

ANALYSES FOR A MATHEMATICAL MODEL OF THE PATTERN FORMATION ON SHELLS OF MOLLUSCS

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Abstract. This paper analyses a mathematical model of the pattern formation on the shell of molluscs which is actually a kind of reaction-diffusion system. The existence and uniqueness of a global smooth solution of this system with Cauchy problem and its stability and time decay rate are studied by means of an elementary energy method.

1. Introduction

How to understand the pattern formation of a shell of molluscs is an interesting problem for bio-mathematicians. In the nature, some molluscs are quite different in the sense of their sorts, but their pattern formations are so similar. This shows us that they have the same reaction function. In 1969, C. H. Waddington and J. Cowe[7] proposed a concept of the tent-like pattern formation. In 1982, D. Lingdsay[2] proposed one called as pattern formation of bivalved molluscs (for example, shell, etc.). After that, H. Meinhardt and H. Klingler[5] explained that the pattern formation of shell of molluscs is a reaction-diffusion process. We believe that this explanation is reasonable due to that, for example, the formation of oblique-line is just one: a pigment-producing cell can affect its neighbour cell, and that, this neighbour cell will become a pigment-producing cell and influence its neighbour in turn, then step by step, an oblique-line of pigment-producing cells will be formed. For this phenomenon, H. Meinhardt and H. Klingler[5] gave a model as follows:

$$a_t - D_a \Delta a = -\mu a + \frac{a^2 s}{1 + \kappa a^2 + \rho_0}, \quad (1.1)$$

$$s_t - D_s \Delta s = -\gamma s + \sigma - \frac{a^2 s}{1 + \kappa a^2 + \rho_0}. \quad (1.2)$$

Here, $a(x, t)$ the activator density, $s(x, t)$ the substrate density, $x \in R^3$, $t \geq 0$, $D_a > 0$ and $D_s > 0$ are the diffusion coefficients of $a(x, t)$ and $s(x, t)$, respectively. ρ_0

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$\sigma, \rho_0, \mu, \gamma$ and κ are positive constants, μ and γ denote the decay rates of activator and substrate, respectively. Δ is the Laplacian operator in R^3 . T. Jiang[1] studied the existence and uniqueness of the solution for (1.1), (1.2) with Neumann boundary condition, and discussed the branch of the solutions.

In this paper, we study the Cauchy problem for system (1.1), (1.2) with the initial data

$$t = 0: \quad a = a_0(x), \quad s = s_0(x), \quad x \in R^3. \quad (1.3)$$

Our plan contains the following. After stating the notions, we prove the existence and uniqueness of global smooth solutions of (1.1)–(1.3) in Sect.2, and show the stability and time decay rate of the solutions in Sect.3. These results will show us that, in this autocatalytic molecular reaction process, the densities of activator and substrate stably extend to a steady station in exponential decay, and there is no pattern to form after the end of this process for a long time.

Notations We denote the norm and the product of $L^2(R^3)$ by $\|\cdot\|$ and (\cdot, \cdot) , the norms of $H^k(R^3)$ and $C^k(R^3)$ by $\|\cdot\|_k$ and $\|\cdot\|_{C^k}$, respectively. Let

$$D^k = \partial^k / \partial x_1^{k_1} \partial x_2^{k_2} \partial x_3^{k_3}, \quad k = k_1 + k_2 + k_3.$$

For any fixed positive constants $N_1, M_i, i = 1, 2$, we define a functional set ($0 < N < N_1, T > 0$) as the following

$$\begin{aligned} & \Omega(0, T | N, M_1^2, M_2^2) \\ &= \{(u, v) \in R^2 \mid (u, v) \in (C^1(0, T; H^2) \cap C^0(0, T; H^4) \cap L^2(0, T; H^5))^2, \\ & \quad \sup_{0 \leq t \leq T} (\|u(t)\|_4^2 + \|v(t)\|_4^2) \leq N^2 \\ & \quad \sup_{0 \leq t \leq T} (\|u_t(t)\|_4^2 + \|v_t(t)\|_4^2) \leq M_1^2 \\ & \quad \sup_{0 \leq t \leq T} \int_0^T (\|u(t)\|_4^2 + \|v(t)\|_4^2) dt \leq M_2^2\}, \end{aligned}$$

which will be used later. We can well understand that $\Omega(0, T | N, M_1^2, M_2^2)$ is a closed convex set in the Banach space $(C^1(0, T; H^2) \cap C^0(0, T; H^4) \cap L^2(0, T; H^5))^2$.

