### Lattices, Travelling Waves, and Differential Equations with Retarded and Advanced Arguments

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### Lattices, Travelling Waves, and Differential Equations with retarded and advanced arguments

Many lattice differential equations appear to admit standing or travelling wave solutions. In applications (e.g., crystal growth, nerve conduction) it is important to know which occurs. However, this is a difficult question to answer, because travelling waves on lattices are defined by Advanced-Retarded Functional Differential Equations with the propagation failure limit as the wave speed vanishes being singular, whereas standing waves are defined by difference equations.



### Introduction Lattice Differential Equations

A typical LDE has the form

$$\dot{u}_i = g_i(\{u_j\}_{j \in \Lambda}), \quad i \in \Lambda.$$

 $\Lambda \subset \mathbb{R}^n$  is a lattice; a discrete subset of  $\mathbb{R}^n$ , finite or infinite number of points, regular spatial structure (eg  $\mathbb{Z}^n$ )



- $a_i(v)$  for each  $v \in \Pi$  may be cealer of vec
- Continuous in time, discrete in space
- Today will restrict attention to 1D lattices for simplicity

# Travelling Pulse Model Discrete Fitzhugh-Nagumo Equation

$$\dot{u}_i = (u_{i+1} - 2u_i + u_{i-1}) - f(u_i) - v_i$$
  
 $\dot{v}_i = b(u_i - rv_i)$ 

Models a Myelinated Nerve fibre

- lattice points *i* represent nodes of Ranvier; gaps in myelin sheath where nerve may be excited
- $u_i$  represents transmembrane potential at node *i*
- $v_i$  is a recovery variable (potassium current)

Normal myelinated Fibre [Experiment] [HUGH BOSTOCK, UNIVERSITY OF LONDON].

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# Leading Edge Model Discrete Nagumo Equation

$$\dot{u}_i = (u_{i+1} - 2u_i + u_{i-1}) - \beta f(u_i) \qquad \beta > 0,$$

Models leading edge behaviour of pulse. Two examples:





# Leading Edge Model Discrete Nagumo Equation

$$\dot{u}_i = (u_{i+1} - 2u_i + u_{i-1}) - \beta f(u_i) \qquad \beta > 0,$$

Models leading edge behaviour of pulse. Two examples:

1. Cubic nonlinearity

$$f(u) = u(u-a)(u-1)$$

[Travelling Wave Movie] [Standing Wave Movie]

2. McKean's caricature of cubic

$$f(u) = \begin{cases} u - 1, & u > a, \\ [u - 1, u], & u = a, \\ u, & u < a. \end{cases}$$

[Travelling Wave Movie] [Standing Wave Movie]

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Consider the PDE

$$u_t = u_{xx} - f(u), \quad x \in \mathbb{R},$$

with cubic nonlinearity f(u) = u(u - a)(u - 1) models leading edge behaviour of pulse in the squid giant axon.

• Homogeneous steady states satisfy f(u) = 0 implies u = 0, u = a or u = 1. Natural to look for solutions  $\lim_{x \to -\infty} u(x, t) = 0$ ,  $\lim_{x \to +\infty} u(x, t) = 1$ .

### **Travelling Wave Ansatz PDE to ODE reduction**

Travelling Wave ansatz:

• Let  $u(x,t) = \varphi(x - ct) = \varphi(\xi)$ , where c is unknown wave speed

 $u_t = u_{xx} - f(u)$ 





### **Travelling Wave Ansatz PDE to ODE reduction**

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• Let  $u(x,t) = \varphi(x - ct) = \varphi(\xi)$ , where c is unknown wave speed

$$u_t = u_{xx} - f(u) \Rightarrow -c\varphi'(\xi) = \varphi''(\xi) - f(\varphi(\xi)),$$





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- TW ansatz reduces PDE to ODE
- $\xi$  is time-like variable
- Boundary conditions  $\varphi(-\infty) = 0, \ \varphi(\infty) = 1.$
- Solutions not unique (translational invariance)

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### **Functional Differential Equation Reduction Travelling Waves for Discrete Nagumo Equation**

$$\dot{u}_i = (u_{i+1} - 2u_i + u_{i-1}) - \beta f(u_i)$$

• Travelling Wave ansatz  $u_i(t) = \varphi(i - ct) = \varphi(\xi)$  gives

 $-c\varphi'(\xi) = \varphi(\xi+1) - 2\varphi(\xi) + \varphi(\xi-1) - \beta f(\varphi(\xi))$ 





## **Functional Differential Equation Reduction Travelling Waves for Discrete Nagumo Equation**

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$$-c\varphi'(\xi) = \varphi(\xi+1) - 2\varphi(\xi) + \varphi(\xi-1) - \beta f(\varphi(\xi))$$

• 
$$i \in \mathbb{Z}$$
 but  $\xi = i - ct \in \mathbb{R}$  is time-like and  $\varphi : \mathbb{R} \to \mathbb{R}$ .

