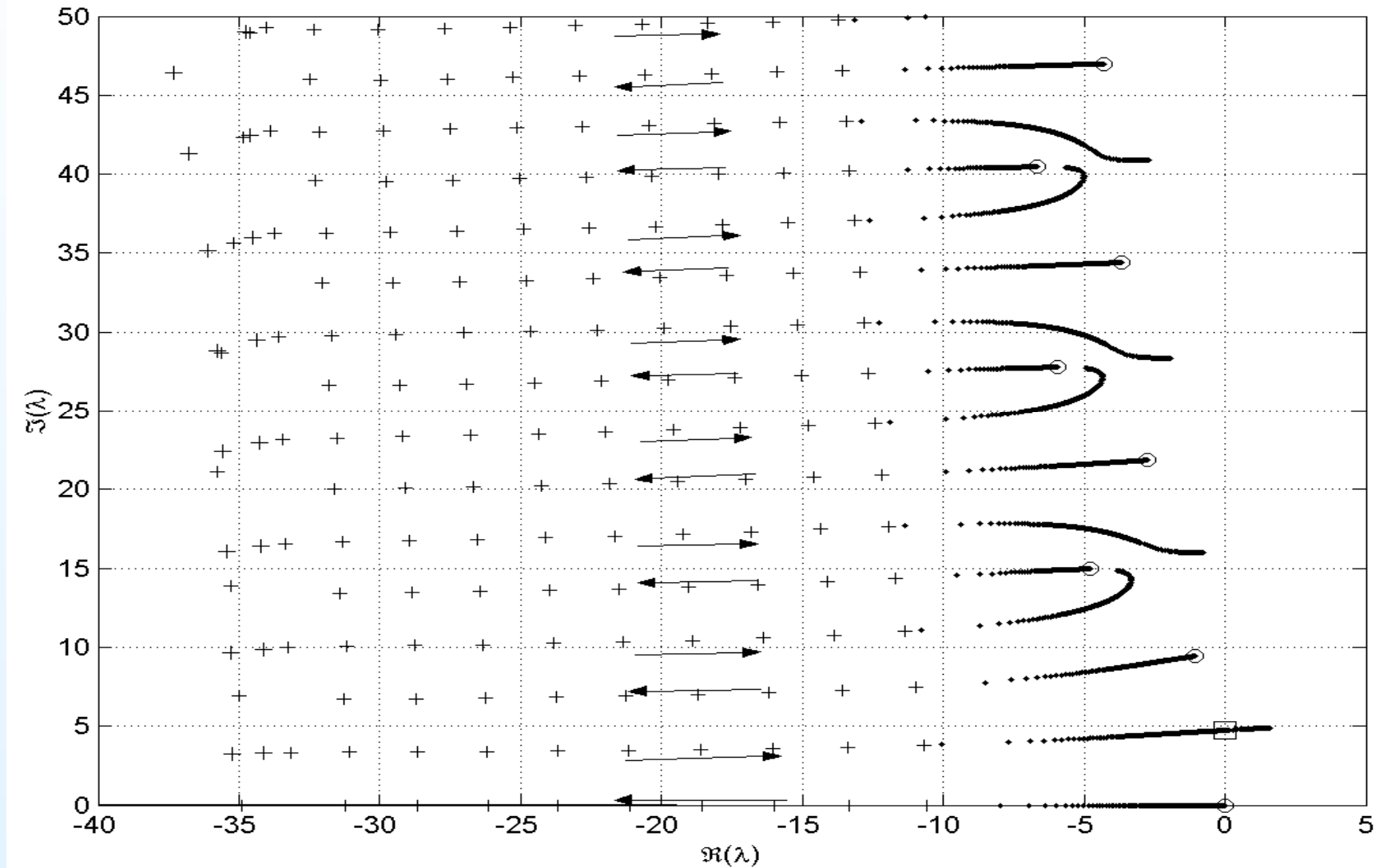


### III - Results: population model, spectrum

$$\left\{ \begin{array}{l} \frac{\partial x}{\partial t}(a, t) + \frac{\partial x}{\partial a}(a, t) = 0, \quad a \in [0, a_{\dagger}], \quad t \geq 0 \\ x(0, t) = \int_0^{a_{\dagger}} \delta [1 - \ln R_0] (1 - a) \chi_{[\frac{1}{2}, 1]}(a) x(a, t) da, \quad t \geq 0 \\ x(a, 0) = \varphi(a), \quad a \in [0, a_{\dagger}] \end{array} \right.$$