By the Sobolev's inequality, there exists $N_1 > 0$ such that for any $T > 0$ the inequality

$$\sup_{0 \leq t \leq T} (\|u(t)\|_4^2 + \|v(t)\|_4^2) \leq N^2$$

implies that

$$\sup_{0 \leq t \leq T} (\|u(t)\|_{L^\infty}^2 + \|v(t)\|_{L^\infty}^2) \leq r^2.$$

Therefore we choose $R_1 = R_1(r)$ as such constant satisfying above.

2. Global Existence and Uniqueness

Letting

$$u(x, t) = a(x, t), \quad v(x, t) = s(x, t) - \sigma\gamma^{-1},$$

then (1.1)–(1.3) can be reduced to

$$u_t - D_a \Delta u = -\mu u + f(u, v), \tag{2.1}$$

$$v_t - D_s \Delta v = -\gamma v - f(u, v), \tag{2.2}$$

$$t = 0: \quad u = a_0(x), \quad v = s_0(x) - \sigma\gamma^{-1}, \quad x \in R^3. \tag{2.3}$$

where $f(u, v) = u^2(v + \sigma\gamma^{-1}) / (1 + \kappa u^2 + \rho_0)$.

The differential inequalities as the following lemmas can be found in [3,6], see also [4].

Lemma 2.1[3,6] Suppose that $f \in C^5(R^2)$ and $(u, v) \in \Omega(0, T | N, M_1^2, M_2^2)$, then

$$\begin{aligned} & \|D^p\{f(u, v)w(x, t)\} - f(u, v)D^p w(x, t)\| \\ & \leq C(\|u(t)\|_4 + \|v(t)\|_4)\|w(t)\|_4, \quad 0 \leq p < 4 \end{aligned} \tag{2.4}$$

holds for $t \in [0, T]$ and $w(x, t) \in C^0(0, T; H^4)$, where $C > 0$ only depends on N_1 .

Lemma 2.2[3,6] Suppose that $h(u, v) \in C^5(R^2)$, $h(0, 0) = 0$ and $(u, v) \in \Omega(0, T | N, M_1^2, M_2^2)$, then

$$\|D^p h(u, v)\| \leq C(\|u(t)\|_4 + \|v(t)\|_4), \quad 0 \leq p \leq 4 \tag{2.5}$$

holds for $t \in [0, T]$, where $C > 0$ only depends on N_1 .

By a standard energy method, we can prove that there exists the unique local solution of (2.1)–(2.3) in $\Omega(0, t_0 | N, M_1^2, M_2^2)$ for some $t_0 > 0$. For the details, we may refer to [4]. Thus, our local existence is stated as follows without proof.

Proposition 2.3. (Local Existence) Suppose that $a_0(x), s_0(x) - \sigma\gamma^{-1} \in H^4(R^3)$ and satisfy

$$\|a_0\|_4^2 + \|s_0(x) - \sigma\gamma^{-1}\|_4^2 \leq N_0^2, \quad (N_0 < N/2). \tag{2.6}$$

Then there exists $t_0 = t_0(N_0) > 0$ such that there is a unique pair of solutions for (2.1)–(2.3) satisfying

$$(u, v) \in \Omega(0, t_0 | 2N_0, C'N_0^2, C''N_0^2),$$

where $C', C'' > 0$ are constants independent of N_0 .

As we know, to show the global existence, the *a priori estimate* plays an important role in the procedure by the energy method. Our basic energy estimate is the following.

Proposition 2.4. (A Priori Estimate) Under the assumptions in Proposition 2.3. Suppose that $(u, v) \in \Omega(0, T | 2N, C^1N^2, C''N^2)(T > 0, N < N_1/2)$ is the solution of (2.1)–(2.3). Then there exists a sufficiently small $N_0 > 0$, such that

$$\|a_0\|_4^2 + \|s_0(x) - \sigma\gamma^{-1}\|_4^2 \leq N_0^2, \quad (N_0 < N/2), \tag{2.7}$$

when $N \leq N_0$, then

$$\|u(t)\|_4^2 + \|v(t)\|_4^2 \leq N_0^2 \tag{2.8}$$

holds for $t \in [0, T]$.

Proof. We first denote that

$$L_1(u, v; U, V) \equiv U_t - D_a \Delta U + \mu U - \frac{\sigma u}{\gamma(1 + \kappa u^2 + \rho_0)} U - \frac{u^2}{(1 + \kappa u^2 + \rho_0)} V, \tag{2.9}$$

$$L_2(u, v; U, V) \equiv V_t - D_s \Delta V + \gamma V + \frac{\sigma u}{\gamma(1 + \kappa u^2 + \rho_0)} U + \frac{u^2}{(1 + \kappa u^2 + \rho_0)} V, \tag{2.10}$$

and $u_\epsilon = J_\epsilon u, v_\epsilon = J_\epsilon v$, where $J_\epsilon u = \epsilon^{-3} \int_{\mathbb{R}^3} j(\frac{x-y}{\epsilon}) u(y, t) dy$.