- $\varphi(\xi 1) = \text{delay}, \ \varphi(\xi + 1) = \text{advance}.$
- Both nonlinearities have three constant solutions  $\varphi \equiv 0$ , a and 1. Seek solutions with  $\varphi(-\infty) = 0$ ,  $\varphi(\infty) = 1$ .
- Propagation Failure  $c \rightarrow 0$  is singular limit
- TW ansatz "reduces" LDE to a mixed-type FDE !!

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### **Another Example Of**

#### **Mixed Type Functional Differential Equations**



[Wheeler Feynman 1945&1949],[Schild 1963],[Many Others...]

**ATEX** 

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### Nonlinear FDE BVP Existence and Uniqueness

$$-c\varphi'(\xi) = \varphi(\xi+1) - 2\varphi(\xi) + \varphi(\xi-1) - \beta\varphi(\xi)(\varphi(\xi) - a)(\varphi(\xi) - 1)$$

 $\varphi(-\infty) = 0, \quad \varphi(\infty) = 1.$ 

- [ZINNER 1991]: Uniqueness and Stability of Monotonic TWs
- [ZINNER 1992]: Existence of Monotonic TWs for  $\beta$  suff small.
- Zinner's theory covers larger class of *f*. More recent extensions include, in particular [MALLET-PARET 1999A],[MALLET-PARET 1999B].
- When is wave travelling or standing?
- Question has practical relevance to problem of waveblock in for example MS where signals fail to propagate along a demyelinated nerve.
- Solve TW equations numerically using a mixed-type DDE collocation code written for the purpose [ ABELL ET AL 2005], (built on colmod [CASH ET AL 1995]).

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#### **Nonlinear Nagumo Equation**

*a-c* curves

$$\dot{u}_i = u_{i+1} - 2u_i + u_{i-1} - \beta u_i (u_i - a) (u_i - 1), \quad \beta > 0$$
$$-c\varphi'(\xi) = \varphi(\xi + 1) - 2\varphi(\xi) + \varphi(\xi - 1) - \beta\varphi(\xi)(\varphi(\xi) - a)(\varphi(\xi) - 1),$$



$$\beta \text{ small } \Longrightarrow$$
  
 $c = 0 \iff a = 1/2 ???$ 

 $\beta$  large  $\implies$  c = 0 for growing range of a: = Propagation Failure





# **Nonlinear Nagumo Equation Evolution of Wave Profile for** $\beta = 1$ **and** $\beta = 8$ **.**



• Consider evolution of wave profile as  $c \rightarrow 0$ 

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- Consider evolution of wave profile as  $c \rightarrow 0$
- Step profile explains this
- TW equation becomes a difference equation

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**Propagation Failure & Standing Waves** c = 0: A difference Equation

$$0 = -c\varphi'(\xi) = \varphi(\xi + 1) - 2\varphi(\xi) + \varphi(\xi - 1) - \beta f(\varphi(\xi))$$
$$0 = \dot{u}_i = u_{i+1} - 2u_i + u_{i-1} - \beta f(u_i)$$

McKean's caricature of cubic

$$f(\varphi) = \begin{cases} \beta(\varphi - 1), & \varphi > a, \\ \beta[\varphi - 1, \varphi], & \varphi = a, \\ \beta\varphi, & \varphi < a. \end{cases} = \varphi - H(\varphi - a),$$

where H is heaviside function.



