

Lecture 3: Initial and boundary value problems in 1 dimension

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We have $u_x(x) \approx \frac{u(x+h) - u(x)}{h}$ for small h , if e.g. $u \in C^1(\mathbb{R})$. So $u_x = f$ is something like

$$y_{i+1} - y_i = b_{i+1},$$

where $y_i \approx u(ih)$ and $b_{i+1} \approx hf(ih)$. This can be solved as

$$y_n = y_{n-1} + b_n = y_{n-2} + b_{n-1} + b_n = \dots = y_0 + b_1 + \dots + b_n.$$

Let us rewrite the equation as

$$Ay = b,$$

with

$$y = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{pmatrix}, \quad b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}, \quad A = \begin{pmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}_{n \times (n+1)}.$$

The dimension of $\text{Ker} A$ is 1.



So if we give $y_0 = \alpha$, then the solution is unique. This means we consider the equation $\tilde{A}y = \tilde{b}$ where

$$\tilde{A} = \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}_{(n+1) \times (n+1)} \quad \text{and} \quad \tilde{b} = \begin{pmatrix} \alpha \\ b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}.$$

In particular $\tilde{A}: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ is an invertible matrix, with the inverse

$$G := \tilde{A}^{-1} = \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \\ 1 & 1 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 1 & 1 & 1 & \dots & 1 \end{pmatrix}.$$



The rows of G correspond to how particular y_i depends on b_k (and α):

$$y_i = 1 \cdot \alpha + 1 \cdot b_1 + \dots + 1 \cdot b_i + 0 \cdot b_{i+1} + \dots + 0 \cdot b_n.$$

The k -th column of G corresponds to the solution of the problem $\tilde{A}y = e_k$ where $e_k = [0, \dots, 0, 1, 0, \dots, 0]$ with the 1 at k -th place. Let G_0, G_1, \dots be the columns of G . Then we have

$$y = \alpha G_0 + b_1 G_1 + \dots + b_n G_n.$$

In other words,

- G_0 is the solution when $\alpha = 1$, $b_1 = \dots = b_n = 0$,
- G_1 is the solution when $\alpha = 0$, $b_1 = 1$, and $b_2 = \dots = b_n = 0$, etc.

To know a linear system, it is enough to know the responses of the system for a “few” well-chosen set of inputs.



What if $y_n = \beta$ is given, and we want to find y_0, \dots, y_{n-1} ? Then we need to “integrate backwards”

$$y_i = y_{i+1} - b_{i+1} = y_{i+2} - b_{i+1} - b_{i+2} = \dots = y_n - b_{i+1} - \dots - b_n.$$

Now the problem is $\tilde{\tilde{A}}y = \tilde{\tilde{b}}$ where

$$\tilde{\tilde{A}} = \begin{pmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}_{(n+1) \times (n+1)} \quad \text{and} \quad \tilde{\tilde{b}} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \\ \beta \end{pmatrix},$$

and we have

$$\tilde{\tilde{A}}^{-1} = \begin{pmatrix} -1 & \dots & -1 & -1 & 1 \\ \vdots & \ddots & & & \vdots \\ 0 & \dots & -1 & -1 & 1 \\ 0 & \dots & 0 & -1 & 1 \\ 0 & \dots & 0 & 0 & 1 \end{pmatrix}.$$



The analogue of the matrix inversion for $u_x = f$ with $u(0) = \alpha$ is

$$u(x) = \alpha + \int_0^\infty G(x, t) f(t) dt,$$

where

$$G(x, t) = \begin{cases} 1 & \text{if } t \leq x \\ 0 & \text{otherwise} \end{cases}$$

is called **Green's function** for the problem $u_x = f$ on $(0, \infty)$ with the initial condition at $x = 0$.

The function $G_t(x) = G(x, t)$ is the response to the Dirac function $\delta(x - t)$ centered at t .

$$\delta(x - t) = 0 \quad \text{for } x \neq t, \quad \text{and} \quad \int \delta(x - t) f(x) dx = f(t).$$



For the problem $u_x = f$ on $(-\infty, 0)$ with the “terminal” condition at $x = 0$, we have

$$u(x) = u(0) - \int_x^0 f(t) dt = u(0) + \int_{-\infty}^0 G(x, t) f(t) dt,$$

so its Green's function would be

$$G(x, t) = \begin{cases} -1 & \text{if } t \geq x \\ 0 & \text{otherwise} \end{cases}$$



The **Laplace operator** is $\Delta u = u_{xx}$ in 1D, $\Delta u = u_{xx} + u_{yy}$ in 2D etc. The two basic equations involving this operator are the **Laplace equation**

$$\Delta u = 0,$$

whose solutions are called **harmonic functions**, and the more general **Poisson equation**

$$\Delta u = f.$$



Consider $u_{xx} = f$ on the interval $(0, 1)$ subject to the **initial conditions** $u(0) = \alpha$ and $u_x(0) = \beta$.

- For $\alpha = 1$, $\beta = 0$, and $f = 0$, the solution is $u(x) = 1$
- For $\alpha = 0$, $\beta = 1$, and $f = 0$, the solution is $u(x) = x$
- For $\alpha = 0$, $\beta = 0$, and $f(x) = \delta(x - t)$, let $u(x) = G(x, t)$ be the solution

Then in the general case we anticipate

$$u(x) = \alpha + \beta x + \int_0^1 G(x, t) f(t) dt.$$

We have $G_{xx}(x, t) = 0$ **unless** $x = t$, so $G(x, t)$ is linear in x except possibly at $x = t$. This gives $G(x, t) = 0$ for $x \leq t$.

On the other hand, we have

$$1 = \int_{t-\varepsilon}^{t+\varepsilon} G_{xx}(x, t) dx = G_x(t + \varepsilon) - G_x(t - \varepsilon) = G_x(t + \varepsilon),$$

so $G(x, t) = x - t$ for $x \geq t$.



Consider now $u_{xx} = f$ on the interval $(0, 1)$ subject to the **boundary conditions** $u(0) = \alpha$ and $u(1) = \beta$.

- For $\alpha = 1$, $\beta = 0$, and $f = 0$, the solution is $u(x) = 1 - x$
- For $\alpha = 0$, $\beta = 1$, and $f = 0$, the solution is $u(x) = x$
- For $\alpha = 0$, $\beta = 0$, and $f(x) = \delta(x - t)$, let $u(x) = G(x, t)$ be the solution

So we anticipate

$$u(x) = \alpha(1 - x) + \beta x + \int_0^1 G(x, t) f(t) dt.$$

$G(x, t)$ is linear in x except possibly at $x = t$. In the vicinity of $x = t$:

$$1 = \int_{t-\varepsilon}^{t+\varepsilon} G_{xx}(x, t) dx = G_x(t + \varepsilon) - G_x(t - \varepsilon)$$

So $G(x, t) = kx$ for $x \leq t$, and $G(x, t) = (k + 1)x - t$ for $x \geq t$. From $G(1, t) = 0$ we get $k = t - 1$. The final result is

$$G(x, t) = \begin{cases} (t - 1)x & \text{for } x \leq t \\ t(x - 1) & \text{for } x \geq t \end{cases}$$