Differentiating $L_i(u, v; u_\epsilon, v_\epsilon)$ ($i = 1, 2$) as D^k ($0 \leq k \leq 4$), making their products with $D^k u_\epsilon$ and $D^k v_\epsilon$, respectively, adding them and integrating the result yield

$$\begin{aligned} I_k &\equiv \int_0^t ((D^k u_\epsilon, D^k L_1(u, v; u_\epsilon, v_\epsilon)) + (D^k v_\epsilon, D^k L_2(u, v; u_\epsilon, v_\epsilon))) d\tau \\ &= \frac{1}{2} (\|D^k u_\epsilon(t)\|^2 + \|D^k v_\epsilon(t)\|^2 - \|D^k u_\epsilon(0)\|^2 - \|D^k v_\epsilon(0)\|^2) \\ &\quad + \int_0^t (D_a \|D^{k+1} u_\epsilon(\tau)\|^2 + D_s \|D^{k+1} v_\epsilon(\tau)\|^2) d\tau \\ &\quad + \int_0^t (\mu \|D^k u_\epsilon(\tau)\|^2 + \gamma \|D^k v_\epsilon(\tau)\|^2) d\tau \\ &\quad + \int_0^t (-D^k u_\epsilon + D^k v_\epsilon, D^k g(u, v; u_\epsilon, v_\epsilon)) d\tau, \end{aligned} \tag{2.11}$$

where

$$g(u, v; u_\epsilon, v_\epsilon) = \frac{\sigma u}{\gamma(1 + \kappa u^2 + \rho_0)} u_\epsilon + \frac{u^2}{(1 + \kappa u^2 + \rho_0)} v_\epsilon. \tag{2.12}$$

From Lemmas 2.1 and 2.2 we obtain

$$\|D^k g(u, v; u_\epsilon, v_\epsilon)\| \leq C_1 R (\|u_\epsilon(t)\|_4^2 + \|v_\epsilon(t)\|_4^2). \tag{2.13}$$

Moreover, by Schwarz's inequality and Cauchy's inequality ($ab \leq \frac{\eta}{2}a^2 + \frac{1}{2\eta}b^2$, for any $\eta > 0$), using (2.13), we have

$$\begin{aligned} I_k \geq & \frac{1}{2}(\|D^k u_\varepsilon(t)\|^2 + \|D^k v_\varepsilon(t)\|^2 - \|D^k u_\varepsilon(0)\|^2 - \|D^k v_\varepsilon(0)\|^2) \\ & + \int_0^t (D_a \|D^{k+1} u_\varepsilon(\tau)\|^2 + D_s \|D^{k+1} v_\varepsilon(\tau)\|^2) d\tau \\ & + \int_0^t [(\mu - \frac{\eta}{2}) \|D^k u_\varepsilon(\tau)\|^2 + (\gamma - \frac{\eta}{2}) \|D^k v_\varepsilon(\tau)\|^2] d\tau \\ & - \frac{C_1 R}{\eta} \int_0^t (\|u_\varepsilon(\tau)\|_4^2 + \|v_\varepsilon(\tau)\|_4^2) d\tau. \end{aligned} \quad (2.14)$$

Choosing $\eta < \min\{2\mu, 2\gamma\}$ and summing (2.14) with k yield

$$\begin{aligned} \sum_{k=0}^4 I_k \geq & \frac{1}{2}(\|u_\varepsilon(t)\|_4^2 + \|v_\varepsilon(t)\|_4^2 - \|u_\varepsilon(0)\|_4^2 - \|v_\varepsilon(0)\|_4^2) \\ & + \int_0^t (D_a \|u_\varepsilon(\tau)\|_5^2 + D_s \|v_\varepsilon(\tau)\|_5^2) d\tau \\ & + \int_0^t [(\mu - \frac{\eta}{2}) \|u_\varepsilon(\tau)\|_4^2 + (\gamma - \frac{\eta}{2}) \|v_\varepsilon(\tau)\|_4^2] d\tau \\ & - \frac{5C_1 R}{\eta} \int_0^t (\|u_\varepsilon(\tau)\|_4^2 + \|v_\varepsilon(\tau)\|_4^2) d\tau. \end{aligned} \quad (2.15)$$