### **Propagation Failure & Standing Waves** c = 0: A difference Equation

$$0 = u_{i+1} - 2u_i + u_{i-1} - \begin{cases} \beta(u_i - 1), & u_i > a, \\ \beta u_i, & u_i < a. \end{cases}$$

Consider monotonic solution s.t.

$$u_i < a, \quad i < 0,$$
$$u_i > a, \quad i \ge 0.$$

$$x^{2} - (2 + \beta)x + 1 = 0 \implies x = 1 + \frac{\beta}{2} + \frac{1}{2}\sqrt{4\beta + \beta^{2}}$$

Solution:

$$u_i = \frac{x^{i+1}}{x+1}, \quad i \le 0, \qquad u_i = 1 - \frac{1}{x^i(x+1)}, \quad i \ge -1$$

valid for

$$u_{-1} = \frac{1}{1+x} < a < 1 - \frac{1}{1+x} = u_0$$

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### **Propagation Failure & Standing Waves** c = 0: A difference Equation

$$0 = -c\varphi'(\xi) = \varphi(\xi + 1) - 2\varphi(\xi) + \varphi(\xi - 1) - \beta f(\varphi(\xi))$$
  
$$0 = \dot{u}_i = u_{i+1} - 2u_i + u_{i-1} - \beta f(u_i)$$







### **Propagation Failure**

### **McKean and Cubic Nonlinearities**



**ATEX** 

• McKean:  $\forall \beta > 0 \ \exists \varepsilon > 0 : c = 0 \text{ for } a \in [1/2 - \varepsilon, 1/2 + \varepsilon]$ 

• Cubic:  $\beta \gg 0 = \text{ditto}$ 

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- Cubic:  $\beta \approx 0$ :  $\varepsilon = 0$  or  $\mathcal{O}(e^{-1/\beta})$  ???
- Why not always steps in wave profile as  $c \rightarrow 0$  ???

### Discrete Nagumo Standing Waves As Hamiltonian Discretizations

$$0 = \dot{u}_i = u_{i+1} - 2u_i + u_{i-1} - \beta f(u_i)$$

Let  $h = \sqrt{\beta}$  and  $v_{j+1} = (u_{j+1} - u_j)/h$ . Then

$$u_{j+1} = u_j + hv_{j+1}, \qquad v_{j+1} = v_j + hf(u_j)$$

Standing wave of LDE is a heteroclinic connection of this mapping between (0,0) and (1,0) in (u,v)-plane.





### Discrete Nagumo Standing Waves As Hamiltonian Discretizations

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Which is symplectic Euler applied to the Hamiltonian system

$$\dot{v} = -H_u(u, v), \qquad \dot{u} = v = H_v(u, v)$$

where

$$H(u, v) = \frac{v^2}{2} - W(u), \quad W'(u) = f(u)$$

For cubic f, W is a quartic double-well potential The standing wave is a heteroclinic connection between (u, v) = (0, 0) and (1, 0). But we can do better...

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### Discrete Nagumo Standing Waves Stormer-Verlet Discretization

$$u_{i+1} - 2u_i + u_{i-1} = h^2 f(u_i)$$

Let  $v_j = \frac{1}{2h}(u_{j+1} - u_{j-1})$  then

$$u_{j+1} = u_j + hv_j + \frac{1}{2}h^2 f(u_j), \qquad v_{j+1} = v_j + \frac{h}{2}f(u_j) + \frac{h}{2}f(u_{j+1}),$$

or

$$v_{j+\frac{1}{2}} = v_j + \frac{h}{2}f(u_j),$$
  

$$u_{j+1} = u_j + hv_{j+\frac{1}{2}},$$
  

$$v_{j+1} = v_{j+\frac{1}{2}} + \frac{h}{2}f(u_{j+1}).$$

Which is Stormer-Verlet method for  $\dot{u} = v$ ,  $\dot{v} = f(u)$ .

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### Discrete Nagumo Standing Waves Stormer-Verlet Discretization

Standing wave of LDE is a heteroclinic connection of Stormer-Verlet method

$$u_{j+1} = u_j + hv_j + \frac{1}{2}h^2 f(u_j), \qquad v_{j+1} = v_j + \frac{h}{2}f(u_j) + \frac{h}{2}f(u_{j+1}),$$

between (0,0) and (1,0) in (u,v)-plane, again applied to the Hamiltonian system

$$\dot{v} = -H_u(u, v), \qquad \dot{u} = v = H_v(u, v)$$

where

$$H(u,v) = \frac{v^2}{2} - W(u), \quad W'(u) = f(u)$$

Stormer-Verlet as well as being symplectic and explicit is also second order and symmetric.