### III - Results: population model, spectrum variation

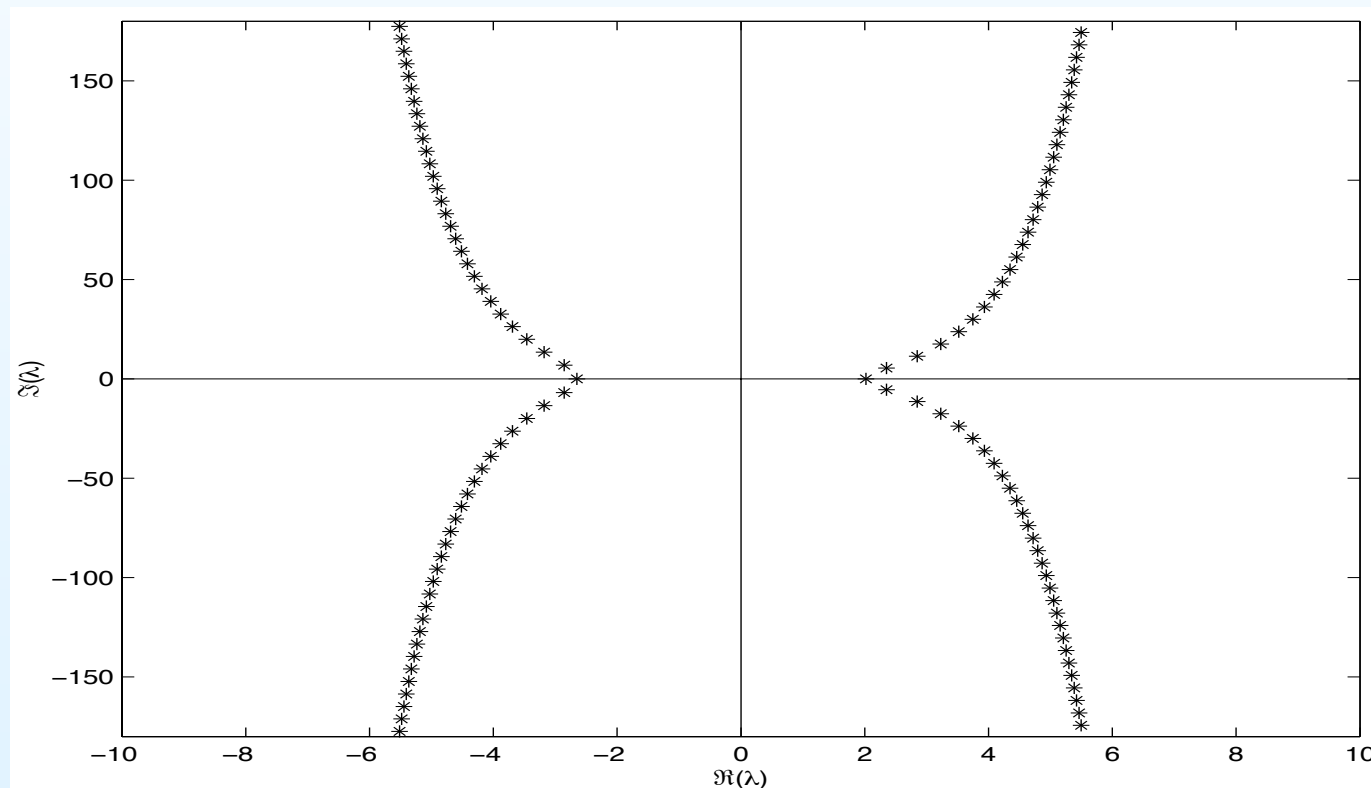




### III - Results: mixed-type RFDEs, spectrum

$$x'(t) = ax(t + 1) + bx(t) + cx(t - 1)$$

$$a = c = -0.714, \quad b = 7.5$$



### III - Results: space discretized PDE, delay in diffusion

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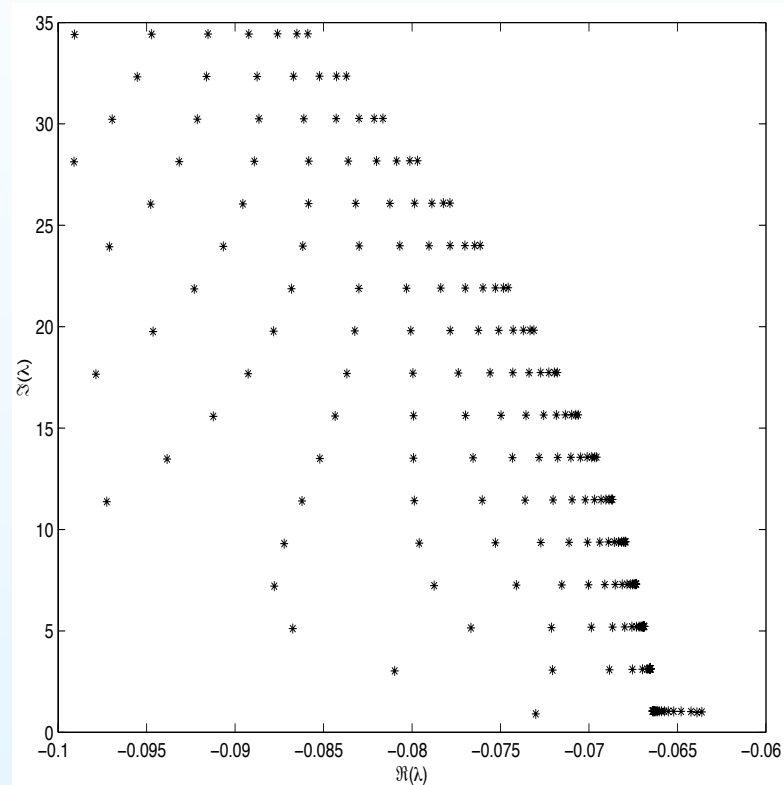
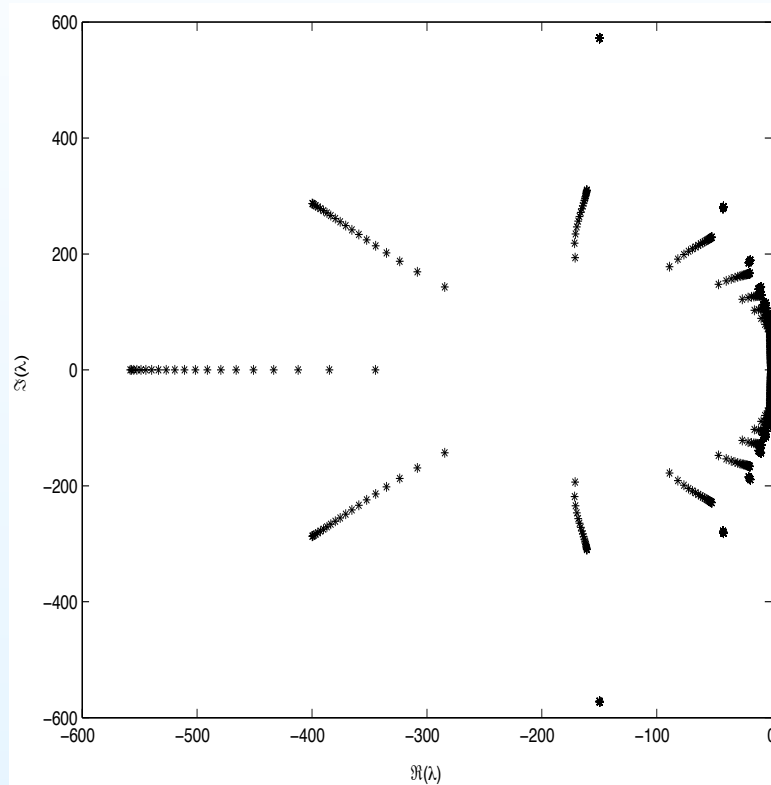
$$x'(t) = L_0 x(t) + L_1 x(t - \tau), \quad L_0, L_1 \in \mathbb{C}^{m \times m}$$

$$L_0 = \frac{1}{h^2} \left( \frac{1 - \alpha}{\beta} + \alpha \right) \begin{pmatrix} -2 & 1 & & \\ 1 & \ddots & \ddots & \\ & \ddots & \ddots & 1 \\ & & 1 & -2 \end{pmatrix} + RI_m$$

$$L_1 = \frac{1}{h^2} \frac{1 - \alpha}{\beta} \begin{pmatrix} -2 & 1 & & \\ 1 & \ddots & \ddots & \\ & \ddots & \ddots & 1 \\ & & 1 & -2 \end{pmatrix}$$

### III - Results: space discretized PDE, delay in diffusion

$$m = 20, \quad h = \frac{\pi}{m+1}, \quad \alpha = 0.1, \quad \beta = 2, \quad R = 0.08$$



## Conclusions

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- behavior of solution as time-evolution of state
- asymptotic stability depends on eigenvalues of derivative operator
- holds for more than DDEs
- $\infty$  eigenvalues: discretization via pseudospectral methods
- fast convergence

The end

*...and thanks for your attention!*