In particular, selecting $N_0 < \min\{\frac{\eta(2\mu-\eta)}{10C_1}, \frac{\eta(2\gamma-\eta)}{10C_1}, \frac{N_1}{2}\}$, when $N \leq N_0$, we get

$$\begin{aligned} \sum_{k=0}^4 I_k \geq & \frac{1}{2}(\|u_\varepsilon(t)\|_4^2 + \|v_\varepsilon(t)\|_4^2 - \|u_\varepsilon(0)\|_4^2 - \|v_\varepsilon(0)\|_4^2) \\ & + \theta \int_0^t (\|u_\varepsilon(\tau)\|_4^2 + \|v_\varepsilon(\tau)\|_4^2) d\tau, \end{aligned} \quad (2.16)$$

where $\theta = \min\{\mu - \frac{\eta}{2} - \frac{5}{\eta}C_1 N_0, \gamma - \frac{\eta}{2} - \frac{5}{\eta}C_1 N_0\}$.

Letting $\varepsilon \rightarrow 0$, we know that the following uniformly holds for $t \in [0, T]$

$$\|u_\varepsilon(t)\|_4 \rightarrow \|u(t)\|_4, \quad \|v_\varepsilon(t)\|_4 \rightarrow \|v(t)\|_4. \quad (2.17)$$

Notice that (u, v) is the smooth solution of (2.1)–(2.3), namely, $L_1(u, v; u, v) = L_2(u, v; u, v) = 0$, then we have

$$\begin{aligned} I_k \equiv & \int_0^t ((D^k u_\varepsilon, D^k(L_1(u, v; u_\varepsilon, v_\varepsilon) - J_\varepsilon L_1(u, v; u, v))) \\ & + (D^k v_\varepsilon, D^k(L_2(u, v; u_\varepsilon, v_\varepsilon) - J_\varepsilon L_2(u, v; u, v)))) d\tau. \end{aligned}$$

Due to the properties of J_ϵ (see [6]) we have

$$\begin{aligned} & \|D^k(L_i(u, v; u_\epsilon, v_\epsilon) - J_\epsilon L_i(u, v; u, v))\| \rightarrow 0, \quad i = 1, 2, \quad 0 \leq k \leq 3, \\ & \left| \int_0^t ((D^k u_\epsilon, D^k(L_1(u, v; u_\epsilon, v_\epsilon) - J_\epsilon L_1(u, v; u, v)))d\tau \right| \\ & \leq \left(\int_0^t \|D^5 u_\epsilon(\tau)\|^2 d\tau \right)^{\frac{1}{2}} \left(\int_0^t \|D^3(L_1(u, v; u_\epsilon, v_\epsilon) - J_\epsilon L_1(u, v; u, v))\|^2 d\tau \right)^{\frac{1}{2}} \rightarrow 0, \\ & \left| \int_0^t ((D^k v_\epsilon, D^k(L_2(u, v; u_\epsilon, v_\epsilon) - J_\epsilon L_2(u, v; u, v)))d\tau \right| \\ & \leq \left(\int_0^t \|D^5 v_\epsilon(\tau)\|^2 d\tau \right)^{\frac{1}{2}} \left(\int_0^t \|D^3(L_2(u, v; u_\epsilon, v_\epsilon) - J_\epsilon L_2(u, v; u, v))\|^2 d\tau \right)^{\frac{1}{2}} \rightarrow 0, \end{aligned}$$

as $\epsilon \rightarrow 0$. Therefore, we obtain $I_k \rightarrow 0$ as $\epsilon \rightarrow 0$. Above results imply that (let $\epsilon \rightarrow 0$)

$$\begin{aligned} & \|u(t)\|_4^2 + \|v(t)\|_4^2 + 2\theta \int_0^t (\|u(\tau)\|_4^2 + \|v(\tau)\|_4^2) d\tau \\ & \leq \|u(0)\|_4^2 + \|v(0)\|_4^2. \end{aligned} \tag{2.18}$$

Thus (2.7) and (2.18) yield (2.8). The proof is completed. \square

Up to now, we can prove the global existence by *a priori estimate* together with the local existence.