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Recall TW for  $u_t = u_{xx} - f(u)$  given by  $u(x,t) = \varphi(x - ct) = \varphi(\xi)$  satisfying ODE

$$-c\varphi'(\xi) = \varphi''(\xi) - f(\varphi(\xi)).$$

Note standing wave c = 0 is not a singular limit





$$\varphi''(\xi) = f(\varphi(\xi)),$$

or

$$\varphi'(\xi) = \psi(\xi), \qquad \psi'(\xi) = f(\varphi(\xi)),$$

which is Hamiltonian System

$$\psi' = -H_{\varphi}(\varphi, \psi), \qquad \varphi' = \psi = H_{\psi}(\varphi, \psi)$$

where

$$H(\varphi,\psi) = \frac{\psi^2}{2} - W(\varphi), \quad W_{\varphi}(\varphi) = f(\varphi)$$

• Thus for all  $\beta > 0$  discrete Nagumo Standing Wave problem corresponds to a Stormer-Verlet discretization with  $h = \sqrt{\beta}$  of continuous Nagumo Standing Wave Problem

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$$\psi' = -H_{\varphi}(\varphi, \psi, a), \qquad \varphi' = H_{\psi}(\varphi, \psi, a)$$
$$H(\varphi, \psi, a) = \frac{\psi^2}{2} - W(\varphi, a), \qquad W_{\varphi}(\varphi, a) = f(\varphi, a)$$



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$$\psi' = -H_{\varphi}(\varphi, \psi, a), \qquad \varphi' = H_{\psi}(\varphi, \psi, a)$$
$$H(\varphi, \psi, a) = \frac{\psi^2}{2} - W(\varphi, a), \qquad W_{\varphi}(\varphi, a) = f(\varphi, a)$$







$$\psi' = -H_{\varphi}(\varphi, \psi, a), \qquad \varphi' = H_{\psi}(\varphi, \psi, a)$$
$$H(\varphi, \psi, a) = \frac{\psi^2}{2} - W(\varphi, a), \qquad W_{\varphi}(\varphi, a) = f(\varphi, a)$$

• For Nagumo PDE c = 0 iff a = 1/2

• Then unstable manifold of (0,0) and stable manifold of (1,0) intersect tangentially





$$u_{j+1} = u_j + hv_j + \frac{1}{2}h^2 f(u_j), \qquad v_{j+1} = v_j + \frac{h}{2}f(u_j) + \frac{h}{2}f(u_{j+1}),$$



$$\beta = 8$$
$$h = \sqrt{\beta}$$
$$a = 0.5$$

Manifolds intersect transversally

$$u_{j+1} = u_j + hv_j + \frac{1}{2}h^2 f(u_j), \qquad v_{j+1} = v_j + \frac{h}{2}f(u_j) + \frac{h}{2}f(u_{j+1}),$$



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$$u_{j+1} = u_j + hv_j + \frac{1}{2}h^2 f(u_j), \qquad v_{j+1} = v_j + \frac{h}{2}f(u_j) + \frac{h}{2}f(u_{j+1}),$$



$$\beta = 8$$
$$h = \sqrt{\beta}$$
$$a = 0.55$$

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#### **Discrete Nagumo**

### **Standing/Travelling Wave Boundary**







#### **Discrete Nagumo**

### **Standing/Travelling Wave Boundary**







- Expect heteroclinic connection for discretization for nearby parameter value [BEYN, 1990], [DOEDEL&FRIEDMAN, 1990]
- In general stable-unstable manifold intersection for discrete map generally transversal; so heteroclinic orbit will persist over (exponentially) small parameter range [FIEDLER & SCHEURLE, 1996]
- Manifolds 'touch' at boundary of interval of propagation failure
- Generically should expect propagation failure for cubic for  $\beta$  small
- Missing steps as c → 0 in numerical computations for β ≈ 0, are result of modified equations argument. Computed wave form is spurious, but is "exact" solution for perturbed continuous problem, and has exponentially small residual for stated problem

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#### **Conclusions**

- Advanced-Retarded FDE theory is incomplete
- Good numerics are needed to inform analysis
- Analysis is needed to inform numerics
- Can exploit discrete dynamical systems & symplectic method theory
- And difference equations are just numerical methods in disguise!

