# Lecture 12: Method of characteristics and the Courant-Friedrichs-Lewy condition

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Consider the initial value problem for the advection equation

$$u_t + c(x, t) u_x = 0,$$
  $u(x, 0) = f(x),$ 

where the velocity c(x, t) can vary in space and time.

Example:  $c(x, t) = \sin t$ 

### Characteristic curves satisfy

$$\dot{x} \equiv \frac{\mathrm{d}x}{\mathrm{d}t} = c(x, t),$$

and u(x(t), t) is constant along them.





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Example:  $c(x, t) = \cos x + \sin t$ 

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Let  $c(x, t) = \sin t$ . The characteristics are given by

$$\dot{x} = c(x, t)$$
  $\Leftrightarrow$   $x(t) = -\cos t + C = x_0 + 1 - \cos t$ ,

where  $x_0 = x(0)$ .

$$x_0 = x + \cos t - 1, \qquad \Rightarrow \qquad u(x, t) = f(x + \cos t - 1).$$

Now consider c(x, t) = x. We have

$$x(t) = x_0 e^t$$
,  $x_0 = x(t)e^{-t}$ ,  $u(x, t) = f(xe^{-t})$ .

In general, suppose that the characteristics are given by  $x(t) = h(x_0, t)$ . Then if we can find  $x_0 = q(x(t), t)$ , we would have

$$u(x,t) = f(q(x,t)).$$



Consider the system

$$u_t + Au_x = 0,$$

where A is an  $n \times n$  matrix, possibly depending on x and t. Suppose that  $A = P^{-1}DP$  with a diagonal matrix D. Note that P and D can depend on x and t. We have

$$u_t + P^{-1}DPu_x = 0,$$

and after multiplying by  $\boldsymbol{P}$  from the left

$$Pu_t + DPu_x = 0.$$

Upon introducing q = Pu, the new variable q satisfies

$$q_t + Dq_x = 0.$$

In general, we have *n* characteristic curves, corresponding to the eigenvalues  $\lambda_i(x, t)$  of A(x, t).



Given a point (x, t), trace all the characteristic curves emanating from (x, t) backward in time. The area "under" these curves is the **domain of dependence** of (x, t). This is the set of points that can influence the point (x, t).

Now trace all the characteristic curves emanating from (x, t) forward in time. The area "above" these curves is the **range of influence** of (x, t). This is the set of points that can be influenced by the point (x, t).



Let us discretize

$$u_t + cu_x = 0,$$
  $u(x, 0) = f(x),$ 

by a finite difference scheme, with *time-step*  $\tau$  and spacial *mesh-size* h:

$$\frac{u_{i,k+1} - u_{i,k}}{\tau} + c \frac{u_{i+1,k} - u_{i,k}}{h} = 0, \qquad u_{i,0} = f(ih),$$

or

$$u_{i,k+1} = \left(1 + \frac{c\tau}{h}\right) u_{i,k} - \frac{c\tau}{h} u_{i+1,k}, \qquad u_{i,0} = f(ih).$$

So,  $u_{i,k+1}$  can be calculated directly from the data on the **time level** *k*. In particular, no matrix inversion is needed.

If c < 0 then the above scheme is called an **upwind scheme**. If c > 0, an upwind scheme would use  $u_{i-1,k}$  instead of  $u_{i+1,k}$ . "Downwind" scheme is never used.



Suppose that

$$u_{i,k+1} = F(u_{i-n,k},\ldots,u_{i+m,k}),$$

is a discretization of a hyperbolic system, on a grid with time-step  $\tau$  and spacial mesh-size h. We say that the scheme **converges**, if for all i and k,  $u_{i,k} \rightarrow u(ih, k\tau)$  as we send both h and  $\tau$  to 0 in some fashion.

A necessary condition for the scheme to converge is that the line segment connecting the points  $(ih - nh, k\tau)$  and  $(ih + mh, k\tau)$  contains the domain of dependence of the point  $(ih, k\tau + \tau)$  intersected with the line  $t = k\tau$ .

This is called the Courant-Friedrichs-Lewy (CFL) condition. For our earlier example, the CFL condition is

$$h \ge c\tau$$
, or  $\frac{c\tau}{h} \le 1$ .