Theorem 2.5. (Global Existence) Suppose that $a_0(x), s_0(x) - \sigma\gamma^{-1} \in H^4(R^3)$. Then there exists a suitably small positive constant N_0 , such that, when

$$\|a_0\|_4^2 + \|s_0(x) - \sigma\gamma^{-1}\|_4^2 \leq N_0^2, \tag{2.19}$$

then there exists a unique pair of global solutions for (2.1)–(2.3) $(u, v) \in \Omega(0, \infty | 2N_0, C^1 N_0^2, C'' N_0^2)$ satisfying

$$\|u(t)\|_4^2 + \|v(t)\|_4^2 \leq N_0^2, \quad \text{for } t \in [0, \infty]. \tag{2.20}$$

Proof. Let N_0 be the selected positive constant in Proposition 2.4. According to the local existence result (Proposition 2.3), there is a $t_0 > 0$ such that the problem (2.1)–(2.3) has a unique local smooth solution in $R^2 \times [0, t_0]$. Due to the *a priori* estimates (Proposition 2.4), we know the local solution satisfies (2.20) for $t \in [0, t_0]$. Now we consider the system (2.1), (2.2) with the “initial data” $(u(x, t_0), v(x, t_0))$. Since this “initial data” satisfies (2.20), applying Proposition 2.3 again, we can extend the solvable interval of the solution $(u(x, t), v(x, t))$ to $R \times [0, 2t_0]$, and can also show the estimate (2.20) for $t \in [0, 2t_0]$ by Proposition 2.4. Repeating this procedure, we prove that (u, v) is the global smooth solution and satisfies (2.20) for $t \in [0, \infty)$. The proof is completed. \square

3. Global Stability and Asymptotic Decay

Before stating our stability theorem, we give a basic estimate on the global smooth solution as follows.

Lemma 3.1. *Under the assumptions in Theorem 2.5,*

$$\begin{aligned} & \|u(t)\|_4^2 + \|v(t)\|_4^2 + 2\theta \int_0^t (\|u(\tau)\|_4^2 + \|v(\tau)\|_4^2) d\tau \\ & \leq \|a_0\|_4^2 + \|s_0 - \frac{\sigma}{\gamma}\|_4^2 \end{aligned} \quad (3.1)$$

holds for $t \in [0, \infty)$.

Proof. Firstly, we consider (2.1), (2.2) with this initial data

$$(u, v)|_{t=0} = (J_\varepsilon a_0, J_\varepsilon (s_0 - \frac{\sigma}{\gamma}))(x),$$

and denote the solution as $(u_\varepsilon(x, t), v_\varepsilon(x, t))$. By the same procedure in Proposition 2.4, we can obtain a similar estimate corresponding (2.18) as

$$\begin{aligned} & \|u_\varepsilon(t)\|_4^2 + \|v_\varepsilon(t)\|_4^2 + 2\theta \int_0^t (\|u_\varepsilon(\tau)\|_4^2 + \|v_\varepsilon(\tau)\|_4^2) d\tau \\ & \leq \|u_\varepsilon(0)\|_4^2 + \|v_\varepsilon(0)\|_4^2, \quad t \in [0, \infty). \end{aligned} \quad (3.2)$$

Considering now $(u, v)|_{t=0} = (a_0, s_0 - \frac{\sigma}{\gamma}) \in H^4(R^3)$, remarking the relative solution as (u, v) , since $C_0^\infty(R^3)$ is dense in $H^4(R^3)$, and using Banach-Saks theorem, we have

$$(u_\varepsilon, v_\varepsilon) \rightarrow (u, v) \quad \text{in } H^4(R^3), \quad \text{as } \varepsilon \rightarrow 0.$$

Taking the limit, we obtain (3.1). \square

Theorem 3.2. (Global Stability) *Under the assumptions in Theorem 2.5, the solution of (2.1)–(2.3) is globally stable, i.e., when*

$$\|a_0\|_4^2 + \|s_0 - \frac{\sigma}{\gamma}\|_4^2 \leq \varepsilon, \quad (3.3)$$

where $\varepsilon > 0$ is any constant, then

$$\|u(t)\|_{L^\infty} + \|v(t)\|_{L^\infty} \leq C\varepsilon \quad (3.4)$$

holds for $t \in [0, \infty)$.

Proof. The assertion can be verified by Lemma 3.1 and Sobolev's inequality. \square

Theorem 3.3. (*Asymptotic Decay Rate*) Under the assumptions in Theorem 2.5, the asymptotic decay rate of the solution for (2.1)–(2.3)

$$\|u(t)\|_{L^\infty} + \|v(t)\|_{L^\infty} \leq CN_0 e^{-\theta t} \quad (3.5)$$

holds for $t \in [0, \infty)$.

Proof. Due to (3.1) in Lemma 3.1 and Gronwall's inequality, we have

$$\|u(t)\|_4^2 + \|v(t)\|_4^2 \leq N_0^2 e^{-2\theta t}. \quad (3.6)$$

Applying Sobolev's inequality to (3.6) yields our desired estimate (3.5). \square

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